

Part 2 Matlab

a. Plot $z = x^2 - y^2$ adjust viewport so interesting + print

b) Plot $z = xye^{x^2 - y^2}$
* make sure to put the dots in

why am I getting errors

that z is not a matrix - it is

- oh did not do mesh grid

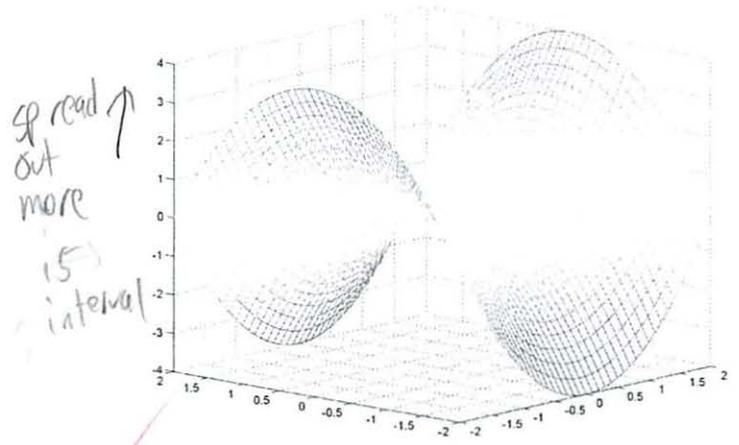
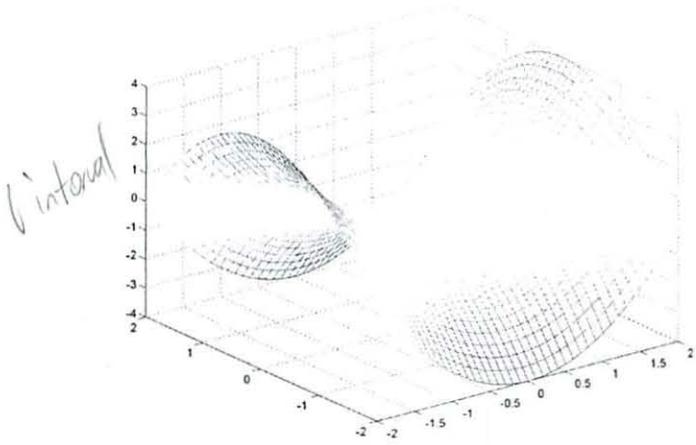
- must do all steps in order

9/9

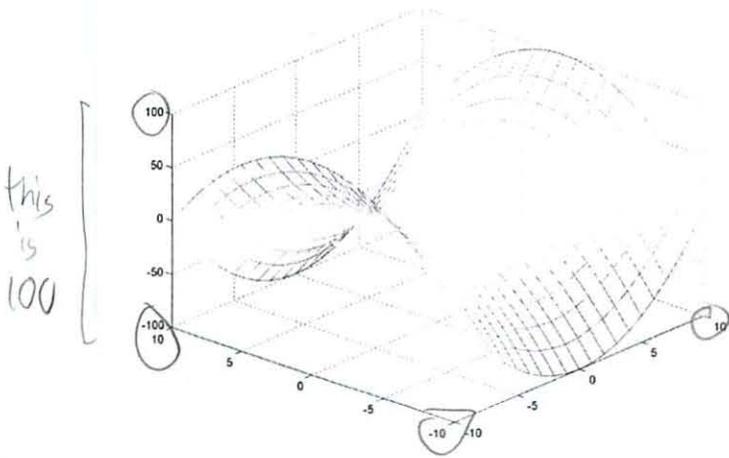
→
see printout

a)

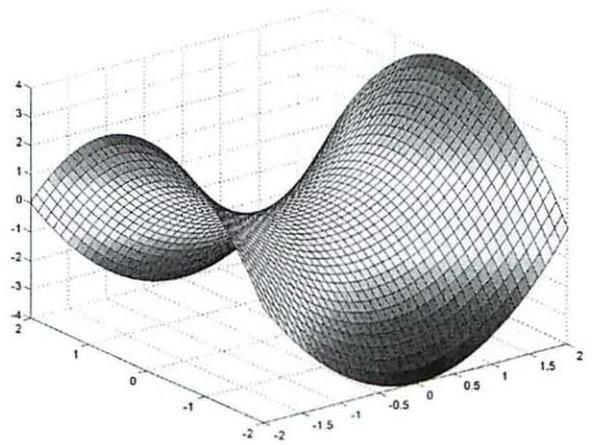
Sorry print at so faint

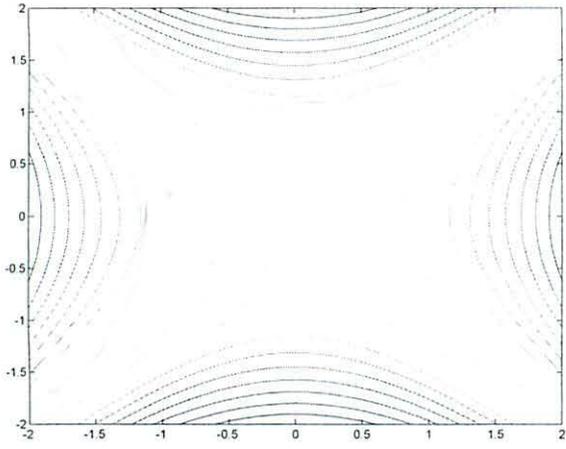


large axis

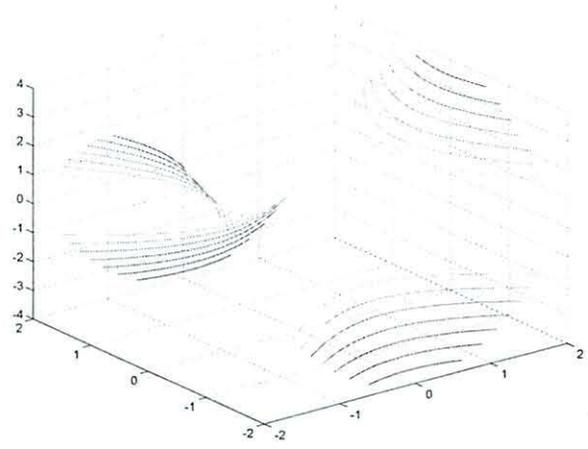


surf



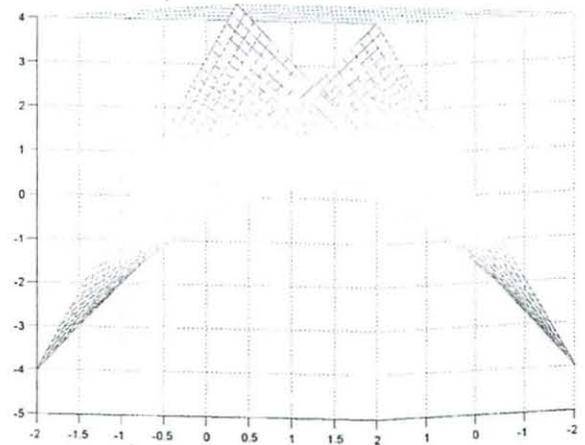
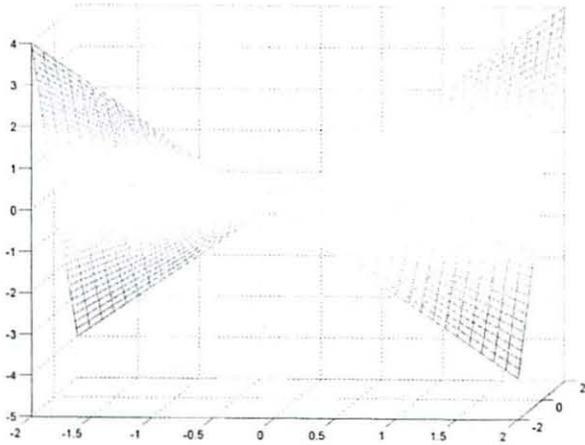


Contour
from top



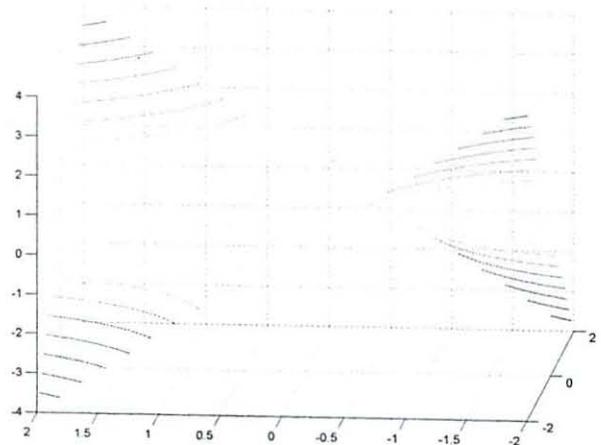
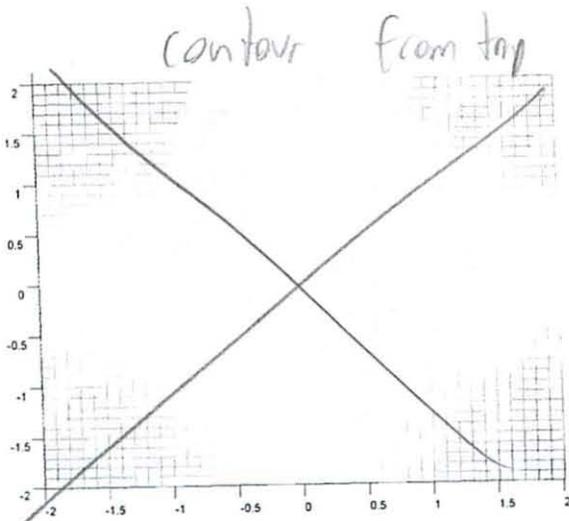
Contour 3d

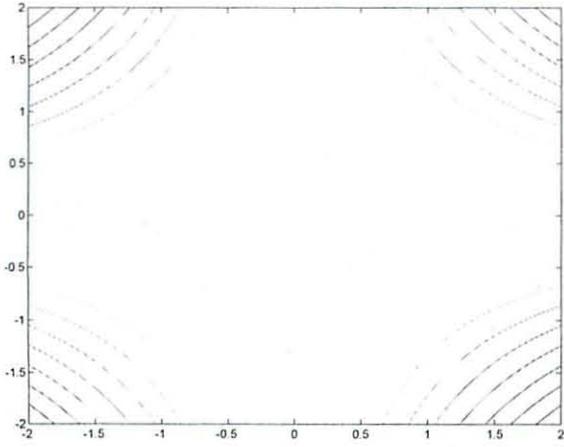
b+c)



different views

3D contour





center from top

2. Surface $z = x^2 - y^2$ saddle shape
- contains 2 families of line which fill surface
 - ↳ can't see from Matlab
 - 2 lines - one from each family - goes through every P_0 on surface.
 - spans tangent plane at P_0
 - intersection of surface w/ tangent planes
- Verify w/ $(3, 2, 5)$

- a) Write the parametric equation for a general non-horiz line through P
- passes through P and parallel to $a\vec{i} + b\vec{j} + c\vec{k}$
 - Are 2 sets of values for (a, b) for which the resulting line lies entirely on surface
 - (lies on surface if every pt on line works)

Other OH

$S: f(x, y, z) = C$ on curve $= \vec{r}(t) = \langle \dots \rangle$ for every t belongs to surface

Is the curve on surface - plug in to

$$A = \frac{a\vec{i}}{c} + \frac{b\vec{j}}{c} + \vec{k}$$

← same

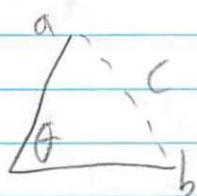
↳ just as specific

Yes for process but no answers 1/4

3.
2B-8 Two sides of of triangle a, b, θ in included angle
Third side is c

d/1.5 a) Give the approx for Δc in terms of $a, b, c, \theta, \Delta a, \Delta b, \Delta \theta$

b) If $a=1, b=2, \theta=\frac{\pi}{3}$ is c more sensitive to small changes in a or b ?



So this is error/approx formula

$$\Delta w = \left(\frac{\partial w}{\partial x} \right)_0 \Delta x + \left(\frac{\partial w}{\partial y} \right) \Delta y$$

-so need formula \rightarrow trig

$$c = a^2 + b^2 - 2ab \cos(\theta)$$

$$\Delta c = 2a - 2b \cos \theta \Delta a + 2b - 2a \cos \theta \Delta b + 2ab \sin(\theta) \Delta \theta$$

$\Delta \theta$? need to do θ , yeah its a variable

$$c = 2(1) - 2(2) \cos\left(\frac{\pi}{3}\right) \Delta a + 2(2) - 2(1) \cos\left(\frac{\pi}{3}\right) \Delta b + 2(1)(2) \sin\left(\frac{\pi}{3}\right) \Delta \theta$$

$$c = 0 \Delta a + 3 \Delta b + 2\sqrt{3} \Delta \theta$$

\uparrow largest change in volume due to c

1/1.5



but if this is not an option then

$$\text{total change} = 3 + 2\sqrt{3} = 6.46$$

\uparrow
correct

- don't have to do

4. Topo Map

level curve indicates h above sea level in ft

a. Estimate h_x, h_y at B

I guess h_x is gradient in x dir \rightarrow

or is pt where tangent = 0
- but pt given

change \rightarrow $\frac{-100 \text{ ft}}{1000 \text{ ft}} = -0.1$ ✓

$h_y = \frac{-100 \text{ ft}}{500 \text{ ft}} = -0.2$ ✓

→
over

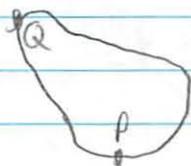
did/scale
wrong
should be
fixed

b. Now in dir $\uparrow - \rightarrow$

$\frac{-100 \text{ ft}}{800 \text{ ft}} = -0.125$ ✓

c. Find P and Q having the smallest y coords
such that $h(P) = h(Q) = 3000$ $h_x(P) = 0$ $h_y(P) = 0$

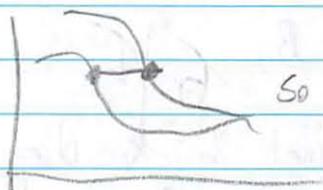
So are on the same 3000 line
where



d

oliver
011

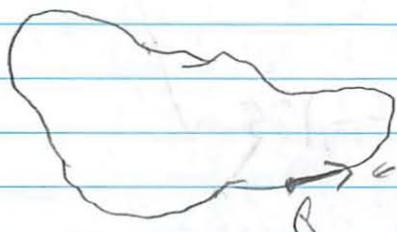
$$h(x) = \frac{\partial h}{\partial x} = \text{rate of change in dir of } x$$



so I did get it

- d Find the R with the largest x -coord
such that $h(R) = 2900$
on that line

$$\frac{dh}{ds} = 0 \text{ at } R \text{ in dir } \hat{i} + \hat{j}$$



in 45° dir, no change in height
since along line

5. In the first octant of 3-space $xyz=a$
for a fixed constant $a > 0$

Graphic surface is a hyperboloid

Has 3 coordinate planes as asymptotes

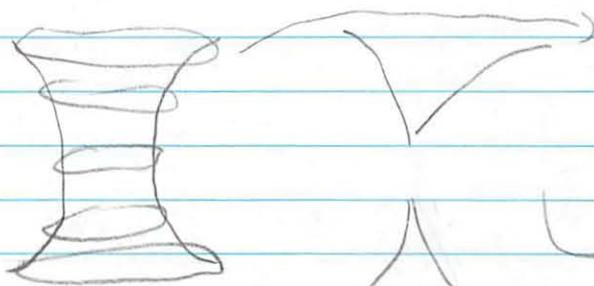
- gets closer & closer to a coord plane as variable $\rightarrow \infty$

$P_0(x_0, y_0, z_0)$ tangent plane cuts off a tetrahedron
from 1st octant, origin is 1 vertex, 3 coord planes +
tangent plane are the 4 surfaces

As P_0 varies, shape varies, volume constant

Prove + find volume

Wikipedia

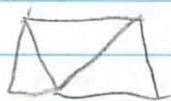


one sheet

two sheets

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

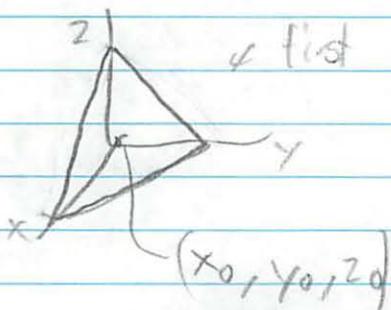
$$-\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$



↳ worst tetrahedron ever

4 triangular faces

↳ but how can it do that
- sides are curved



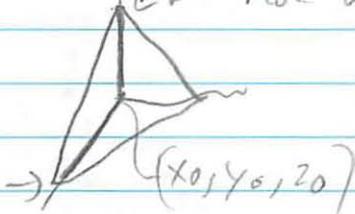
↳ first octant

3 faces are coord plane
4th (face) is from octant
from tangent plane

And how can volume remain constant?

$$\hookrightarrow \text{Volume} = \frac{1}{3}bh$$

but these are:



$$w = xyz$$

$$\nabla w = \langle yz, xz, xy \rangle$$

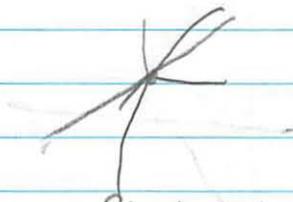
level surface - want dot product \circ with pt through

$$\langle yz, xz, xy \rangle \circ \langle x_0, y_0, z_0 \rangle \\ x_0(yz) + y_0(xz) + z_0(xy)$$

find where plane intersects coord axis

- did I draw it wrong

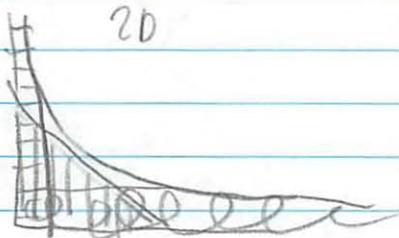
- so where do we put the axis?



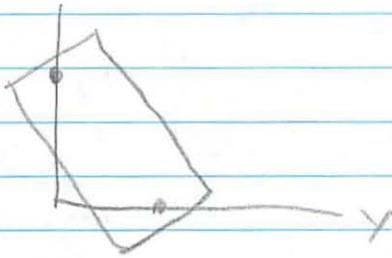
then find volume

change + reprove

oliver



all 3 areas =
not obvious in 3D



partial derivatives

other
of

$$(0, y, 0)$$

$$(0, 0, z) \text{ satisfy}$$

$$[x_0 y_0 (z - z_0) + x_0 y_0 (y - y_0) + \dots = 0$$

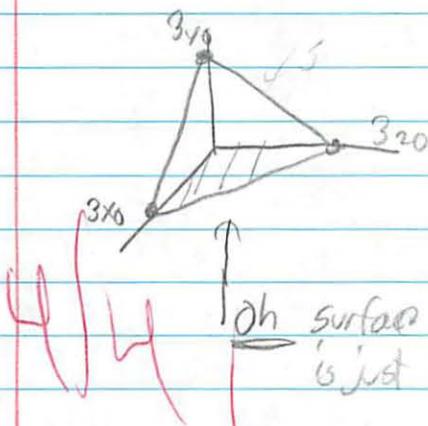
$$y = 0$$

$$x = 0$$

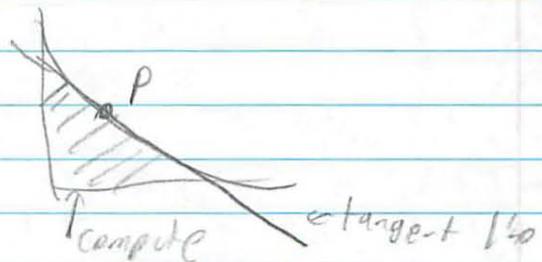
$$\nabla w \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$$

$$S: w(x, y, z) = c$$

$$S: \text{ is a graph of } f(x, y) \Leftrightarrow z - f(x, y) = 0$$



2D

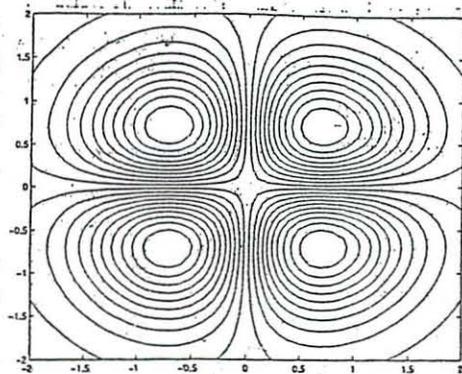
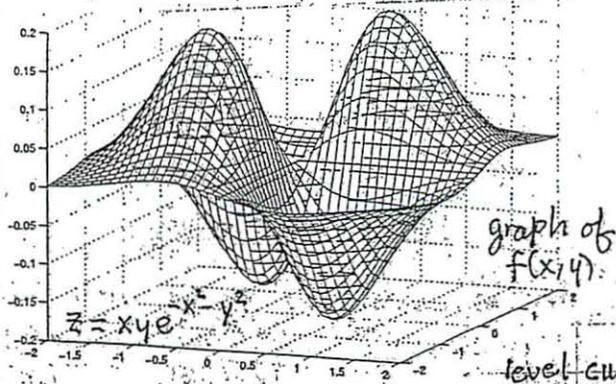
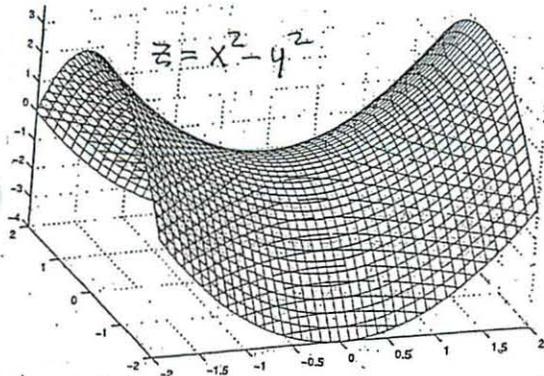


sh surface

is just touching the tangent plane here

prove volume does not depend on x_0, y_0, z_0

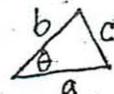
1



graph of $f(x,y)$

level curves of $f(x,y)$

3



By law of cosines

$$c = \sqrt{a^2 + b^2 - 2ab \cos \theta}$$

$$\frac{\partial c}{\partial a} = \frac{2a - 2b \cos \theta}{2c}, \quad \frac{\partial c}{\partial b} = \frac{2b - 2a \cos \theta}{2c}$$

$$\frac{\partial c}{\partial \theta} = \frac{+2ab \sin \theta}{2c}$$

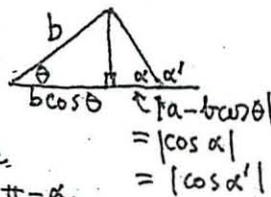
$$a) \Delta c \approx \left(\frac{a - b \cos \theta}{c}\right) \Delta a + \left(\frac{b - a \cos \theta}{c}\right) \Delta b + \left(\frac{ab \sin \theta}{c}\right) \Delta \theta$$

$$b) a=1, b=2, \theta=\pi/3, \text{ formula is: } \Delta c \approx \left(\frac{1-2 \cdot 1/2}{c}\right) \Delta a + \left(\frac{2-1/2}{c}\right) \Delta b + \left(\frac{2 \cdot \sqrt{3}/2}{c}\right) \Delta \theta$$

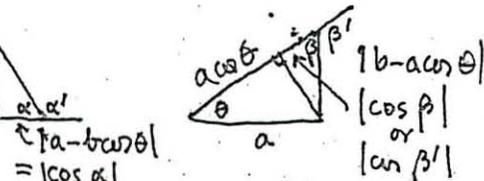
$$\Delta c \approx 0 \cdot \Delta a + \frac{3}{2c} \Delta b + \frac{\sqrt{3}}{c} \Delta \theta$$

\therefore more sensitive to b

c)



(since $\alpha' = \pi - \alpha$, $\cos \alpha' = -\cos \alpha$)



According to (a) c is most sensitive to changes in the side

for which the angle α or β has the biggest cosine, i.e. is further from $\pi/2$. Makes sense geometrically. (more sensitive to a than to b .)

2 $z = x^2 - y^2$ $P: (3, 2, 5)$ line is: $x = 3 + at$
 $y = 2 + bt$
 $z = 5 + t$

a) L goes through P ; it lies on the graph of $z \iff$

$$5 + t = (3 + at)^2 - (2 + bt)^2 \text{ for all } t.$$

$$5 + t = (a^2 - b^2)t^2 + (6a - 4b)t + 5$$

$$\iff \boxed{a^2 - b^2 = 0} \text{ and } \boxed{6a - 4b = 1}:$$

(so $b = a$ or $b = -a$) if $b = a$, $a = b = 1/2$
 if $b = -a$, $a = 1/10, b = -1/10$

so these values of (a, b) give the two lines.

b) The tan. plane at $(3, 2, 5)$ is $\left(\begin{matrix} \text{since } \frac{\partial z}{\partial x} = 6 \\ \text{at } (3, 2): \frac{\partial z}{\partial y} = -4 \end{matrix} \right)$
 $z - 5 = 6(x - 3) - 4(y - 2)$

Subst. the eqns of the line in: line lies on plane if $t = 6at - 4bt$, for all t .

But this is true for on two lines, since $a + b$ satisfy \otimes for both pairs (a, b) .

4

a) $h_x \approx \frac{\Delta h}{\Delta x} \approx \frac{-100}{1000} = -.1$

$h_y \approx \frac{\Delta h}{\Delta y} \approx \frac{-100}{500} = -.2$

b) $\frac{dh}{ds} \Big|_{A, \hat{j} - \hat{i}} \approx \frac{\Delta h}{\Delta s} \approx \frac{-100}{500} = -.2$

c) $P \approx (1.8, 1.1)$ $Q: (2.6, 1.9)$

d) $R: (4.0, 1.7)$ or $R: (4.2, 1.9)$ (maybe)
 $(\hat{i} + \hat{j})$ should have the tangent direction at R

Lecture 12

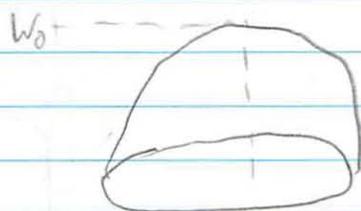
Min-max problems, least squares approx

3/4

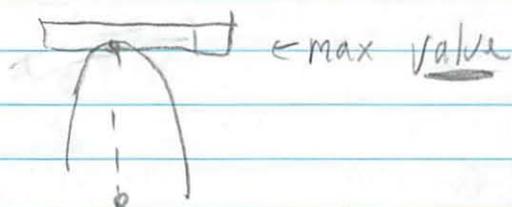
Handout PS 4

In math, max and min are important
- how some problems can be solved

$$w = f(x, y)$$



(x_0, y_0) ← how do you find a max
or min point
- where the tangent plane
is horizontal



← max point (the independent variables)

$$w - w_0 = \left(\frac{\partial f}{\partial x} \right)_0 (x - x_0) + \left(\frac{\partial f}{\partial y} \right)_0 (y - y_0)$$

↑
horizontal when this = 0

↑
eqn. of tangent plane

$$\frac{\partial f}{\partial x} \text{ and } \frac{\partial f}{\partial y} = 0 \text{ at } P_0$$

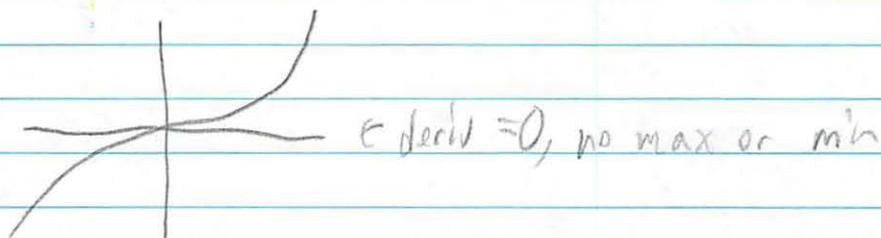
Critical point

$$\text{if } \begin{cases} \frac{\partial f}{\partial x} = 0 \\ \frac{\partial f}{\partial y} = 0 \end{cases} \text{ at } P_0$$

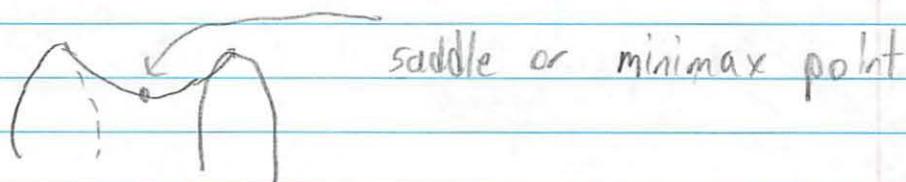
But it could be a max or min
which is it?

Usually obvious if physical
Will do: tomorrow

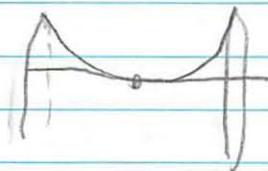
But also can have issue



A saddle shaped surface is an example $x^2 - y^2$



So the tangent line intersects the end of the saddle



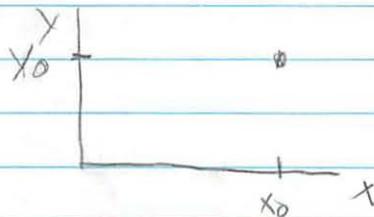
A cone as well



↳ minimum, obvious not a critical pt
does not have a tangent plane at that pt
so can't calc partial derivs don't exist there

If boundaries, max and min can occur on boundary
- partial derivs $\neq 0$
- calculus will not help

If more than 3D
- can't draw tangent planes
- but it's the same
- different reasonings



$w = \text{temp at } x, y$

$w = f(x, y_0)$ partial function

↳ has x_0 at max pt

$P_0 = \text{max point}$

$$\left. \frac{df(x, y_0)}{dx} \right|_0 = 0$$

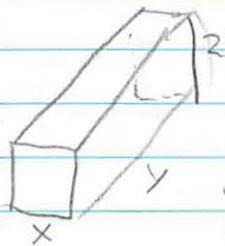
Same reasoning
for y

$$\left. \frac{\partial f}{\partial x} \right|_{P_0} = 0$$

Can use identical reasoning for n -variables

$$\frac{d}{dx} f(x, y_0, z_0) = \left(\frac{\partial f}{\partial x} \right)_{y_0, z_0}$$

Example



Vol must be 3 cu ft

3 layers on bottom

2 layers on ends

1 layer on side

0 layers on top

rectangular

Minimize cost \rightarrow cardboard area C

$$C = 3(xy) + 2 \cdot 2(xz) + 2 \cdot 1(yz)$$

no gradients + partial derivatives

- since variables depend on each other

need constraint $xyz = 3$

$$z = \frac{3}{xy}$$

get into terms of 1 variable

$$C = \frac{4 \cdot 3}{y} + \frac{2 \cdot 3}{x} + 3xy \quad \text{now only 2 variables}$$

$$= \frac{12}{y} + \frac{6}{x} + 3xy$$

*remember
how to do

$$\frac{\partial C}{\partial x} = -\frac{6}{x^2} + 3y = 0$$

$$\frac{\partial C}{\partial y} = -\frac{12}{y^2} + 3x = 0$$

a) simultaneous

b) not linear

* must eliminate one variable
(think about it)

* if not linear, not easy to solve, need to read a gigantic book on how
* guess for a solution

$$y = \frac{2}{x^2}$$

$$x = \frac{4}{y^2} = \frac{4x^4}{4}$$

reject $x=0$

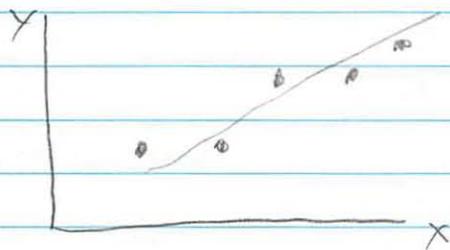
get $x=1$

then $y=2$

$$2 = \frac{3}{2}$$

Method of Least Squares / Regression Line

Math: explanation
cutting
corners



trying to find general law connecting the lines

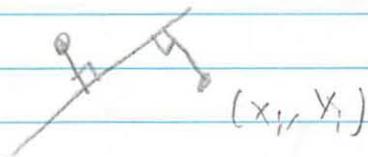
"line of best fit"

treated as a minimum problem

$$y = mx + b$$

which m, b should choose for line

okward to calc perpendicular distance



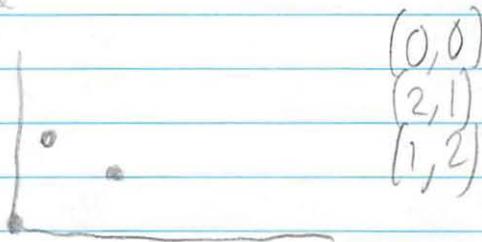
So optimize vertical line

- all must be $(+)$
- can't differentiate abs

deviation: $mx_i + b - y_i$

$$\text{minimize } D = \sum_{i=1}^n (mx_i + b - y_i)^2 \quad m, b \text{ rational}$$

Example



$$b^2 + (2m + b - 1)^2 + (m + b - 2)^2 = D$$

do not expand
differentiate as they are

$$\frac{\partial D}{\partial m} = 2(2m + b - 1) \cdot 2 + 2(m + b - 2) \cdot 1 = 0$$

$$\frac{\partial D}{\partial b} = 2b + 2(m + b - 2) + 2(2m + b - 1) = 0$$

Lecture 13

2nd Deriv Max Min 2 + Lagrange multipliers

3/5

Review

$$W = f(x, y) \quad \text{max + min pts}$$

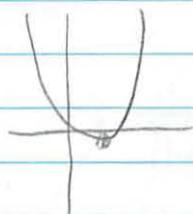
critical pts
↳ solutions

$$\begin{cases} \frac{\partial E}{\partial x} = 0 \\ \frac{\partial E}{\partial y} = 0 \end{cases}$$

Usually non linear

- hard to solve
- easy in this class

2D



min

~~first deriv~~ $\ominus \rightarrow \oplus$
2nd deriv \oplus



max

2nd deriv \ominus

3D

similar - but more partial derivatives

$$W = W_0 + (W_x)_0 (x - x_0) + (W_y)_0 (y - y_0) + \frac{1}{2} (W_{xx})_0 (x - x_0)^2 + 2(W_{xy})_0 (x - x_0)(y - y_0) + (W_{yy})_0 (y - y_0)^2$$

2nd order terms

\uparrow
 $W_{xy} + W_{yx}$

same for nice functions

At a critical pt

$$(W_x)_0 = (W_y)_0 = 0$$

Must calc the 3 partial derivs

$$(W_{xx})_0 = A$$

$$(W_{xy})_0 = B$$

$$(W_{yy})_0 = C$$

} aliases

$\hookrightarrow P_0$ is the critical pt you are testing for min-max

$$AC - B^2$$

\uparrow discriminant

if $< 0 \rightarrow$ saddle

$> 0 \rightarrow$ if A or $C > 0 \rightarrow$ min
 \hookrightarrow if A or $C < 0 \rightarrow$ max

Example $w = x^3 + 3xy^2 - 3x$

$$w_x = 3x^2 + 3y^2 - 3$$

$$w_y = 6xy$$

} when both = 0

$$6xy = 3x^2 + 3y^2 - 3 = 0$$

\hookrightarrow know either x or y or both = 0

can be or $\begin{cases} x=0 & y = \pm 1 \\ x = \pm 1 & y = 0 \end{cases}$

have 4 critical points

↳

the aliases

$$W_{xx} = 6x = A$$

$$W_{xy} = 6y = B$$

$$W_{yy} = 6x = C$$

Critical pts to test

$$(0, 1) \rightarrow AC - B^2 = 6 \cdot 0 \cdot 6 \cdot 1 - (6 \cdot 1)^2 = -36 \ominus \text{ saddle}$$

$$(0, -1) \rightarrow AC - B^2 = 6 \cdot 0 \cdot 6 \cdot (-1) - (6 \cdot (-1))^2 = -36 \ominus \text{ saddle}$$

$$(1, 0) \rightarrow AC - B^2 = 6 \cdot 1 \cdot 6 \cdot 0 - (6 \cdot 0)^2 = 0 \oplus \rightarrow A \oplus \text{ min}$$

$$(-1, 0) \rightarrow AC - B^2 = 6 \cdot (-1) \cdot 6 \cdot 0 - (6 \cdot 0)^2 = 0 \oplus \rightarrow A \ominus \text{ max}$$

Why test works: algebra

at critical pt w

assume

$$c.p. = (0, 0) \quad w_0 = 0$$

$$z_w \approx \frac{1}{2} [Ax^2 + 2Bxy + Cy^2]$$

when at $[0, 0]$ min, max, or saddle?

Same as proving quadratic formula

* Completing the square *

$$= A \left(x + \frac{B}{A} y \right)^2 + \left(\frac{AC - B^2}{A} \right) y^2$$

\oplus

\oplus/\ominus

\oplus

↳ did not really get what he said about this

he did
quickly

Lagrange multiplier

$$W = f(x, y, z)$$

↳ variables constrained by equation

Find max or min

but variables are constrained to satisfy eq

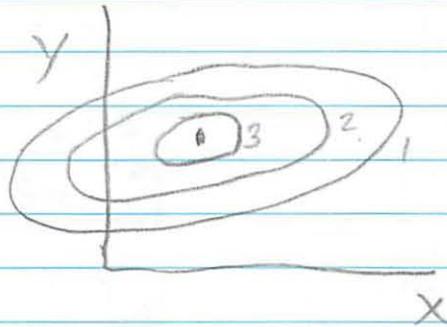
$$g(x, y, z) = 0$$

↳ defines a surface

don't know what it looks like

$$W = f(x, y)$$

$$g(x, y) = 0$$

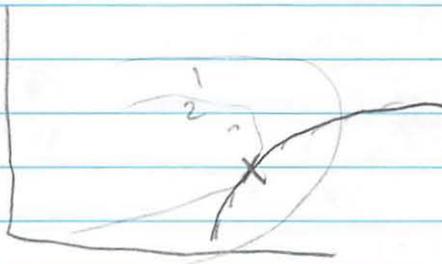


what do points satisfying constraint look like?

* constraint curve *

- walk along the trail

$$g(x, y) = 0$$



What is special about this point?

- two curves tangent

* at P_0 level curves through P_0 and $G=0$ *
have parallel Normals
- scalar multiple of the other

⊥ to level curve $\vec{\nabla} W$
⊥ to $g(x, y) = 0$ $\vec{\nabla} g$

$$\frac{4}{y} + \frac{3}{z} = d$$

$$\frac{2}{x} + \frac{3}{z} = d \quad \theta = 0$$

$$\frac{4}{y} + \frac{2}{x} = d$$

Set = to and solve

$$\frac{4}{y} + \frac{3}{z} = \frac{2}{x} + \frac{3}{z} = \frac{4}{y} + \frac{2}{x}$$

$$x y z = 3$$

$$\frac{4}{y} = \frac{2}{x} - \frac{3}{z}$$

$$\frac{24}{x y z} = 8 \quad \leftarrow \text{where?}$$

$$\frac{4}{y} = 2 \quad y = 2$$

$$\frac{3}{z} = 2 \quad z = \frac{3}{2}$$

$$\frac{2}{x} = 2 \quad x = 1$$

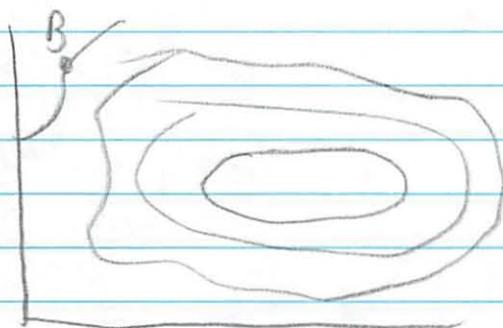
Recitation

3/8

Pset solutions - get

Maintain problem a lot of people missed

a)



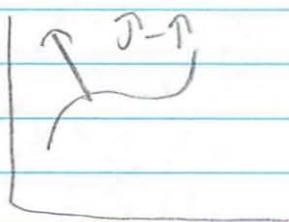
$h(x, y)$

$$a) h_x(B) = \frac{\partial h}{\partial x}(B) \approx \frac{\Delta h}{\Delta x}$$

for small Δx (limit)

$\int \Delta x$ ← parallel to x axis

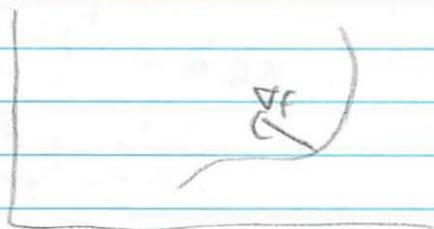
b)



same directional derivative

c)

$$h_x = 0$$



∇ always perpendicular to level curve

$$\nabla f = \langle 0, _ \rangle$$

↑ gradient is vertical
→ tangent is horizontal



all points inside out

Lectures - optimization problems; min/max of $f(x, y)$

- without constraints

- critical pts, etc

ex least $\frac{1}{1}$ (could not read)

- w/ constraint $g(x, y) = 0$

- elimination or Lagrange multipliers

ex) $f(x) = 2x^2 + y^4 - xy + 1$

a) What are the critical points?

b) Are they local mins, local maxes, or saddle pts?

a) When the 2 partial derivs $\stackrel{\text{each}}{=} 0$

$$\frac{\partial}{\partial x} = 2 \cdot 2x - 1 \cdot y = f_x(x, y)$$

$$\frac{\partial}{\partial y} = 4y^3 - 1 \cdot x = f_y(x, y)$$

So set $=$ to 0

$$\begin{cases} 4x - y = 0 \\ 4y^3 - x = 0 \end{cases}$$

Solve system for x and y

today
- do Post now
- ten night for
proposal
gives in
save the

Not linear - no matrix

Use substitution to get in terms of 1 equation

$$4y^3 - \frac{y}{4} = 0$$

Solve equation for y

~~$$\frac{4y^3}{4} = \frac{y}{4}$$~~

~~$$y^3 = \frac{y}{16}$$~~

~~$$\cdot y \quad \cdot y$$~~

~~$$y^4 = \frac{1}{16}$$~~

also $y=0$

$$y^4 - y = 0$$

$$y^2 - \frac{1}{16} = 0$$

$$y = \pm \frac{1}{4}$$

plug in to find x

$$\begin{aligned} (x, y) &= (0, 0) \\ &= \left(\frac{1}{16}, \frac{1}{4}\right) \\ &= \left(-\frac{1}{16}, -\frac{1}{4}\right) \end{aligned}$$

These are the 3 possibilities

b) Which are max, min, or saddle?

Need the 2nd deriv test

$$\begin{aligned} f_{xx} f_{yy} - f_{xy}^2 > 0 &\rightarrow f_{xx} > 0 \text{ local min} \\ &\rightarrow f_{xx} < 0 \text{ local max} \\ f_{xx} f_{yy} - f_{xy}^2 < 0 &\rightarrow \text{saddle pt} \\ = 0 &\rightarrow \text{don't know} \end{aligned}$$

$$f_{xx} = 4 \quad f_{yy} = 12y^2 \quad f_{xy} = -1 \quad \text{often} = f_{yx}$$

$$-4 \cdot 12y^2 - (-1)^2$$

$$48y^2 - 1$$

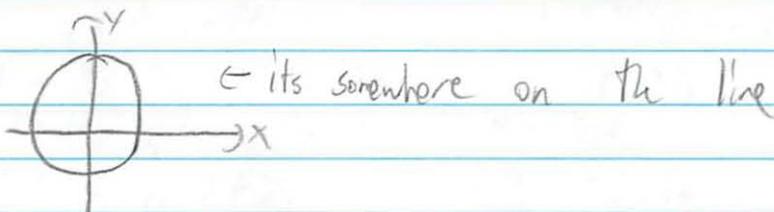
↳ at $(0,0)$ this is \ominus so saddle pt
 $(\frac{1}{6}, \frac{1}{4}) \quad \oplus \rightarrow f_{xx} \oplus \rightarrow \text{minimum (local)}$
 $(-\frac{1}{6}, -\frac{1}{4}) \quad \oplus \rightarrow f_{xx} \oplus \rightarrow \text{local min}$

Ex2 Is a constraint

$$f(x,y) = x^2 - y^2 - xy \quad g(x,y) = x^2 + y^2 - 1$$

What is the maximum of $f(x,y)$ subject to the constraint $g(x,y) = 0$

↑ needs to satisfy the equation
 in this case it is a unit circle



2 methods

Method 1 - elimination

use constraint to get rid of 1 variable

$$g(x,y) = 0 \rightarrow y = \pm \sqrt{1-x^2}$$

want to maximize

$$h(x) = f(x,y) = x^2 - (1-x^2) \pm x\sqrt{1-x^2}$$

± need to find max $h(x)$ min $h(x)$

Now easier to solve - only 1 variable
Sometimes this is easy - but not always

Method 2 - Lagrange Multipliers
- need to know this

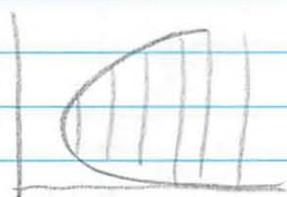
Solve
$$\begin{cases} f_x = \lambda g_x \\ f_y = \lambda g_y \\ g(x, y) = 0 \end{cases}$$
 \leftarrow don't forget constraint

Variables x, y, λ (3 equations w/ 3 unknowns \odot)

Here
$$\begin{cases} 2x - y = \lambda 2x \\ 2y - x = \lambda 2y \\ x^2 + y^2 = 1 \end{cases}$$
 \leftarrow did the partial derivatives

ex 3

General situation \rightarrow optimization problem



D = domain bounded by $g(x, y) = 0$
 D : $g(x, y) > 0$

Find min + max of f in that domain
 $f(x, y)$ D
values of x and y constrained

Where can the maximum value be attained?

Either

- at critical pt inside domain D
- on the boundary $g(x, y) = 0$
- must use elimination / Lagrange multiplier to find

- can also find max nowhere (at ∞)
when $x \rightarrow \infty$ or $y \rightarrow \infty$
if ∞ is in the domain

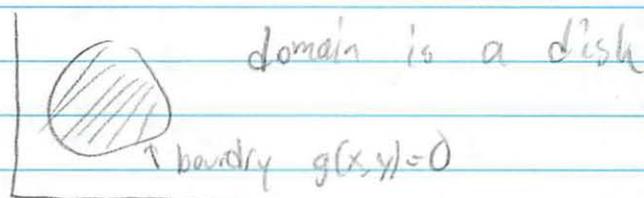
example

$$\text{min of } f(x, y) = (x-1)^2 + y^2$$

in domain $g(x, y) \leq 0$ (inside circle)

where $g(x, y) = x^2 + y^2 - 2$

- here is no ∞



→ Look at these points + find max
↳ Compare the value of $f(x, y)$ for all
of the above candidates

Lecture 14

Chain Rule

3/9

Chain rule

- important in functions that use several variables
- important in every subject
- may have wrong idea

1 var

- 2 forms: functions $f(g(x))$

$$\frac{d}{dx} f(g(x)) = f'(g(x)) \cdot g'(x)$$

ex $\sin^2(\sqrt{2x+1})$

\uparrow w/ respect to $g(x)$ considered as a variable
 \uparrow w/ respect to x

- Variable form

$$w = w(x)$$

\uparrow usually y

$$x = x(t)$$

$$w(x(t))$$

use Leibniz's form

$$\boxed{\frac{dw}{dt} = \frac{dw}{dx} \cdot \frac{dx}{dt}}$$

just cancel the x s (in right)

- theoretical
- related rates

2 variables (n-variables same)

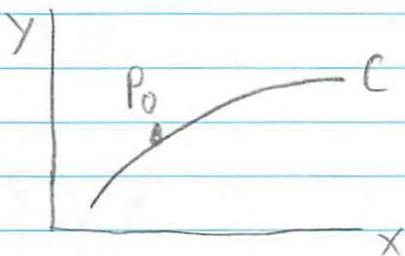
$$w = w(x, y)$$

$x = x(t)$ $y = y(t)$ sub in and w becomes function of t
curve

$$W = w(x(t), y(t))$$

$$\frac{dw}{dt} = ?$$

↑ parametrized motion in a plane



$w = \text{temp at } (x, y)$

What is being asked?

w is temp of ant at that pt at time t

What is rate of change of temp as ant walks? - chain rule gives you this

$$\frac{dw}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\Delta w}{\Delta t} \leftarrow \text{new temp}$$

) all at P_0

? calc Δw w/ approx formula

$$\Delta w \approx \left(\frac{\partial w}{\partial x} \right)_{P_0} \Delta x + \left(\frac{\partial w}{\partial y} \right)_{P_0} \Delta y$$

at P_0

Now / by Δt

$$\frac{\Delta w}{\Delta t} = \left(\frac{\partial w}{\partial x} \right)_0 \frac{\Delta x}{\Delta t} + \left(\frac{\partial w}{\partial y} \right)_0 \frac{\Delta y}{\Delta t}$$

↓

$$\left(\frac{dw}{dt} \right)_0 = \left(\frac{\partial w}{\partial x} \right)_0 \left(\frac{dx}{dt} \right)_0 + \left(\frac{\partial w}{\partial y} \right)_0 \left(\frac{dy}{dt} \right)_0 \quad \text{at } P_0$$

Can drop to P_0 to find general point
Get to chain rule ↷

$$\boxed{\frac{dw}{dt} = \frac{\partial w}{\partial x} \frac{dx}{dt} + \frac{\partial w}{\partial y} \frac{dy}{dt} \quad \text{chain rule (2 variables)}}$$

= Now a form which does not specify # of variables

$$\boxed{\frac{dw}{dt} = \nabla w \cdot \frac{dr}{dt}}$$

$$\vec{r} = \langle x(t), y(t) \rangle$$
$$\vec{v} = \frac{d\vec{r}}{dt}$$

depends only on $w(x, y)$
↑
temp

the motion you are interested in
 $x(t), y(t)$
motion

Works in nD (dimensions).

This is theoretical - not for actual calculation

Helix $\vec{r} = \langle a \cos t, a \sin t, t \rangle$

$w = x^2 + y^2$ ← temp function

$w(t) = (a \cos t)^2 + (a \sin t)^2$

$w(t) = a^2$

$\frac{dw}{dt} = 0$

easy, substitution, no need to do chain rule

$w = C$ cylinder in space
axis is on z-axis

As ant goes around path, its temp does not change, always C , so deriv = 0

Now with chain rule

$$\frac{dw}{dt} = 2x(-a \sin t) + 2y(a \cos t)$$

- can't abandon, need to simplify

- but how - still in terms of t

- sub in values for x, y, t for a pt

- otherwise sub in $x = x(t)$ $y = y(t)$

$$= -2a \cos t \sin t + 2a \sin t \cos t$$

$$= 0$$

↑ see how much more trouble
that's why the other way

If can't remember 18.01,

$$\frac{d}{dx} u(x)v(x)$$

$$w = u \cdot v$$

$$u = u(x)$$

$$v = v(x)$$

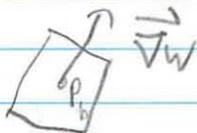
$$= v \cdot \frac{du}{dx} + u \cdot \frac{dv}{dx} \quad \text{by the chain rule}$$

3 functions

$$\frac{d}{dx}(uvw)$$

$$= vw \cdot \frac{du}{dx} + \text{---} + \text{---}$$

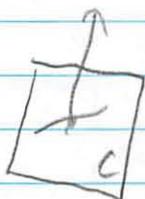
Works w/ n variables
will have n terms



n level surface $w(x, y, z) = c$

For tangent vector of plane, take normal vector to plane.

$(\vec{\nabla} w)_r \perp$ surface at P_0



ie perpendicular to any curve
on surface S through P_0

$$C: \vec{r} = \langle x(t), y(t), z(t) \rangle$$

lies on surface at $t=0$ at $P=0$

↳ $w(x(t), y(t), z(t))$ when plug in
must get back C

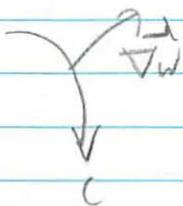
$$\frac{dw}{dt} = 0$$

↳ constant - level surface, temp constant

Now long version w/ chain rule

$$\frac{dw}{dt} = \vec{\nabla}w \cdot \frac{d\vec{r}}{dt} = 0$$

↑ ↑ dot product
Gradient is perpendicular to
tangent of curve



Functions that are functions of other variables

$$w = w(x, y)$$

$$x = x(u, v)$$

$$y = y(u, v)$$

$$w = w(x(u, v), y(u, v))$$

- What are the partial derivatives $\frac{\partial w}{\partial u}, \frac{\partial w}{\partial v}$

$$\frac{\partial w}{\partial u} \quad \text{- hold } v \text{ constant}$$
$$\frac{\partial w}{\partial u} = \frac{dw}{du} \quad \text{with } v \text{ held constant}$$

Ok to use $\frac{\partial w}{\partial u}$ chain rule for 1 variable
chain rule from earlier today

$$\frac{\partial w}{\partial u} = \frac{\partial w}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial w}{\partial y} \cdot \frac{\partial y}{\partial u}$$

$$\frac{\partial w}{\partial v} = \frac{\partial w}{\partial x} \cdot \frac{\partial x}{\partial v} + \frac{\partial w}{\partial y} \cdot \frac{\partial y}{\partial v}$$

↳ just another way of writing chain rule

Rect \rightarrow Polar coords

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$w = \sqrt{x^2 + y^2}$$

$$\frac{\partial w}{\partial r} = 1 \quad \text{after changing to polar} = 1 \quad \text{since } w = r$$

$$\frac{\partial w}{\partial x} = \frac{x}{\sqrt{x^2+y^2}} = \frac{x}{w}$$

$$\frac{\partial w}{\partial y} = \frac{y}{\sqrt{x^2+y^2}} = \frac{y}{w}$$

$$w = \sqrt{x^2+y^2}$$
$$\frac{\partial w}{\partial r} = \frac{x}{w} \cdot \cos \theta + \frac{y}{w} \cdot \sin \theta$$

Which = 1 since $w=r$
Some hard to simplify
continue substitution

$$= \cos \theta \cdot \cos \theta + \sin \theta \cdot \sin \theta$$
$$= 1$$

Recitation

3/10

ex 1 Find the pt on the plane $x+2y+3z=7$ which is closest to origin

- optimization problem
- solve using Lagrange

Need to minimize $f(x, y, z) = \sqrt{x^2 + y^2 + z^2}$
easier to do distance squared $\Rightarrow x^2 + y^2 + z^2$ function to be minimized

$$\text{Constraint } g(x, y, z) = 0 \\ \hookrightarrow g(x, y, z) = x + 2y + 3z - 7$$

$$\text{Equations } \begin{cases} f_x = \lambda g_x \\ f_y = \lambda g_y \\ f_z = \lambda g_z \\ g = 0 \end{cases} \text{ = don't forget}$$

for variables x, y, z, λ

Compute partial derivatives

$$\begin{cases} f_x = 2x = \lambda \\ f_y = 2y = \lambda \\ f_z = 2z = \lambda \\ x + 2y + 3z = 7 \end{cases}$$

Solve for x, y, z

$$\begin{aligned} x &= \frac{\lambda}{2} \\ y &= \frac{\lambda}{2} \\ z &= \frac{3\lambda}{2} \end{aligned}$$

get it better now

$$\frac{\lambda}{2} + 2\lambda + 3 \times \frac{3}{2}\lambda = 7$$

$$7\lambda = 7$$

$$\lambda = 1$$

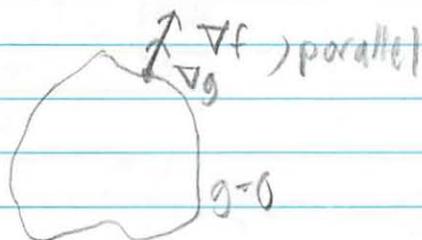
Now plug λ in

$$x = \frac{\lambda}{2} = \frac{1}{2}$$

$$y = \lambda = 1$$

$$z = \frac{3}{2}\lambda = \frac{3}{2}$$

Thus closet pt is $(x, y, z) = \left(\frac{1}{2}, 1, \frac{3}{2}\right)$



Lecture
review

$$\frac{d}{dt} f(x(t), y(t)) = x(t) \frac{\partial f}{\partial x}(x, y) + y(t) \frac{\partial f}{\partial y}(x, y)$$

$$\begin{aligned} \frac{\partial}{\partial u} w(x(u, v), y(u, v)) &= \frac{\partial x}{\partial u} \frac{\partial w}{\partial x} + \frac{\partial y}{\partial u} \frac{\partial w}{\partial y} \\ &= w_u = \frac{\partial x}{\partial u} w_x + \frac{\partial y}{\partial u} w_y \end{aligned}$$

Ex 2 $f(u, v) = u^v$

a) Find a general formula for $\frac{d}{dx} f(u(x), v(x))$

$$\frac{d}{dx} f(u(x), v(x)) = u' \frac{\partial f}{\partial u} + v' \frac{\partial f}{\partial v}$$

↑ ↑
plug in

$$\frac{\partial f}{\partial u} = \frac{\partial u^v}{\partial u} = u^{v-1} = c u^{c-1} = v u^{v-1}$$

c = constant

$$\frac{\partial f}{\partial v} = \frac{\partial u^v}{\partial v} = u^v = \frac{\partial}{\partial v} e^{(\ln u)v} =$$

$$= \ln u e^{(\ln u)v} = (\ln u) u^v$$

$u^v = (e^{\ln u})^v = e^{(\ln u)v}$
trick
know tricks!

Thus $\frac{d}{dx} f(u(x), v(x))$

$$= u' v u^{v-1} + v' (\ln u) u^v$$

b $g(x) = x^{\sin x}$
 $g'(x) = ?$

$(x^{\sin x})^x$
Plug in for these values

$$g(x) = x^{\sin x} = f(u(x), v(x))$$

↑ ↑
u(x) v(x)

recognize that it fits the pattern

calculate

$$u = x \rightarrow u' = 1$$

$$v = \sin x \rightarrow v' = \cos x$$

$$\text{So } g'(x) = |x \sin x \cdot x^{\sin x - 1} + \cos x \ln x \cdot x^{\sin x}|$$

c) $h(x) = (\ln x)^x$ Plug in for these values
 $h'(x) = ?$

$$h(x) = f(\ln x, x)$$

$$u = \ln x \rightarrow u' = \frac{1}{x}$$

$$v = x \rightarrow v' = 1$$

$$h'(x) = \frac{1}{x} \cdot x \ln x^{x-1} + \ln(\ln(x)) (\ln x)^x$$

ex3

$$x = u^2 - v^2$$

$$y = 2uv$$

a function of u and v

$$w = f(x, y) \text{ a function of } x \text{ and } y$$

$$\text{Show/Prove } (w_x)^2 + (w_y)^2 = \frac{(w_u)^2 + (w_v)^2}{4(u^2 + v^2)}$$

$$w_u = \frac{\partial x}{\partial u} w_x + \frac{\partial y}{\partial u} w_y$$

$$= 2u w_x + 2v w_y$$

$$w_v = \frac{\partial x}{\partial v} w_x + \frac{\partial y}{\partial v} w_y$$

$$= -2v w_x + 2u w_y$$

Now put it in

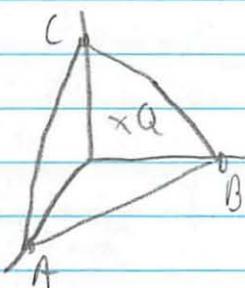
$$\begin{aligned}w_x^2 + w_y^2 &= (2uw_x + 2vw_y)^2 + (-2vw_x + 2uw_y)^2 \\&= (4u^2 + 4v^2)w_x^2 + (4u^2 + 4v^2)w_y^2 \\&\quad + (4uv - 4uv)w_xw_y \\&= 4(u^2 + v^2)(w_x^2 + w_y^2)\end{aligned}$$

So, proved now

$$\frac{w_x^2 + w_y^2}{4(u^2 + v^2)} = w_x^2 + w_y^2 \quad \textcircled{1}$$

ex 4 Optimization w/ Lagrange Multipliers

$$Q = (1, 1, 2)$$



Look at planes going through Q and crossing axis at point

$$A = (a, 0, 0) \quad \text{with } a, b, c > 0$$

$$B = (0, b, 0)$$

$$C = (0, 0, c)$$

should realize this!

Find the minimum value of V_C tetrahedron OABC

Trying to optimize: volume
minimum

Variables are a, b, c

volume tetrahedron = $\frac{abc}{6}$ ← know this too!

constraint: Q is in the plane ABC

(That's setup - won't do today)

.08 (1971) .10 (1974) .13 (1975) .15 (1978) .20 (1981) .22 (1985) .25 (1988) .29 (1991)
 .32 (1995) .33 (1999) .34 (2001) .37 (2002) .39 (2006) .41 (2007) .42 (2008) .44 (2009)

b) Using MatLab (or an equivalent program that gives printout, like Maple or Mathematica), make a scatter plot of this data (i.e., just plot the data points; put a * at each data point). To get a decent result, use as the scales: x = number of years after 1970, y = postage in cents.

c) In Matlab, enter A and r , and calculate a and b , using part (a).

Then plot the line $Y = aX + b$, superimposed upon the scatter plot (use the "hold" command). To do this let $t = [0 : 1 : 45]$ and plot the function $a * t + b$. Note down the values of a and b . Get a printout and on it, write the equation of the line and label the two axes. On this printout, include the results of part (a).

d) What does the model predict for the postage rate in 2013, the year you graduate? Note it on the printout.

Problem 3. (Fri. 3 pts.: 1,2)

a) Verify using the second-derivative test that the critical point you found in Problem 1 is actually a minimum point for $w(t, u)$.

b) Work 2H-2; you'll need to use the result in Exercise 1B-15, which you can accept without proof.

Problem 4. (Fri. 3 pts.: 1.5, 1.5)

A surface given by an equation $f(x, y, z) = c$ can be thought of as a level surface for the function $f(x, y, z)$.

Suppose the point $A : (a, b, c)$ is not on the surface, and we want to find the point $P_0 : (x_0, y_0, z_0)$ on the surface which is closest to A . The way to do this is (as in Problem 1 above) to find the point P_0 minimizing the square of the distance $w(x, y, z) = |AP|^2$, since this leads to easier computations than minimizing the distance $|AP|$ itself. (Here P is a general point on the surface.)

Suppose this minimum problem is solved by Lagrange multipliers.

a) Give the four equations of the Lagrange method.

b) Show they can be interpreted as saying that

the minimizing line segment AP_0 is perpendicular to the surface.

Problem 5. (Tues. 4 pts: 1, 1, 2)

Let $x = u \cos \phi - v \sin \phi$, $y = u \sin \phi + v \cos \phi$.

a) Write this variable change in matrix form: $\langle x, y \rangle = \langle u, v \rangle M$, where M is a matrix.

b) The vectors $\mathbf{i}' = \langle 1, 0 \rangle$ and $\mathbf{j}' = \langle 0, 1 \rangle$ in the uv -coordinates correspond to what vectors in the xy -coordinates? Calculate and draw them in the xy -plane.

c) As part (b) suggests, the uv -axes are just the xy -axes rotated through the angle ϕ . Show using the chain rule that this change of variables does not change the length of the gradient vector. That is, if for any differentiable function $w(x, y)$ we calculate $\nabla w(x, y)$ in xy -coordinates, or make the above change of variables and calculate $\nabla w(x(u, v), y(u, v))$ in uv -coordinates, we get the same value for the length-squared of ∇w at every point P :

$$(w_u)^2 + (w_v)^2 = (w_x)^2 + (w_y)^2.$$

(As we did in two previous problems, it suffices to work with the square of the length rather than the length itself.)

P-Set 4

Michael Plasmier

3/9

Lecture 12 Min max problems, least squares approx

2F-1b Find the points on each of the following surfaces which is closest to the origin
- minimize the square of the distance
not the distance itself

$$x^2 - yz = 1$$

Use the relation $x^2 = 1 + yz$
to eliminate x
- I guess just pick one

~~or~~

* Denote $x^2 + y^2 + z^2 = D$ as square of distance from point (x, y, z)

$$\text{So } D = 1 + yz + y^2 + z^2$$

$$\frac{\partial}{\partial y} = 0 + z + 2y + 0$$

$$\frac{\partial}{\partial z} = 0 + y + 0 + 2z$$

set = 0

$$z + 2y = 0$$

$$y + 2z = 0$$

solve - but get it in terms of 1 variable to make it easy.

$$\begin{aligned} z + 2y &= 0 \\ y + 2z &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{for both!}$$

$$z = -2y \quad y = -2z$$

← plug into other →

$$y = -2(-2y)$$

$$y = 4y$$

now what solves that

$$y = 0$$

⓪ only solution

So find z $z = -2(0) = 0$

So find x $x^2 = 1 + (0)^2$

$$x^2 = 1$$

$$x = \pm 1$$

So 2 pts $(\pm 1, 0, 0)$ which are
distance $1 + (0)(0) + (0)^2 + (0)^2 = 1$
from origin

get this
better now

5. A drawer in a chest has open top bottom + back # $1/\text{ft}^2$
sides # $2/\text{ft}^2$ front # $4/\text{ft}^2$ $V = 2.5 \text{ft}^3$
Optimize.



$$C = 1x^2 + 1xy + 2 \cdot 2yz + 4xy$$

$$xy^2 = 2.5$$

Solve for 1 : $z = \frac{2.5}{xy}$ and sub in

$$C = x \cdot \frac{2.5}{xy} + 5xy + 4y \frac{2.5}{xy}$$

$$= \frac{2.5}{y} + 5xy + \frac{10}{x}$$

$$\frac{\partial C}{\partial x} = 0 + 5y + \frac{-10}{x^2}$$

$$\frac{\partial C}{\partial y} = \frac{-2.5}{y^2} + 5x + 0$$

$$5y - \frac{10}{x^2} = 0$$

$$\frac{-2.5}{y^2} + 5x = 0$$

$$5y = \frac{10}{x^2}$$

$$5x = \frac{2.5}{y^2}$$

$$y = \frac{2}{x^2}$$

$$x = \frac{1}{2y^2}$$

plug 1 into other \rightarrow

$$x = \frac{1}{2\left(\frac{2}{x^2}\right)^2} = \frac{1}{2\left(\frac{4}{x^4}\right)} = \frac{1}{\frac{8}{x^4}} = \frac{x^4}{8} \quad \text{①}$$

now what solves that?

$$8x = x^4$$

$$\text{calc } x=0 \text{ or } x=2$$

reject, otherwise no box!

$$y = \frac{2}{(2)^2} = \frac{1}{2}$$

$$2 = \frac{2.5}{(2)\left(\frac{1}{2}\right)} = 2.5$$

$$\text{Cost} = \frac{2.5}{1.5} + 5(2)\left(\frac{1}{2}\right) + \frac{10}{2} = 15$$

must have made math error - steps right (memorize)

26-1C

Find by method of least squares the line which best fits the data points given

(1,1) (2,3) (3,2)

- trying to find general law connecting lines "line of best fit"

- want to minimize $D = \sum_{i=1}^n (mx_i + b - y_i)^2$ m, b rational

$$(m+b-1)^2 + (2m+b-3)^2 + (3m+b-2)^2$$

Don't expand! Differentiate as is

$$\frac{\partial D}{\partial m} = 2(m+b-1) \cdot 1 + 2(2m+b-3) \cdot 2 + 2(3m+b-2) \cdot 3 = 0$$

$$\frac{\partial D}{\partial b} = 2(m+b-1) \cdot 1 + 2(2m+b-3) + 2(3m+b-2) = 0$$

~~always the same! no! copy error~~

lecture notes
end!

$$2m + 2b - 2 + 8m + 4b - 12 + 18m + 6b - 12 = 0$$

$$\therefore 28m + 18b = 26 \quad \text{= addition error}$$

$$14m + 9b = 13$$

$$2m + 2b - 2 + 2m + 2b - 2 + 2m + 2b - 2 = 0$$

$$6m + 6b = 6$$

$$\cancel{2m + b = 1}$$

$$14m = 13 - 9b$$

$$3b = 6m - 6$$

carried errors

$$14m = 13 - 9(2m - 2)$$

$$b = 2m - 2$$

$$14m = 13 - 18m + 18$$

$$28m = 5$$

$$m = 3.5 \dots$$

$$b = 3.5 - 1 = 2.5$$

$$y = 3.5x + 2.5$$

$$y = \frac{1}{2}x + 1$$

are kind fun
even

26-4 What linear equation in a, b, c does the method of least squares lead you to when you fit $z = a + bx + cy$ to (x_i, y_i, z_i) , $i=1 \dots n$

So are trying to fit a line to a lot of points

I guess some $\sum_{i=1}^n (mx_i + b - y_i)^2 = 0$

what is this??

$D = \sum (a + b x_i + c y_i - z_i)^2$ c w/ 3 variables
so equations are

$$\frac{\partial D}{\partial a} = \sum 2(a + b x_i + c y_i - z_i) = 0$$

$$\frac{\partial D}{\partial b} = \sum 2 x_i (a + b x_i + c y_i - z_i) = 0$$

$$\frac{\partial D}{\partial c} = \sum 2 y_i (a + b x_i + c y_i - z_i) = 0$$

2's cancel

like a matrix

$$\begin{aligned} n a + (\sum x_i) b + (\sum y_i) c &= \sum z_i \\ (\sum x_i) a + (\sum x_i^2) b + (\sum x_i y_i) c &= \sum x_i z_i \\ (\sum y_i) a + (\sum x_i y_i) b + (\sum y_i^2) c &= \sum y_i z_i \end{aligned}$$

would have never found this on own!

Lecture 13 Second Derivative Test, La Grange multipliers

2H-1a Find critical pts and tell if min or max

$$x^2 - xy - 2y^2 - 3x + 3y + 1 = W$$

So at critical pt when partial derivs each = 0

$$\frac{\partial}{\partial x} = 2x - y - 0 - 3 + 0 + 0 = 0$$

$$\frac{\partial}{\partial y} = 0 - x - 2 \cdot 2y - 0 + 3 + 0 = 0$$

$$2x - y - 3 = 0$$

$$2x - y = 3$$

$$y = -3 + 2x$$

$$-4y - x + 3 = 0$$

$$-4y - x = -3$$

$$x = 3 - 4y$$

$$x = 3 - 4(-3 + 2x)$$

$$x = 3 + 12 - 8x$$

$$x = 15 - 8x$$

$$9x = 15$$

$$x = \frac{5}{3}$$

$$y = -3 + 2\left(\frac{5}{3}\right) = \frac{1}{3}$$

$\left(\frac{5}{3}, \frac{1}{3}\right)$ is possibility

$$f_{xx} = A = \frac{\partial}{\partial x} (2x - y - 3)$$

$$= 2 - 0 - 0$$

$$= 2 \quad (\text{✓})$$

$$f_{xy} = B = \frac{\partial}{\partial x} (-4y - x + 3)$$

$$= 0 - 1 + 0$$

$$= -1 \quad (\text{✓})$$

$$f_{yy} = C = \frac{\partial}{\partial y} (-4y + x + 3)$$

$$= -4 - 0 + 0$$

$$= -4 \quad \text{Ⓢ}$$

$$AC - B^2$$

$$2 \cdot (-4) - (-1)^2$$

$$-8 - 1 = -9 \quad \ominus \text{ so saddle pt } \text{Ⓢ Correct!}$$

d. $x^3 - 3xy + y^3$

$$\frac{\partial}{\partial x} = 3x^2 - 3y + 0 \quad \frac{\partial}{\partial y} = 0 - 3x + 3y^2$$

$$3x^2 - 3y = 0$$

$$3x^2 = 3y$$

$$y = x^2$$

$$3y^2 - 3x = 0$$

$$3y^2 = 3x$$

$$x = y^2$$

don't
reel

$$x = (x^2)^2 = x^4$$

$$y = (x^4)^2 = x^8$$

calc solve

$$x = 0 \quad x = 1$$

$$y = (0)^2 = 0 \quad y = (1)^2 = 1$$

A) $f_{xx} = 6x$ B) $f_{xy} = 0 - 3 + 0$ C) $f_{yy} = 6y$

$$AC - B^2$$

$$6(0) \cdot 6(0) - (-3)^2$$

$$-3$$

⊖
Saddle
Ⓢ

$$6(1) \cdot 6(1) - (-3)^2$$

$$33 \quad \oplus$$

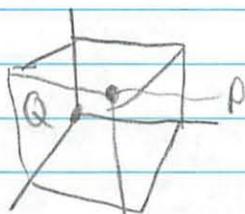
test $f_{xx} = 6(1) \quad \oplus$

↓ local min
Ⓢ

Lagrange

2I-1a

A rectangular box in first octant



$$f(x, y, z) = C$$

For what point P will
the box have the largest
Volume

$$\text{plane} = x + 2y + 3z = 18$$

$g(x, y, z)$ defines a surface

Solve system x, y, z, λ

$$C_x = 1 = \lambda y z$$

$$C_y = 2 = \lambda x z \quad g = 18$$

$$C_z = 3 = \lambda x y$$

don't forget!

$$x z = \lambda$$

$$x z = 2 \lambda$$

$$x y = 3 \lambda$$

$$\lambda x = 2 \lambda y = 3 \lambda z$$

$$x = 2y = 3z = \lambda$$

sum 18

$$x = 6$$

$$y = 3$$

$$z = 2$$

) max pt - since if P lies
on triangular boundary of the
region over the 1st octant
which it varies volume = 0

These topics
were presented
clearly

- so Lagrange is alt method we need to know

4a Drawers open top 2 Sides + back \$2/ft²
bottom \$1/ft² front \$4/ft²
Largest w/ \$72



$$72 = 2xy + 2 \cdot 2yz + 4xy + 1 \cdot xz$$
$$72 = xz + 6xy + 4yz$$

$$xyz = V$$

$$C_x = 2 + 6y + 0 = \lambda yz$$

$$C_y = 0 + 6x + 4z = \lambda xz$$

$$C_z = x + 0 + 4y = \lambda xy$$

$$C = 72$$

right

now solve for λ for each

$$\lambda = \frac{2+6y}{yz} = \lambda = \frac{6x+4z}{xz} = \lambda = \frac{x+4y}{xy}$$

they did not divide $x \cdot y + 6xz = xy + 4yz = 4yz + 6xz = 72$

$$\lambda = \frac{1}{y} + \frac{6}{z} = \frac{6}{z} + \frac{4}{x} = \frac{1}{y} + \frac{4}{x} = \lambda = 72$$

Solve

$$\frac{1}{y} - \frac{6}{z} = \frac{4}{x} = 72 = xy = 4yz = 6xz$$

$$\frac{24}{xy} = 72 \rightarrow 24 = xyz = 72$$

by hypothesis

$$xy = 24$$

$$x = 4z$$

$$yz = 6$$

$$y = 6z$$

$$xz = 4$$

I don't really
get what happened.

$$x = 4$$

$$y = 6$$

$$z = 1$$

ask about

for letters
may be
diff

Lecture 14 Chain Rule

2E-1b Find $\frac{df}{dt}$ for the composite function $f(x(t), y(t), z(t))$

$$w = x^2 - y^2 \quad x = \cos t \quad y = \sin t$$

- i) Use the chain rule, express ans in terms of t by using $x = x(t)$
- ii) express f in terms of t & differentiate

Sort out what we should do b/c he said a lot was theoretical

$$\begin{aligned} \text{i) } \frac{dw}{dt} &= \frac{\partial w}{\partial x} \frac{dx}{dt} + \frac{\partial w}{\partial y} \frac{dy}{dt} \\ &= 2x(-\sin t) - 2y(\cos t) \\ &\quad \begin{matrix} \uparrow & \uparrow \\ \text{deriv of} & \text{deriv of} \\ \text{function} & \text{what } x \text{ is} \end{matrix} \\ &= -4 \sin t \cos t \end{aligned}$$

simplify
(no x and y)
why/how?
* sub in values of
a point

↓ actually plug in

$$\begin{aligned} \text{ii) } w &= x^2 - y^2 = \cos^2 t - \sin^2 t \\ &= \cos 2t \end{aligned}$$

$$\begin{aligned} \frac{dw}{dt} &= -2 \sin 2t \\ &\quad \leftarrow \text{now differentiate} \end{aligned}$$

2c Function unknown $f(x, y)$
Gradient is given

$$\nabla f = \langle 1, -1, 2 \rangle \text{ at } (1, 1, 1)$$

$x=t \quad y=t^2 \quad z=t^3$

Find $\frac{df}{dt}$ at $t=1$

no clue
-like just
doing a pattern

Use chain rule to find additional info about
 $w = f(x(t), y(t))$ w/o finding f

$$t=1 \quad (x(1), y(1), z(1)) = (1, 1, 1)$$

$$\begin{aligned} \frac{df}{dt} \Big|_1 &= 1 \cdot \frac{dx}{dt} \Big|_1 - 1 \cdot \frac{dy}{dt} \Big|_1 + 2 \frac{dz}{dt} \Big|_1 \\ &= 1 \cdot 1 - 1 \cdot 2 + 2 \cdot 3 \\ &= 5 \end{aligned}$$

3b Using the chain rule for $f(u, v, w)$ derive
a similar product rule for $\frac{d}{dt}(uvw)$
and use it to differentiate $t e^{2t} \sin t$

~~have no clue~~

$$\frac{d(uvw)}{dt} = vw \frac{du}{dt} + uv \frac{dv}{dt} + uv \frac{dw}{dt}$$

$$e^{2t} \sin t + 2te^{2t} \sin t + te^{2t} \cos t$$

~~don't get all~~

Have more clue after recitation now

$$\begin{aligned} u &= t \\ v &= e^{2t} \\ w &= \sin t \end{aligned}$$

then just apply formula

and it will apply

6a. Let $w = f(x, y)$ change from rectangular \rightarrow polar coords
 $x = r \cos \theta$
 $y = r \sin \theta$

Show that $(w_x)^2 + (w_y)^2 = (w_r)^2 + \frac{1}{r^2} (w_\theta)^2$

well remember $r = \sqrt{x^2 + y^2}$
 $\theta = \tan^{-1} \left(\frac{y}{x} \right)$

But how to show?

①
$$\begin{aligned} w_r &= w_x x_r + w_y y_r \\ &= w_x \cos \theta + w_y \sin \theta \\ w_\theta &= w_x x_\theta + w_y y_\theta \\ &= w_x (-r \sin \theta) + w_y (r \cos \theta) \end{aligned}$$

②
$$\begin{aligned} \text{So } (w_r)^2 + \left(\frac{w_\theta}{r} \right)^2 &= (w_x)^2 (\cos^2 \theta + \sin^2 \theta) + (w_y)^2 (\sin^2 \theta + \cos^2 \theta) + \\ &\quad 2w_x w_y \cos \theta \sin \theta - 2w_x w_y \sin \theta \cos \theta \\ &= (w_x)^2 + (w_y)^2 \end{aligned}$$

Should
watch
Arrox

So what does that have to do w/ chain rule

- like what did in recitation
function of 2 sub function

- chain rule ①

- then plug it in and after lots of
algebra it ends up right ②

Put in matrix form the chain rule

Lecture $\vec{\nabla} f \cdot \text{vector}$
↑
Jacobian matrix

Oliver OH

$$\nabla f(x(u,v), y(u,v))$$

take gradient

$$\left\langle \frac{\partial}{\partial u}(\quad), \frac{\partial}{\partial v}(\quad) \right\rangle$$

then write in matrix form

$$\frac{\partial x}{\partial u} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial u} \frac{\partial f}{\partial y} = x_u f_x + y_u f_y$$

all 4 are partial derivs

$$\boxed{\begin{aligned} \frac{d}{dt} f(x(t), y(t)) \\ = x'_t f_x + y'_t f_y \quad x_t = x' \end{aligned}}$$

$$\langle x_u f_x + y_u f_y, x_v f_x + y_v f_y \rangle$$

Put in matrix form

$$\langle f_x, f_y \rangle \begin{bmatrix} x_u & y_u \\ x_v & y_v \end{bmatrix} \quad \text{translation}$$

7. Re Jacobian Matrix for change in variables

$$x = x(u, v)$$

$$y = y(u, v)$$

defined to be $J = \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix}$

Let $\nabla f(x, y)$ represent row vector $\langle f_x, f_y \rangle$

Show that $\nabla f(x(u, v), y(u, v)) = \nabla f(x, y) \cdot J$
matrix multiplication?

$$\frac{dw}{dt} = \vec{\nabla} w \cdot \frac{dr}{dt} = 0$$

gradient is perpendicular to tangent of curve

$$f_u = f_x x_u + f_y y_u$$

$$f_v = f_x x_v + f_y y_v$$

another
function
of something
else

$$\langle f_u, f_v \rangle = \langle f_x, f_y \rangle \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix}$$

$\frac{dr}{dt}$ r ? something

Wikipedia: Matrix of all 1st order partial derivs of vector function

$$J = \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \dots & \frac{\partial y_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial y_m}{\partial x_1} & \dots & \frac{\partial y_m}{\partial x_n} \end{bmatrix}$$

8a Let $w = f\left(\frac{y}{x}\right)$ i.e. w is composite $w = f(u)$ $u = \frac{y}{x}$

Show that w satisfies the partial differential equation

$$x \frac{\partial w}{\partial x} + y \frac{\partial w}{\partial y} = 0$$

Well isn't it

$$\frac{dw}{dt} = \frac{\partial w}{\partial x} \frac{dx}{dt} + \frac{\partial w}{\partial y} \frac{dy}{dt}$$

∴ so integrate

$$\int \frac{dw}{dt} = \frac{\partial w}{\partial x} \int \frac{dx}{dt} + \frac{\partial w}{\partial y} \int \frac{dy}{dt} \quad \text{* Never integrate like this}$$

$$w = \frac{\partial w}{\partial x} x + \frac{\partial w}{\partial y} y$$

∴ but how 0? and why is this interesting?

$$\begin{aligned} \frac{\partial w}{\partial x} &= f'(u) \cdot \frac{\partial u}{\partial x} \\ &= f'(u) \cdot \frac{-y}{x^2} \end{aligned} \quad \text{actually do it}$$

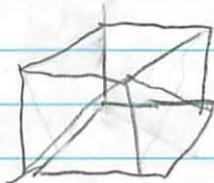
$$\begin{aligned} \frac{\partial w}{\partial y} &= f'(u) \cdot \frac{\partial u}{\partial y} \\ &= f'(u) \cdot \frac{1}{x} \end{aligned}$$

how does it change

$$\text{So it} = f'(u) \left(\frac{-y}{x} + f'(u) \frac{y}{x} \right) = 0$$

∴ how does it change

Part 2 1. Place cube of length 1



Find the length & position of shortest line segment joining them

a) Write parametric equations for 2 diagonals $+$ and $-$

- \therefore But can't I write regular equations?

And don't the lines touch? so is no 2 lines between the 2 lines, or do they want the 2 given pts

but in general $D = \sqrt{x^2 + y^2 + z^2}$
but $D^2 = x^2 + y^2 + z^2$ & easier

OH



Do as optimisation problem - did it before

retry afterwards

write as parameter

So from before $\vec{P}_1 \vec{P}_2 = \langle 0, 1, 1 \rangle$ ✓

$\vec{Q}_1 \vec{Q}_2 = \langle -1, 0, 1 \rangle$ ✓

and then find perp to find line

but this needs parametrizing

Jay
(last semester)
student

$$\langle 1, 0, 0 \rangle + t \langle 0, 1, 1 \rangle$$

so in t seconds it will have moved

$$\langle 0, t, t \rangle$$

$$\langle 1, 1, 0 \rangle + u \langle -1, 0, 1 \rangle$$

how did I overlap mistake so often!

$$\rightarrow \sqrt{\text{So } d = \sqrt{(1+0t - (1+t))}^2 + (0+t - (1-0u))^2 + \dots}$$

on own

*remember
 $(a+b)^2 \neq a^2 + b^2$

$$d = \sqrt{(1+0t - (1+t))}^2 + (0+t - (1-0u))^2 + \dots$$

$$d = \sqrt{0^2 + t^2 - 2t + 1 + t^2 - 2ut + u^2}$$

$$v(t, u) = d^2 = 2t^2 - 2ut + 2u^2 - 2t + 1$$

What is the constraint?

-0.5

~~1~~

$$\begin{cases} t_0 = \langle 0, t, t \rangle \\ u_0 = \langle 0, -u, u \rangle \end{cases}$$

you use the right parameters above, but give the wrong ones here! are these constraints?

be more careful!

key Note this is a thr problem - not a chain rule!

$$\frac{\partial}{\partial t} = 4t - 2u + 0 - 2 + 0$$

$$\frac{\partial}{\partial u} = 0 - 2t + 4u - 0 + 0$$

$$4t - 2u - 2 = 0$$

$$4u - 2t = 0$$

$$t = \frac{2u+2}{4} = \frac{u+1}{2}$$

$$u = \frac{2t}{4} = \frac{1}{2}t$$

plug 1 into other

$$x = \frac{\left(\frac{1}{2}x\right) + 1}{2}$$

$$x = \frac{1}{4}x + \frac{1}{2}$$

$$x = \frac{2}{3}$$

$$u = \frac{1}{2}x = \frac{1}{3}$$

at pt

$$\langle 1, 0, 0 \rangle + \frac{2}{3} \langle 0, 1, 1 \rangle$$

pts $\langle 1, \frac{2}{3}, \frac{2}{3} \rangle$

$$\langle 1, 1, 0 \rangle + \frac{1}{3} \langle -1, 0, 1 \rangle$$

pts $\langle \frac{2}{3}, 1, \frac{1}{3} \rangle$

$$D = \sqrt{2\left(\frac{2}{3}\right)^2 - 2\left(\frac{2}{3}\right)\left(\frac{1}{3}\right) + 2\left(\frac{1}{3}\right)^2 - 2\left(\frac{2}{3}\right) + 1}$$

$$D = \sqrt{\frac{1}{3}}$$

$$D = \frac{\sqrt{3}}{3} \quad \checkmark$$

$$\text{Dir } \langle 1 - \frac{2}{3}, \frac{2}{3} - 1, \frac{2}{3} - \frac{1}{3} \rangle$$

$$\langle \frac{1}{3}, -\frac{1}{3}, \frac{1}{3} \rangle$$

I hope this is it - if it is I am
glad I cracked this one

- Be able to know what problems need what

2. Uses MatLab, but before: (read Least Square Interpolation notes)

a) Let $\vec{x} = [x_1, x_2, \dots, x_n]$
 $\vec{y} = [y_1, y_2, \dots, y_n]$
 $\vec{1} = [1, 1, 1, \dots, 1]$

$Y = aX + b$ is best fit line through n points (x_i, y_i)

Translate $(\sum x_i) a + nb = \sum y_i$
into a single 2×2 matrix $Az = r$
 $z = [a, b]^T$

Write entries of A and r in terms of $\hat{x}, \hat{y}, \hat{1}$
(use dot products not sum signs)
 $\sum x_i = \hat{x} \cdot \hat{1}$

$A = \hat{x} \cdot \hat{1}' (a + nb) = \hat{y} \cdot \hat{1}'$ ← transpose
 $\hat{x} (a \hat{1}' + nb \hat{1}' \hat{1}') = \hat{y} \hat{1}'$

$\hat{1}' = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$

$A = [a, b]' = \begin{bmatrix} x \\ y \end{bmatrix}$

$\begin{pmatrix} x & x \\ y & y \end{pmatrix}$

or jacobian

$\begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \dots & \frac{\partial y_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial y_m}{\partial x_1} & \dots & \frac{\partial y_m}{\partial x_n} \end{bmatrix}$

base thinking off lecture notes

have 2 eq w/ 2 unknowns a, b
write as matrix

* equation 4

are 2 separate things ~~if~~

$$\left(\sum x_i^2 \right) a + \left(\sum x_i \right) b = \sum x_i y_i$$

$$\left(\sum x_i \right) a + nb = \sum y_i$$

$$\begin{bmatrix} \sum (x_i)^2 & \sum x_i \\ \sum x_i & n \end{bmatrix} \cdot \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \sum x_i y_i \\ \sum y_i \end{bmatrix}$$

A Z \vec{r}

$$\begin{bmatrix} x \cdot x' & x \cdot 1' \\ x \cdot 1' & n \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} x \cdot y' \\ y \cdot 1' \end{bmatrix}$$

makes more sense now

At computer

Cost of post stamp for 1 oz envelope is given on chart

b) Use Matlab to make a scatter plot
(see page 117)

c) Enter A and r
- but what is n?
↳ # of columns 2

Plot $Y = aX + b$
 $t = [0; 1; 45]$
plot a, t, b

* # of row in first = # columns in second

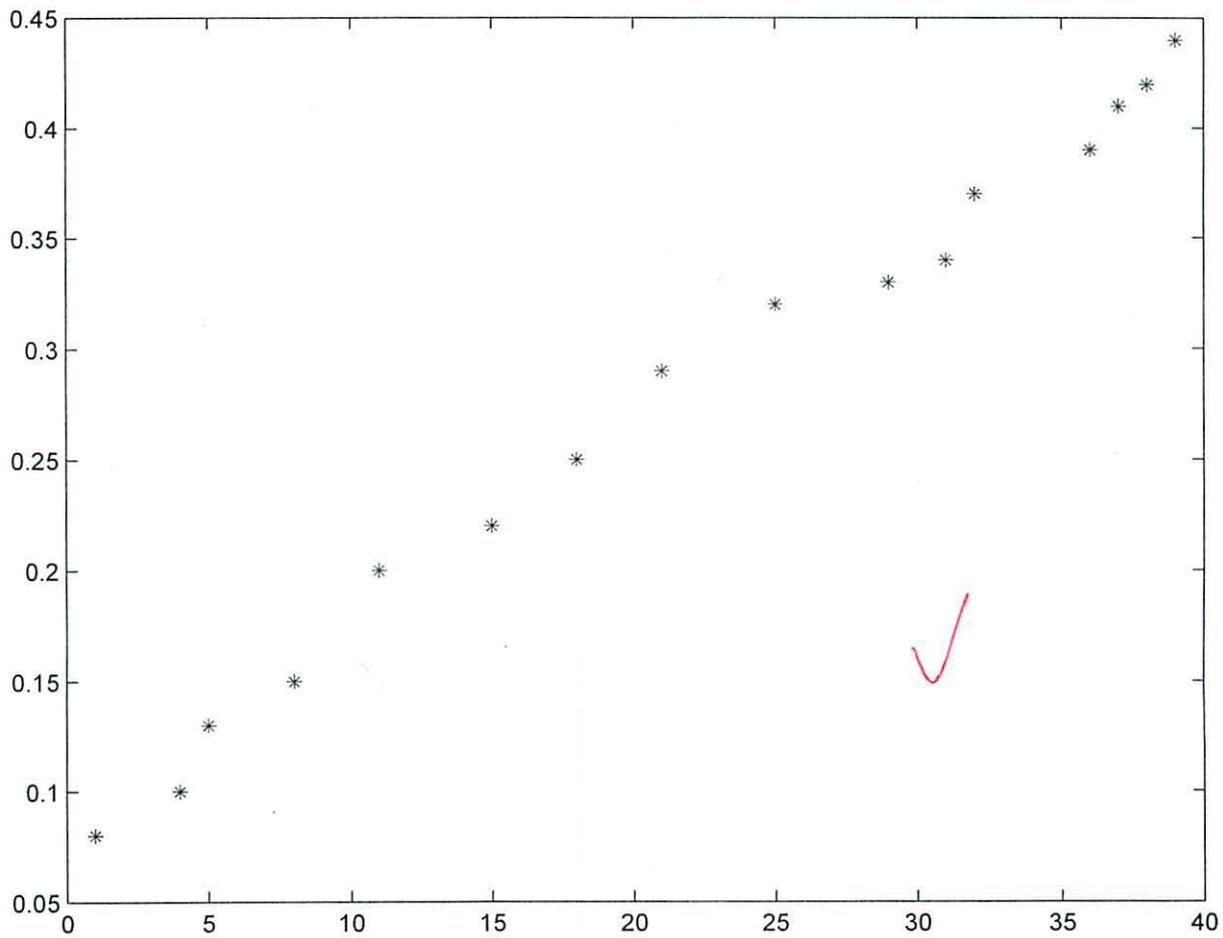
* Recalculate a and b using above

* n is # of points = 16 (not 39)

* must enter $i = []$ or it will calculate

Still won't calculate, I give up, spent 30 min

(-3)



```
>> a=[1 4 5 8 11 15 18 21 25 29 31 32 36 37 38 39];
>> b=[.08 .1 .13 .15 .20 .22 .25 .29 .32 .33 .34 .37 .39 .41 .42 .44];
>> plot(x,y)
???: Undefined function or variable 'x'.
```

*Could not get
what did I do
wrong?*

```
>> plot(a,b)
>> plot(a,b,'*')
???: plot(a,b,'*')
|
Error: A MATLAB string constant is not terminated properly.
```

```
>> plot(a,b,'*')
>> A=[x*x' x*i' x*i' n]
???: Undefined function or variable 'x'.
```

```
>> x=a
```

```
x =
    1     4     5     8    11    15    18    21    25    29    31    32    36    37    38 39
```

```
>> y=b
```

```
y =
Columns 1 through 11
    0.0800    0.1000    0.1300    0.1500    0.2000    0.2200    0.2500    0.2900    0.3200 0.3300 0.3400
```

```
Columns 12 through 16
```

```
    0.3700    0.3900    0.4100    0.4200    0.4400
```

```
>> A=[x*x' x*i' x*i' n]
???: Undefined function or variable 'n'.
```

```
>> A=[x*x' x*i' x*i' 2]
```

```
A =
1.0e+004 *
Columns 1 through 6
    1.0298           0 - 0.0001i           0 - 0.0004i           0 - 0.0005i           0 - 0.0008i
0.0008i           0 - 0.0011i
Columns 7 through 12
    0 - 0.0015i           0 - 0.0018i           0 - 0.0021i           0 - 0.0025i           0 - 0.0028i
```

```
0.0029i      0 - 0.0031i
```

```
Columns 13 through 18
```

```
      0 - 0.0032i      0 - 0.0036i      0 - 0.0037i      0 - 0.0038i      0 - 0.0039i
0.0039i      0 - 0.0001i
```

```
Columns 19 through 24
```

```
      0 - 0.0004i      0 - 0.0005i      0 - 0.0008i      0 - 0.0011i      0 - 0.0015i
0.0015i      0 - 0.0018i
```

```
Columns 25 through 30
```

```
      0 - 0.0021i      0 - 0.0025i      0 - 0.0029i      0 - 0.0031i      0 - 0.0032i
0.0032i      0 - 0.0036i
```

```
Columns 31 through 34
```

```
      0 - 0.0037i      0 - 0.0038i      0 - 0.0039i      0.0002
```

```
>> r=[x*y' y*i']
```

```
r =
```

```
1.0e+002 *
```

```
Columns 1 through 5
```

```
      1.2070      0 - 0.0008i      0 - 0.0010i      0 - 0.0013i      0 - 0.0015i
0.0015i
```

```
Columns 6 through 10
```

```
      0 - 0.0020i      0 - 0.0022i      0 - 0.0025i      0 - 0.0029i      0 - 0.0032i
0.0032i
```

```
Columns 11 through 15
```

```
      0 - 0.0033i      0 - 0.0034i      0 - 0.0037i      0 - 0.0039i      0 - 0.0041i
0.0041i
```

```
Columns 16 through 17
```

```
      0 - 0.0042i      0 - 0.0044i
```

```
>> hold
```

```
Current plot held
```

```
>> t=[0:1:45]
```

```
t =
```

Columns 1 through 18

```
    0    1    2    3    4    5    6    7    8    9    10    11    12    13    14 ✓  
15    16    17
```

Columns 19 through 36

```
    18    19    20    21    22    23    24    25    26    27    28    29    30    31    32 ✓  
33    34    35
```

Columns 37 through 46

```
    36    37    38    39    40    41    42    43    44    45
```

```
>> plot (a*t+b)  
??? Error using ==> mtimes  
Inner matrix dimensions must agree.
```

```
>> plot(a*t+b)  
??? Error using ==> mtimes  
Inner matrix dimensions must agree.
```

```
>> a*b  
??? Error using ==> mtimes  
Inner matrix dimensions must agree.
```

```
>> a*t  
??? Error using ==> mtimes  
Inner matrix dimensions must agree.
```

```
>> a.*t  
??? Error using ==> times  
Matrix dimensions must agree.
```

```
>> a.*t.  
??? a.*t.
```

```
Error: Expression or statement is incomplete or incorrect.
```

```
>> A*t  
??? Error using ==> mtimes  
Inner matrix dimensions must agree.
```

```
>> a.*t  
??? Error using ==> times  
Matrix dimensions must agree.
```

```
>> a
```

```
a =
```

```
    1    4    5    8    11    15    18    21    25    29    31    32    36    37    38 ✓
```

39

```
>> a = [1      4      5      8      11     15     18     21     25     29     31     32     36     37
38      39 45]
```

a =

```
      1      4      5      8      11     15     18     21     25     29     31     32     36     37     38
39      45
```

```
>> a.*t
```

```
??? Error using ==> times
Matrix dimensions must agree.
```

```
>> A.*r
```

```
??? Error using ==> times
Matrix dimensions must agree.
```

```
>> A=[x*x' x*i' x*i' 2]
```

A =

1.0e+004 *

Columns 1 through 5

```
      1.0298          0 - 0.0001i          0 - 0.0004i          0 - 0.0005i          0 -
0.0008i
```

Columns 6 through 10

```
          0 - 0.0011i          0 - 0.0015i          0 - 0.0018i          0 - 0.0021i          0 -
0.0025i
```

Columns 11 through 15

```
          0 - 0.0029i          0 - 0.0031i          0 - 0.0032i          0 - 0.0036i          0 -
0.0037i
```

Columns 16 through 20

```
          0 - 0.0038i          0 - 0.0039i          0 - 0.0001i          0 - 0.0004i          0 -
0.0005i
```

Columns 21 through 25

```
          0 - 0.0008i          0 - 0.0011i          0 - 0.0015i          0 - 0.0018i          0 -
0.0021i
```

Columns 26 through 30

```
          0 - 0.0025i          0 - 0.0029i          0 - 0.0031i          0 - 0.0032i          0 -
```

```
0.0036i
```

```
Columns 31 through 34
```

```
0 - 0.0037i    0 - 0.0038i    0 - 0.0039i    0.0002
```

```
>> r=[x*y' y*i']
```

```
r =
```

```
1.0e+002 *
```

```
Columns 1 through 5
```

```
1.2070    0 - 0.0008i    0 - 0.0010i    0 - 0.0013i    0 - 0.0015i
```

```
Columns 6 through 10
```

```
0 - 0.0020i    0 - 0.0022i    0 - 0.0025i    0 - 0.0029i    0 - 0.0032i
```

```
Columns 11 through 15
```

```
0 - 0.0033i    0 - 0.0034i    0 - 0.0037i    0 - 0.0039i    0 - 0.0041i
```

```
Columns 16 through 17
```

```
0 - 0.0042i    0 - 0.0044i
```

```
>> A.*[a b]
```

```
??? Error using ==> times  
Matrix dimensions must agree.
```

```
>> A.*[a b]'
```

```
??? Error using ==> times  
Matrix dimensions must agree.
```

```
>> A
```

```
A =
```

```
1.0e+004 *
```

```
Columns 1 through 5
```

```
1.0298    0 - 0.0001i    0 - 0.0004i    0 - 0.0005i    0 - 0.0008i
```

```
Columns 6 through 10
```

0 - 0.0011i	0 - 0.0015i	0 - 0.0018i	0 - 0.0021i	0 - κ
0.0025i				

Columns 11 through 15

0 - 0.0029i	0 - 0.0031i	0 - 0.0032i	0 - 0.0036i	0 - κ
0.0037i				

Columns 16 through 20

0 - 0.0038i	0 - 0.0039i	0 - 0.0001i	0 - 0.0004i	0 - κ
0.0005i				

Columns 21 through 25

0 - 0.0008i	0 - 0.0011i	0 - 0.0015i	0 - 0.0018i	0 - κ
0.0021i				

Columns 26 through 30

0 - 0.0025i	0 - 0.0029i	0 - 0.0031i	0 - 0.0032i	0 - κ
0.0036i				

Columns 31 through 34

0 - 0.0037i	0 - 0.0038i	0 - 0.0039i	0.0002	
-------------	-------------	-------------	--------	--

>> A=[x*x' x*i' x*i' 2]

A =

1.0e+004 *

Columns 1 through 5

1.0298	0 - 0.0001i	0 - 0.0004i	0 - 0.0005i	0 - κ
0.0008i				

Columns 6 through 10

0 - 0.0011i	0 - 0.0015i	0 - 0.0018i	0 - 0.0021i	0 - κ
0.0025i				

Columns 11 through 15

0 - 0.0029i	0 - 0.0031i	0 - 0.0032i	0 - 0.0036i	0 - κ
0.0037i				

Columns 16 through 20

0 - 0.0038i	0 - 0.0039i	0 - 0.0001i	0 - 0.0004i	0 - κ
0.0005i				


```
??? Error using ==> mtimes
Inner matrix dimensions must agree.
```

```
>> n=16
```

```
n =
```

```
16
```

```
>> i=[1 1 1 1 1 1 1 1 1 1 1 1 1 1 1]
```

```
i =
```

```
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
```

```
>> A=[x*x' x*i' x*i' n]
```

```
??? Error using ==> mtimes
Inner matrix dimensions must agree.
```

```
>>
```

3. Verify using 2nd deriv test that the critical pt from Problem 1 is actually a min for $w(t,u)$

The point was
 $w\left(\frac{2}{3}, \frac{1}{3}\right)$

So basically do $AC - B^2$

$A = w_{tt}$	$B = w_{tu}$	$C = w_{uu}$
4 - 0 - 0	0 - 2 - 0	-0 + 4 - 0
4 ✓	-2 ✓	4 ✓

$$4 \cdot 4 - (-2)^2$$

⊕

↓

A is ⊕ so min ⊙ ✓

That was
easy
- memorize
steps
* know when
to use what

3b Do 2H2 → Use 2nd deriv criteria to verify (m_0, b_0) which is least sq of $y = m_0 x + b_0$ to minimize $D(m, b)$

Office hrs

Will need inequality $A = \langle a_1, a_2, \dots, a_n \rangle$

define $|A| = \sqrt{\sum a_i^2}$ $A \cdot B = \sum a_i b_i$

$$\sum_{i=1}^m (y_i - m_0 x_i - b_0)^2 = f(m_0, b_0)$$

- take deriv

- 0 for certain values

- 2nd deriv tells min

$$(f+g)' = f' + g'$$

$f_{m_0} = \sum_{i=1}^m 2(-x_i)(y_i - m_0 x_i - b_0)$ *or same sum sign deriv each part*

$$f_{b_0} = \sum 2(y_i - m_0 x_i - b_0)$$

$$f_{m_0 m_0} = -2 \sum_{i=1}^m (-x_i)^2 \checkmark$$

$$f_{m_0 b_0} = 2 \sum x_i \checkmark$$

$$f_{b_0 b_0} = 2 \sum 1 = 2n \checkmark$$

$$AC - B^2 = 4/n \sum (x_i)^2 - 4 \left(\sum_{i=1}^n x_i \right)^2 \checkmark$$

known $\left(\sum v_i v_i \right)^2 \leq \left(\sum v_i^2 \right) \left(\sum v_i^2 \right)$

Want to prove $\left(\sum x_i \right)^2 \leq n \sum x_i^2$

- find right v_i and v_j

$$\sum 1 \sum x_i^2 \quad v_i = 1 \quad v_j = x_i$$

So it will be \oplus

Now look at ΔC - raiser
 $2n$ is \oplus so minimum

4. A surface is $f(x, y, z) = c$ which is level surface for $f(x, y, z)$

γ A

Let $A = (a, b, c)$ not on surface
Want $P_0(x_0, y_0, z_0)$ is on surface closest to A

Minimize the square of distance $w(x, y, z) = |AP|^2$

The 1st qv
in recitation 3/10

Solve w/ Lagrange

C are not the same

$$w = x^2 + y^2 + z^2 \\ = (a - x_0)^2 + (b - y_0)^2 + (c - z_0)^2 \quad \checkmark$$

constraint $g = x_0 + y_0 + z_0 - c = 0$ on surface

$$w_{x_0} = dg_x = 2(a - x_0) \cdot -1 = \lambda \\ w_{y_0} = dg_y = 2(b - y_0) \cdot -1 = \lambda \quad \checkmark \\ w_{z_0} = dg_z = 2(c - z_0) \cdot -1 = \lambda \\ x_0 + y_0 + z_0 - c = 0$$

(where
did go
wrong?)

$$-2a + 2x_0 = -2b + 2y_0 = -2c + 2z_0 = \lambda \quad \text{Don't have to solve}$$
$$-a + x_0 = -b + y_0 = -c + z_0 = \frac{\lambda}{2}$$

solve for x, y, z

$$-a + x_0 = \frac{\lambda}{2} \quad -b + y_0 = \frac{\lambda}{2} \quad -c + z_0 = \frac{\lambda}{2}$$

$$x_0 = \frac{\lambda}{2} + a \quad y_0 = \frac{\lambda}{2} + b \quad z_0 = \frac{\lambda}{2} + c$$

solve for λ by plugging in constraint eq

$$x_0 + y_0 + z_0 - c = 0 \\ \frac{\lambda}{2} + a + \frac{\lambda}{2} + b + \frac{\lambda}{2} + c - c = 0$$

Now what?

$$\frac{3\lambda}{2} + a + b = 0$$

$$3\lambda + 2a + 2b = 0$$

$$\lambda = \frac{-2a - 2b}{3}$$

Now plug λ back in

$$x_0 = \frac{(-2a - 2b)}{3} + a \quad y_0 = \frac{(-2a - 2b)}{3} + b \quad z_0 = \frac{(-2a - 2b)}{3} + c$$

That can't be right!

Or were not suppose to actually find?

b) Show can that minimizing line AP_0 is \perp to surface

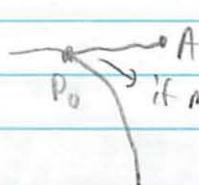
well that is the fastest way to something



P_0 will be on edge of surface as close as possible to A. This means that the line will make a line perpendicular to the tangent line at that surface at that point.

not quite \odot

Anti example



if moves line will get shorter

$$\nabla f = \langle f_x, f_y, f_z \rangle$$

$$J \cdot \Delta f = \langle h_x, h_y, h_z \rangle \text{ parallel}$$

Δf (vector)

$$\frac{dw}{dt} = \nabla w \cdot \frac{dr}{dt}$$

$$\text{dot product} = 0$$

always perp to surface

5. Let $x = v \cos \phi - v \sin \phi$
 $y = v \sin \phi + v \cos \phi$

a. Write this variable change in matrix form $\langle x, y \rangle = \langle u, v \rangle M$

Like the part A question on Jacobian Matrix
 or from lecture $\vec{w} = \frac{d\vec{r}}{dt}$

or a constant way to adjust matrix values

Remember

$$\begin{bmatrix} x \\ y \end{bmatrix} = [v, v] \cdot \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix} \quad \checkmark$$

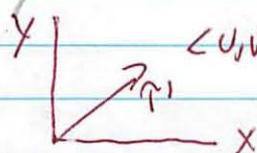
? is this right?

b. The vectors $\hat{i}' = \langle 1, 0 \rangle$ in uv coords correspond
 $\hat{j}' = \langle 0, 1 \rangle$
 to what in xy coords? Calc + draw.

$$\begin{bmatrix} x \\ y \end{bmatrix} = [1, 0] \cdot \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix}$$

$$x = \cos \phi$$

$$y = \sin \phi$$



parametric

$$\langle u, v \rangle = \langle 1, 0 \rangle = \hat{i}'$$

$$\langle x, y \rangle = \langle \cos \phi, \sin \phi \rangle$$

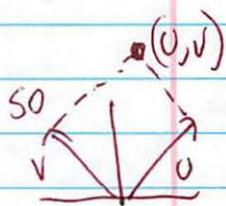
$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \checkmark$$

$$x = -\sin\theta$$

$$y = \cos\theta$$



will be perpendicular to other one



c As part b suggests the uv axis are just xy axis rotated by θ , Show using chain rule does not change length of ∇

Yeah if just rotating total length does not change

Alka For any differentiable function $w(x, y)$ calculate $\nabla w(x, y)$ in xy coords or calc $\nabla w(x(u, v), y(u, v))$ in uv coords - get the same value for length squared of ∇w at every pt P

$$(w_u)^2 + (w_v)^2 = (w_x)^2 + (w_y)^2 \leftarrow \text{as in the same}$$

- One of these change variable comparisons 3/10 ~~#3~~ #3
 \leftarrow only 1-variable

$$\frac{d}{dx} w(x(u, v), y(u, v))$$

$$w_u = w_x \frac{\partial x}{\partial u} + w_y \frac{\partial y}{\partial u}$$

$$w_v = w_x \frac{\partial x}{\partial v} + w_y \frac{\partial y}{\partial v}$$

$$W_u = \cos \theta w_x + \sin \theta w_y \quad w_v = -\sin \theta w_x + \cos \theta w_y$$

Now plug it in

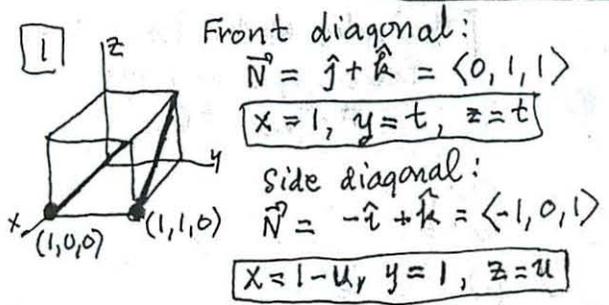
$$\begin{aligned} (w_u)^2 + (w_v)^2 &= (\cos \theta w_x + \sin \theta w_y)^2 + (-\sin \theta w_x + \cos \theta w_y)^2 \\ &= (\cos^2 \theta + \sin^2 \theta) w_x^2 + (\cos^2 \theta + \sin^2 \theta) w_y^2 \\ &= w_x^2 + w_y^2 \quad \checkmark \end{aligned}$$

☺ I did it!

↓ well done :)

oh cool - that's
how it works

18.02 Prob Set 4 Solus - Spring 2010



$W = |\vec{AB}|^2$ A = pt on front diagonal
 B = pt on side diagonal

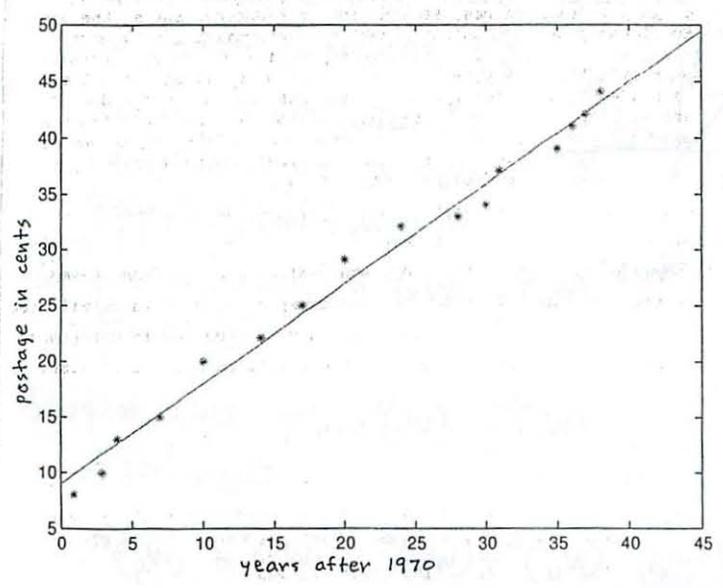
$W = (-u)^2 + (1-t)^2 + (u-t)^2$ to be minimized

Find crit pts:
 $W_u = 2u + 2(u-t) = 4u - 2t = 0$
 $W_t = -2(1-t) - 2(u-t) = -2 + 4t - 2u = 0$

Solving, $\begin{cases} 2u - t = 0 \\ 2t - u = 1 \end{cases} \Rightarrow t_0 = 2/3, u_0 = 1/3$
 so $A_0 = (1, 2/3, 2/3)$
 $B_0 = (2/3, 1, 1/3)$
 min. distance is $|\vec{A}_0 \vec{B}_0| = \sqrt{(-1/3)^2 + (1/3)^2 + (1/3)^2} = \frac{\sqrt{3}}{3}$

2 a) Data vectors: $\vec{x} = \langle x_1, x_2, \dots, x_{16} \rangle$
 $x_i = \text{years after 1970}$
 $\vec{y} = \langle y_1, \dots, y_{16} \rangle$
 $y_i = \text{postage in } \phi$
 $\vec{i} = \langle 1, 1, \dots, 1 \rangle$
 16 1's
 $A = \begin{bmatrix} \vec{x} \cdot \vec{x} & \vec{x} \cdot \vec{i} \\ \vec{x} \cdot \vec{i} & 16 \end{bmatrix}$ $\vec{r} = \begin{bmatrix} \vec{x} \cdot \vec{y} \\ \vec{y} \cdot \vec{i} \end{bmatrix}$

(b, c) the line is $y = .8988t + 8.9312$
 d) when $t = 43$ ($= 2013$), $y = .48$ (.4758)



3 a) Using the expressions for $\frac{\partial w}{\partial u}$ and $\frac{\partial w}{\partial t}$ in Problem 1 we get
 $A = W_{uu} = 4$ $AC - B^2 = 12 > 0$
 $B = W_{ut} = -2$ $A = 4 > 0$
 $C = W_{tt} = 4$
 \therefore the point $(u, t) = (1/3, 2/3)$ is a minimum for W .

b) Let $D = \sum (mx_i + b - y_i)^2$, to be minimized. Then we calculate
 $A = D_{mm} = 2 \sum x_i^2$
 $B = D_{mb} = 2 \sum x_i$
 $C = D_{bb} = 2 \sum 1 = 2n$
 Thus: $AC - B^2 = 4n \sum x_i^2 - 4(\sum x_i)^2$
 This is > 0 , i.e., $(\sum x_i)^2 < n \cdot \sum x_i^2$
 ($= 0$ if all x_i equal) not the case here

This follows from the Cauchy-Schwarz inequality for any 2 vectors \vec{A}, \vec{B} in n -space: $|\vec{A} \cdot \vec{B}| \leq |\vec{A}| |\vec{B}|$
 in 2D+3D, it says: $|\cos \theta| \leq 1$
 $\theta = \text{angle between } \vec{A} \text{ and } \vec{B}$
 using: $\vec{A} = \langle x_1, \dots, x_n \rangle$
 $\vec{B} = \langle 1, \dots, 1 \rangle$

\otimes says $(\frac{\sum x_i}{n})^2 \leq \frac{\sum x_i^2}{n}$
 "square of the average of n numbers \leq average of the squares"

4) a) The surface S is $f(x, y, z) = c$ (*)

and $A: (a, b, c)$ is given

$P: (x, y, z)$ is a point on the surface.

We want to minimize

$$|AP|^2 = (x-a)^2 + (y-b)^2 + (z-c)^2 = w(x, y, z),$$

subject to the constraint (*).

The Lagrange multiplier equations are:

$$2(x-a) = \lambda f_x$$

$$2(y-b) = \lambda f_y$$

$$2(z-c) = \lambda f_z$$

$$f(x, y, z) = c$$

b) If $P_0: (x_0, y_0, z_0)$ and λ_0 are a solution to the above equations,

then P_0 lies on the surface S

$$\text{since } f(x_0, y_0, z_0) = c$$

$$\text{and } \vec{AP}_0 = \frac{\lambda_0}{2} (\vec{\nabla} f)_0 \quad \text{(this is the 3 eqns on the left above)}$$

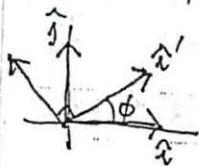
Since $(\vec{\nabla} f)_0$ is normal to the surface S at P_0 , and \vec{AP}_0 is a non-zero scalar multiple of $(\vec{\nabla} f)_0$ (non-zero since A is not on the surface),

\vec{AP}_0 is normal to S at P_0 .

5) a) $(x, y) = (u, v) \begin{pmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{pmatrix}$

b) $\hat{x}' = (1, 0)M = (\cos \phi, \sin \phi)$

$\hat{y}' = (0, 1)M = (-\sin \phi, \cos \phi)$



c) Using the chain rule,

$$w_u = w_x \cos \phi + w_y \sin \phi$$

$$w_v = w_x (-\sin \phi) + w_y \cos \phi$$

thus: $(w_u)^2 = (w_x)^2 \cos^2 \phi + 2w_x w_y \cos \phi \sin \phi + (w_y)^2 \sin^2 \phi$

$$(w_v)^2 = (w_x)^2 \sin^2 \phi - 2w_x w_y \cos \phi \sin \phi + (w_y)^2 \cos^2 \phi$$

Adding, $(w_u)^2 + (w_v)^2 = (w_x)^2 + (w_y)^2$.

Lecture 15

Chain Rule for non-independent variables

3/11

$$w = w(x, y, z) \quad \frac{\partial w}{\partial x}$$

To calc $\frac{\partial w}{\partial x}$ when x, y, z are constrained
 $g(x, y, z) = 0$

Why is this a problem?

- will use specific formulas
- but in real life are hard to find

$$w = x^2 + y^2 + z^2$$

$$1 = x + y + z \quad \text{constraint}$$

Problem $\frac{\partial w}{\partial y}$

1. Substitute z in to remove it

$$z = 1 - x - y$$

$$w = x^2 + y^2 + (1 - x - y)^2$$

$$\frac{\partial w}{\partial y} = 0 + 2y + 2(1 - x - y) \cdot -1$$

$$= -2x + 2y - 2y$$

$$\text{or } = 2y - 2x$$

$$\text{at } P_0 = -2$$

Or can eliminate x instead

- by symmetry change z to x

$$\frac{\partial w}{\partial y} = 2y - 2x$$

$$\text{at } P_0 = 0$$

Now use chain rule mechanically

$$\left(\frac{\partial W}{\partial Y}\right)_X = \frac{\partial W}{\partial V}$$

↳ don't have to hold v constant

u and v are independent variables

Calc w/ chain rule like before

could do
confusing

$$\frac{\partial W}{\partial V} = \frac{\partial W}{\partial X} + \frac{\partial W}{\partial V} + \dots$$

↳ but what does this mean?

Convention
for constrained variables

$\frac{\partial W}{\partial X}$ w/ x = take partial deriv as if
no constraint

$\left(\frac{\partial W}{\partial X}\right)$ = then it is constrained
- before in 18.02 everything unconstrained
but wrote in $()$ anyway

$$\frac{\partial W}{\partial V} = \frac{\partial W}{\partial X} \cdot \frac{\partial X}{\partial V} + \frac{\partial W}{\partial Y} \cdot \frac{\partial Y}{\partial V} + \frac{\partial W}{\partial Z} \cdot \frac{\partial Z}{\partial V}$$

↳ plain old chain rule, all independent
so no parenthesis needed

= 0 since

X is not a function of $V \rightarrow u$ and v are independent

$$\frac{\partial w}{\partial v} = 0 + \frac{\partial w}{\partial y} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial v}$$

new var
rename it
back $\left(\frac{\partial z}{\partial y}\right)_x$ must tell what ind variables are

$$\left(\frac{\partial w}{\partial y}\right)_x = 0 + w_y + w_z \left(\frac{\partial z}{\partial y}\right)_x$$

In the example = $2y + 2z (-1)$

↑ comes out to same answer

Have to get use to it → clumsy

- done same but forget v and v

$$\left(\frac{\partial w}{\partial y}\right)_x = \frac{\partial w}{\partial x} \frac{\partial x}{\partial y} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial y} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial y}$$

↑
0 are
both independent variables

↑
need ()
or else
ambiguous

Examples in course notes

Differentials (bare minimum)

$$w = w(x, y, z)$$

$$dw = w_x dx + w_y dy + w_z dz$$

↑ differential of w

total differential of w

Rules

1. You can add them
Multiply by a scalar function
Substitute (v -substitution)

$$2. dw = f(x, y) dx + g(x, y) dy$$

if x and y are independent variables

$$\hookrightarrow f(x, y) = \frac{\partial w}{\partial x}$$

$$g(x, y) = \frac{\partial w}{\partial y}$$

$$w = x^2 + y^2 + z^2 \quad \text{constraint } x + y + z = 1$$
$$dw = 2x dx + 2y dy + 2z dz$$

$$\text{want } \left(\frac{\partial w}{\partial y} \right)_x$$

↑ must eliminate term
use constraint

$x +$

$$dx + dy + dz = 0 + 0 + 0$$

$$\text{so } dz = -dx - dy$$

$$dw = (2x - 2z) dx + (2y - 2z) dy$$

↑
expressed dw in terms of dx and dy

$$\left(\frac{\partial w}{\partial x} \right)_y$$

$$\left(\frac{\partial w}{\partial y} \right)_x$$

Cyclic Rule

$$g(x, y, z) = 0$$

Independent on the 2 others
which one?

$$\left(\frac{\partial x}{\partial y}\right)_z \left(\frac{\partial y}{\partial z}\right)_x \left(\frac{\partial z}{\partial x}\right)_y$$

3 partial derivs
each calculated differently

they cancel (Lagrange's notation)

-

Why -? you don't want to know

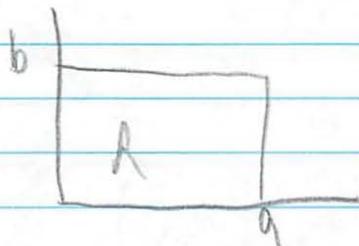
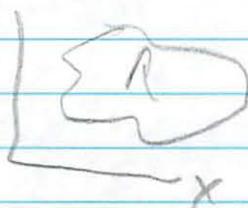
Lecture 16

Double + Iterated Integrals in Rect Coordinates 3/17

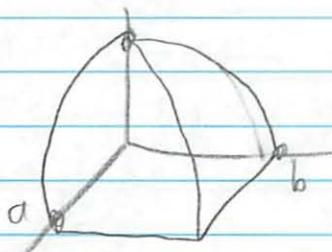
$$\iint dy dx$$

$$w = f(x, y) > 0$$

Volume under the graph
over the region y



Uses nothing
we learned
this semester



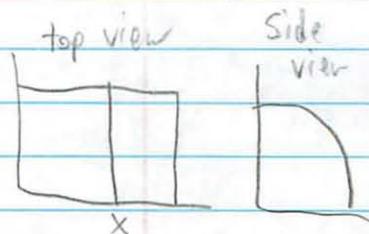
by slicing

18:01 Slices by geometry
- circles
- rectangles

Here by integral



← slice at pt x





Volume under graph = $\int_0^a A(x)$

Area
Cross sectional
slice at
x

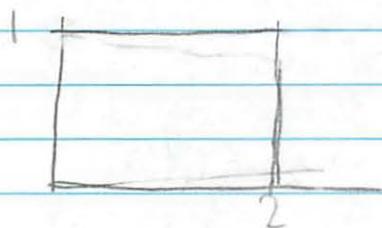
$A(x) = \int_0^b f(x, y) dy$

↑
x held fixed

← always ends at b in rectangle

* partial integration *

think of
math as
patterns



$w = x^2 + y^2$

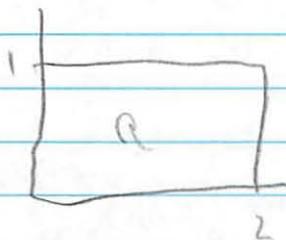
Volume = $\int_a^a \int_a^b f(x, y) dy dx$

A

iterated
integral

order of
integration

example



$w = x^2 + y^2$

Volume under graph $x^2 + y^2 = \int_0^2 \int_0^1 (x^2 + y^2) dy dx$

* do the 2 integrations separately

$$\text{Inner } \int_0^1 (x^2 + y^2) dy$$

$$\left. x^2 y + \frac{y^3}{3} \right|_{0=y}^{1=y}$$

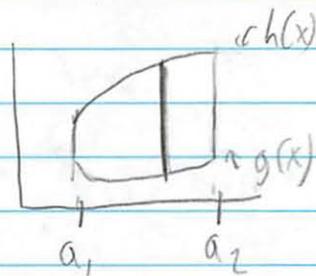
$$x^2 + \frac{1}{3} - 0$$

$$\text{Outer } \int_0^2 \left(x^2 + \frac{1}{3} \right) dx$$

$$\left. \frac{x^3}{3} + \frac{x}{3} \right|_{0=x}^{2=x}$$

$$\left(\frac{10}{3} \right) = \text{Volume}$$

But what if no rectangle?

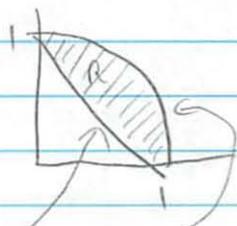


could do circle
if start ends were points

$$W = f(x, y)$$

$$A(x) = \int_{g(x)}^{h(x)} f(x, y) dy \quad x \text{ fixed}$$

$$\text{Volume} = \int_{a_1}^{a_2} \int_{g(x)}^{h(x)} f(x, y) dy dx$$



$w = y$ ← just a plane

$$y = \sqrt{1-x^2}$$
$$y = 1-x$$

$$\text{Vol} = \int_0^1 \int_{1-x}^{\sqrt{1-x^2}} y \, dy \, dx$$

$$\text{Inner} \int_{1-x}^{\sqrt{1-x^2}} y \, dy$$

$$= \frac{y^2}{2} \Big|_{1-x}^{\sqrt{1-x^2}}$$

$$= \frac{1-x^2}{2} - \frac{(1-x)^2}{2}$$

$$= x - x^2$$

$$\text{Outer} \int_0^1 (x - x^2) \, dx$$

$$\frac{x^2}{2} - \frac{x^3}{3} \Big|_0^1$$

$$\frac{1}{2} - \frac{1}{3}$$

$$\text{Volume} = \frac{1}{6}$$

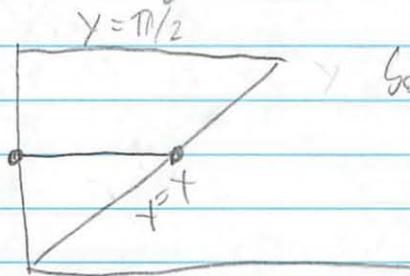
$$\int_0^{\pi/2} \int_x^{\pi/2} \frac{\sin y}{y} dy dx$$

but no elementary integral
use computer

but you can still get ans by changing the order of integration

but limits will change - so can't just change the $\frac{dy}{dx}$

1. Figure out region over which integrating
2. Redo integral



So now use horiz slices

$$\iint \frac{\sin y}{y} dx$$

functions of x of y

$$\int_0^{\pi/2} \int_{x=0}^y \frac{\sin y}{y} dx dy$$

solve for x
as a function
of y

Inner

$$\frac{\sin y \cdot x}{y} \Big|_{x=0}^{x=y}$$

$$= \frac{\sin y}{y}$$

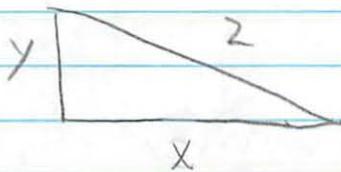
$$= \sin y$$

Outer

$$\int_0^{\pi/2} \sin y \, dy$$

①

More on Chain Rule



constraint $\rightarrow x^2 + y^2 - z^2 = 0$

$$\left(\frac{\partial z}{\partial x} \right)_y$$

say explicitly what ind. variables are

Method 1

- solve for z

$$z = \sqrt{x^2 + y^2}$$

$$\left(\frac{\partial z}{\partial x} \right)_y = \frac{x}{z}$$

implicit differentiation =
kinda like chain rule

Method 2

2. Chain Rule

$$\underbrace{x^2 + y^2 - z^2}_{w} = 0$$

$$\left(\frac{\partial w}{\partial x}\right)_y = w_x = 2x - 2z \left(\frac{\partial z}{\partial x}\right)_y$$

think of z as $f(x, y)$

$$= 0 \text{ since } w = 0$$

Solve for
and it \Rightarrow what got before

3. Abstractly

$$w(x, y, z) = 0$$

\uparrow constant

$$\left(\frac{\partial z}{\partial x}\right)_y$$

Use chain rule

$w = 0$ so ans comes out to 0

$$\left(\frac{\partial w}{\partial x}\right)_y = w_x + w_z \cdot \left(\frac{\partial z}{\partial x}\right)_y = 0$$

\parallel
0

can't
hold
constant

$$\boxed{\left(\frac{\partial z}{\partial x}\right)_y = -\frac{w_x}{w_z}}$$

$$\left(\frac{\partial}{\partial x}\right)_y (xz + y \cos z) = 0$$

↓ product rule

$$= z + x \left(\frac{\partial z}{\partial x}\right)_y - y \left(\frac{\partial z}{\partial x}\right)_y \sin z = 0$$

z is like a function

$$(x - y \sin z) \left(\frac{\partial z}{\partial x}\right)_y = -z$$

$$\left(\frac{\partial z}{\partial x}\right)_y = \frac{-z}{x - y \sin z}$$

So plug it in

$$\left(\frac{\partial z}{\partial x}\right)_y = z + y \left(\frac{-z}{x - y \sin z}\right)$$

By Differentiation

$$df = f_x dx + f_y dy + f_z dz \quad \leftarrow \begin{array}{l} \text{definition} \\ \text{like approx formula} \end{array}$$

$$= 2x dx + (e^y + z) dy + y dz$$

We want an expression like $df = A dx + B dy$

↑ coefficients ↑

$$\left(\frac{\partial f}{\partial x}\right)_y = A$$

$$\left(\frac{\partial f}{\partial y}\right)_x = B$$

Still need to find dz

$$dg = g_x dx + g_y dy + g_z dz = 0$$

$$2 dx + \cos z dy + (x - y \sin z) dz = 0$$

$$dz = \frac{-2}{x - y \sin z} dx - \frac{\cos z}{x - y \sin z} dy$$

get as function of dx and dy only

$$dF = \left(\frac{2x - yz}{x - y \sin z} \right) dx + \left(e^y + z - \frac{y \cos z}{x - y \sin z} \right) dy$$

$$\left(\frac{\partial F}{\partial x} \right)_y = \frac{2x - yz}{x - y \sin z}$$

$$\left(\frac{\partial F}{\partial y} \right)_x = e^y + z - \frac{y \cos z}{x - y \sin z}$$

* Must be able to work w/ both methods x

↳ if just want 1 partial deriv → chain rule
many → differentials

ex2

$$x^2 y + y z = f$$

$$x^2 + y^2 + z^2 = 1$$

$$\left(\frac{\partial f}{\partial x} \right)_y$$

chain rule + differentials

$$2x + \cancel{x^2} + 2z \left(\frac{\partial z}{\partial x} \right)_y = 0$$

↑
constant

~~$$2z \left(\frac{\partial z}{\partial x} \right)_y = -2x - y^2$$~~

~~$$\left(\frac{\partial z}{\partial x} \right)_y = \frac{-2x - y^2}{2z} = -\frac{x}{z} - \frac{y^2}{2z}$$~~

$$\left(\frac{\partial f}{\partial x} \right)_y = 2xy + \cancel{1}x^2 + \cancel{1}z + \left(\frac{\partial z}{\partial x} \right)_y y$$

why am I being stupid and doing chain rule here

~~$$\left(\frac{\partial f}{\partial x} \right)_y = 2xy + \cancel{x^2} + \cancel{z} + \left(\frac{-2x - y^2}{2z} \right) y$$~~

~~$$\left(2xy + \left(2xy - \frac{xy}{z} \right) y \right)$$~~

$$\left(\frac{\partial f}{\partial x} \right)_y = 2xy + y \left(\frac{\partial z}{\partial x} \right)_y$$

$$= 2xy - \frac{xy}{z}$$

b) $df = 2xy dx + (x^2 z) dy + y dz$

$$0 = 2x dx + 2y dy + 2z dz \quad \text{constraint}$$

$$dz = -\frac{x}{y} dx - \frac{y}{z} dy$$

$$df = \left(2xy - \frac{xy}{z} \right) dx + \left(x^2 + 2 - \frac{y^2}{z} \right) dy$$

ex3 x, y, z constrained by $g(x, y, z) = 0$

a) Show that $\left(\frac{\partial z}{\partial x}\right)_y = -\frac{g_x}{g_y}$

b) Show $\left(\frac{\partial x}{\partial y}\right)_z \left(\frac{\partial y}{\partial z}\right)_x \left(\frac{\partial z}{\partial x}\right)_y = -1$

c) Differentiate g w/ respect to x , y constant

$$\left(\frac{\partial}{\partial x} g(x, y, z)\right)_y = 0$$

$$\left(\frac{\partial x}{\partial x}\right)_y g_x + \left(\frac{\partial y}{\partial x}\right)_y g_y + \left(\frac{\partial z}{\partial x}\right)_y g_z = 0$$

\uparrow same \uparrow holding constant

$$g_x + \left(\frac{\partial z}{\partial x}\right)_y g_z = 0$$

$$\left(\frac{\partial z}{\partial x}\right)_y = -\frac{g_x}{g_z}$$

That was not hard - just was very unsure

Using part a

$$b) \left(\frac{\partial x}{\partial y} \right)_z = - \frac{g_y}{g_x}$$

$$\left(\frac{\partial y}{\partial z} \right)_x = - \frac{g_z}{g_y}$$

$$\left(\frac{\partial x}{\partial y} \right)_z \left(\frac{\partial y}{\partial z} \right)_x \left(\frac{\partial z}{\partial x} \right) = \left(\frac{-g_y}{g_x} \right) \left(\frac{-g_z}{g_y} \right) \left(\frac{-g_x}{g_z} \right)$$
$$= -1$$

Lecture 17

Double Integrals in Polar Coords

3/16

SSR

in polar
coords

~~SSR~~

$$\int_a^b \int_{g(x)}^{h(x)} f(x,y) dy dx$$

iterated integral

calculates volume under $f(x,y) = w$
by sliding

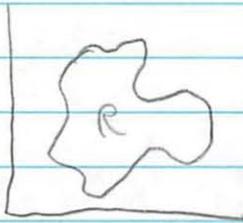
Back up: Double Integral

$$\iint_R f(x,y) dA$$

some region

often not done in rect coords

double integral f over R

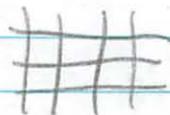


1. use the grid lines of coord system (u, v)
"curves"

$$\begin{cases} u = c_1 \\ v = c_2 \end{cases}$$

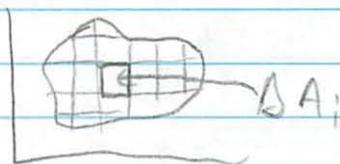
aka level curves
of coord functions

so rect $x = c_1$
 $y = c_2$



2. Divide up R into little pieces

ΔA_i



3. Choose $P_i (u_i, v_i)$ in each ΔA_i

4. Form Riemann Sums

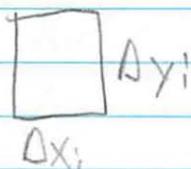
$$\lim_{n \rightarrow \infty} \sum_1^n f(u_i, v_i) \Delta A_i$$

$$= \iint_R f(u, v) dA$$

- but along boundary can be very complicated
- must estimate \square area
- try to divide into 'pieces' which can be calculated ΔA_i

x, y coords

$$\iint_R f(x, y) dy dx$$

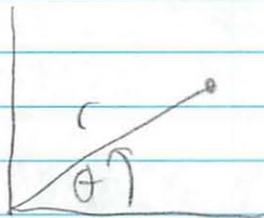


$$dA = \begin{array}{|c|} \hline \square \\ \hline \end{array} dy$$

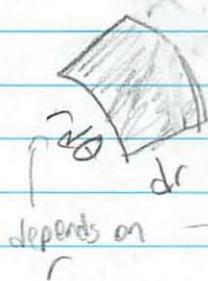
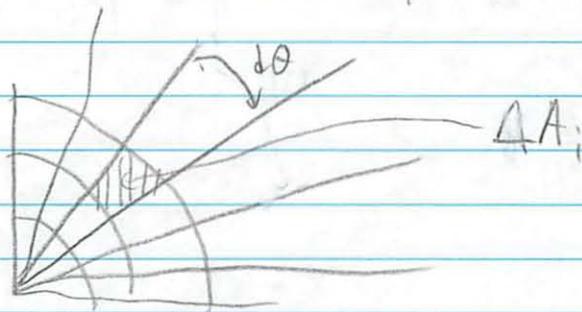
dx

How to evaluate

Polar Coordinates

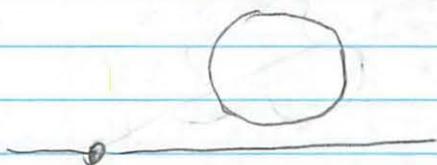


What are the grid lines in polar
 $r = c_1 \rightarrow$ circles with center at origin, radius r
 $\theta = c_2 \rightarrow$ rays from center out



$$dA = r dr d\theta$$

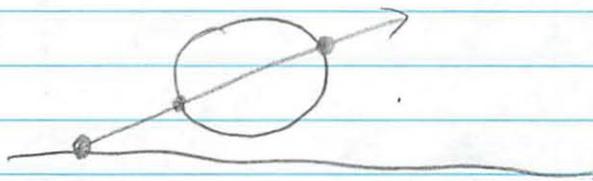
How to put in limits of integration
- see notes I



$$\iint f(r, \theta) r \, dr \, d\theta$$

↑ what integrating 1st w/ respect to?
almost always r

① - so θ fixed, r increases



② inner limits \rightarrow r value where enters region r
to v value where it leaves

- depends on which ray you take (what θ is)

$$r_1 = g(\theta) \quad r_2 = h(\theta)$$

* you must know what region looks like

③

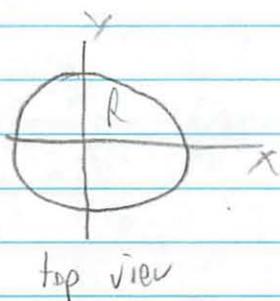
answer a function of θ

So now integrate from where it just enters
to where it just leaves



example

volume of unit hemisphere

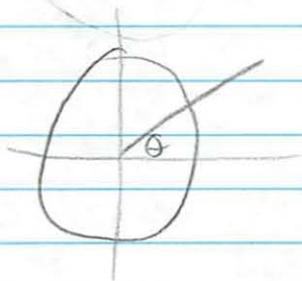


$$f(x, y, z) = x^2 + y^2 + z^2 = 1$$

$$z = \sqrt{1 - x^2 - y^2} \quad \text{solve for } z$$

$$\text{volume} = \iint \sqrt{1 - x^2 - y^2}$$

don't even bother
change to polar coords



$$r = x^2 + y^2$$

$$\text{volume} = \int_0^{2\pi} \int_0^1 \sqrt{1 - r^2} r \, dr \, d\theta$$

angle radius

easy to evaluate

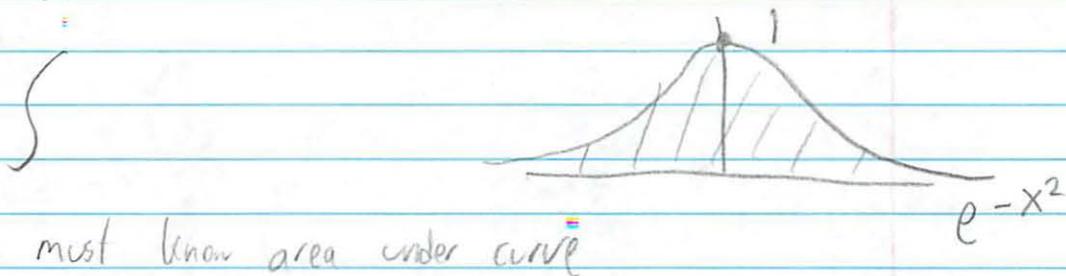
$$\text{Inner} \rightarrow \int \sqrt{1 - r^2}$$

$$-\frac{3}{2} (1 - r^2)^{1/2} \cdot -2r \quad \text{so}$$
$$-\frac{1}{3} (1 - r^2)^{3/2} \Big|_0^1$$

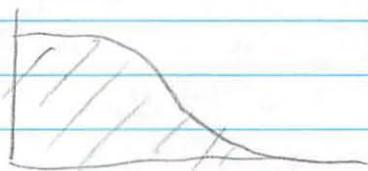
$$= \frac{1}{3}$$

$$\text{outer} = \frac{2\pi}{3}$$

Example 2



must know area under curve



$$\int_0^{\infty} e^{-x^2} dx$$

can't take deriv of "undoable"
but oiler can do it

So trick call it = I

$$\iint e^{-x^2 - y^2} dy dx$$

involves 2 diff
coord systems

$$= \iint e^{-x^2} \cdot e^{-y^2} dy dx$$

Limits

$$\int_0^{\infty} \int_0^{\infty} dy dx$$

Inner: $e^{-x^2} \int_0^{\infty} e^{-y^2} dy$

but know it = $e^{-x^2} I$ ^{don't know how to evaluate}

Outer: $\int_0^{\infty} e^{-x^2} I$

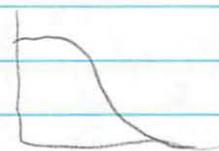
^{don't know}

$$\begin{aligned} &\approx I \cdot I \\ &= I^2 \end{aligned}$$

but what is I ?

In polar coordinates

$$\iint e^{-r^2} r dr d\theta$$



Limits $\int_0^{\pi/2} \int_0^{\infty} e^{-r^2} r dr d\theta$

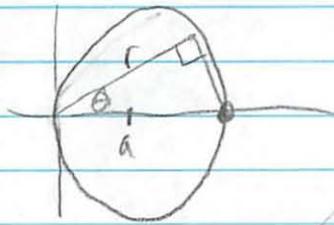
Inner $\rightarrow \frac{1}{2} e^{-r^2} \Big|_0^{\infty}$

$$= \frac{1}{2}$$

Outer $\int_0^{\pi/2} \frac{1}{2} d\theta = \left(\frac{\pi}{4}\right)$ same answer in both coord system

$$= I^2$$

$$\text{So } I = \frac{\sqrt{\pi}}{2}$$



$$r = 2a \cos \theta$$

$$\int_{-\pi/2}^{\pi/2} \int_0^r f(r, \theta) r dr d\theta$$

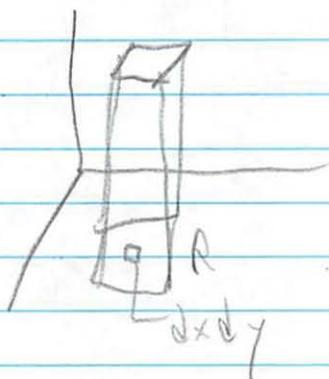


Recitation

3/17

Lecture

- definition
- interpretation of $\iint_R f(x, y) dx dy$
on volume under graph of f

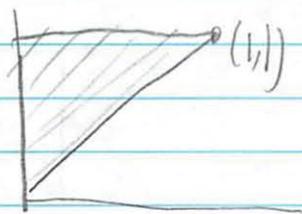


Using polar coords

$$\iint_R f \, dx dy = \iint_{R'} f \, r dr d\theta$$

\uparrow expressed in x, y \uparrow expressed in r, θ

ex1 Compute $I = \iint_R xy \, dx dy$

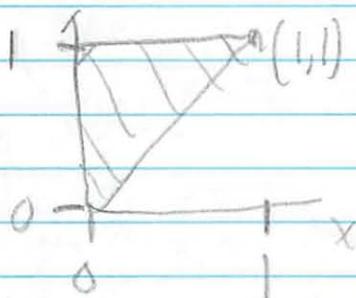


$$I = \iint xy \, dy dx$$

Now need to find limits

- from the triangle
Not the function

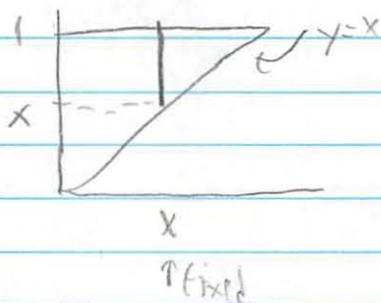
- start w/ outside! (calculation starts inside)



$$\int_0^1 \int dy dx$$

\uparrow_x do 1st
 \uparrow_y do later

For a given x in the range $[0,1]$



$$\int_0^1 \int_x^1 xy dy dx$$

$$I = \int_0^1 \int_x^1 xy \, dy \, dx$$

$$\text{Inside } \int_x^1 xy \, dy$$

$$x \frac{y^2}{2} \Big|_x^1$$

$$\frac{x(1)^2}{2} - \frac{x(x)^2}{2}$$

$$\frac{x}{2} - \frac{x^3}{2}$$

outside

$$\int_0^1 \left(\frac{x}{2} - \frac{x^3}{2} \right) dx$$

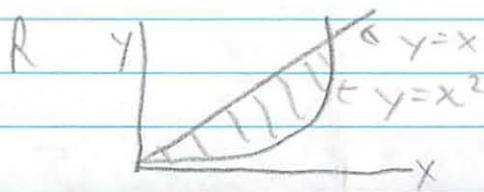
$$\frac{x^2}{4} - \frac{x^4}{8} \Big|_0^1$$

$$\frac{1}{4} - \frac{1}{8} = \frac{1}{8}$$

* at each point have a certain x, y value
want to sum that, not just area *

ex 2 Find the limit of integration of

$$I = \iint_R f(x,y) \, dy \, dx$$



$\int_0^1 \int_{x^2}^x dy dx$

where $x = x^2$ → where does $\frac{x}{x} = \frac{x^2}{x}$
 $1 = x$

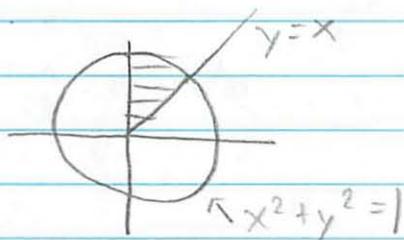
do 1st
 do second



$x^2 \rightarrow x$

$$\int_0^1 \int_{x^2}^x f(x,y) dy dx$$

b)



$$\int_0^1 \int_x^{\sqrt{1-x^2}} f(x,y) dy dx$$

$$x^2 + y^2 = x^2 + x^2 = 1$$

$$2x^2 = 1$$

$$x = \frac{1}{\sqrt{2}}$$

$$x = \frac{\sqrt{2}}{2} = \frac{1}{\sqrt{2}}$$

$$= \cos \frac{\pi}{4}$$

now y

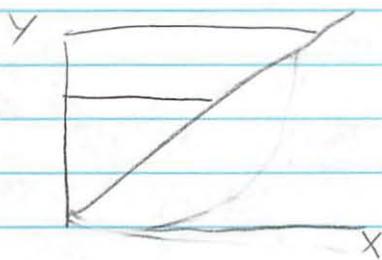


$$\int_x^{\sqrt{1-x^2}}$$

$x^2 + y^2 = 1$
solve for y

$$\int_0^{\frac{\sqrt{2}}{2}} \int_x^{\sqrt{1-x^2}} f(x,y) dy dx$$

What if wanted a $dx dy$



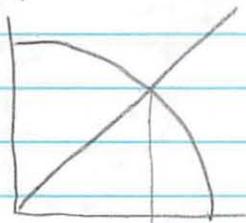
go horizontal

$$\int_0^1 \int_0^y dx dy \quad (\checkmark)$$



picture is intermediate state

If you had



$dy dx$

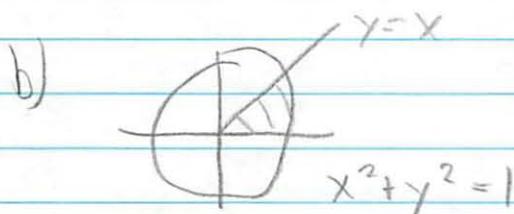
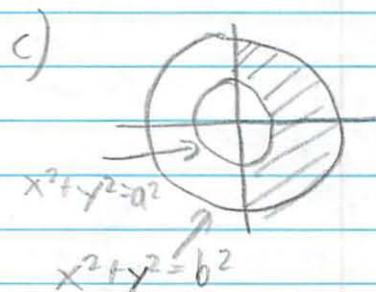
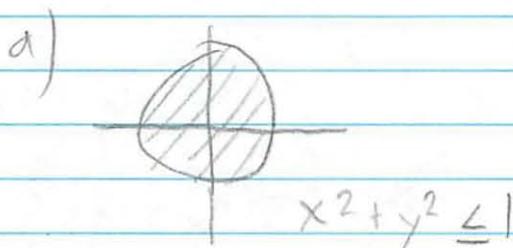
- could split into 2 parts
- or change order to $dx dy$

ex3

Polar Coordinates

Setup the integral

$$I = \iint_R xy \, dx \, dy \text{ in polar coordinates}$$



Find Setup

a)
$$\int_0^{2\pi} \int_0^1 xy \, r \, dr \, d\theta$$

\uparrow \uparrow
 θ r \rightarrow fix θ and look at r \rightarrow

have to replace
 $x = r \cos \theta$
 $y = r \sin \theta$

b)
$$\int_0^{\pi/4} \int_0^1 r \cos \theta, r \sin \theta \, r \, dr \, d\theta$$

\uparrow do let r

$$\int_0^{2\pi} \int_0^1 r \cos \theta \, r \sin \theta \, r \, dr \, d\theta$$

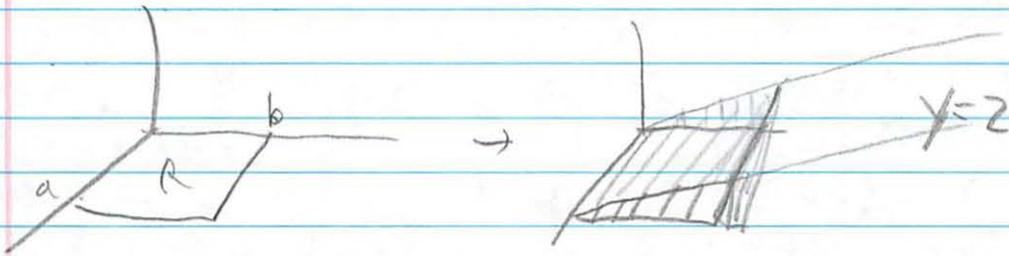
$$r^3 \cos \theta \sin \theta \, dr \, d\theta$$

these
are
actually
really
easy!
but don't
make mistakes

$$\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \int_a^b r \cos \theta r \sin \theta r dr d\theta$$

↑ yes - the radius of each angle
↑ pay attention!

ex4 Computation of volume



$$\text{Vol} = \iint_R f(x, y) dx dy$$

$$f = (x, y) \leftarrow \text{need to find}$$

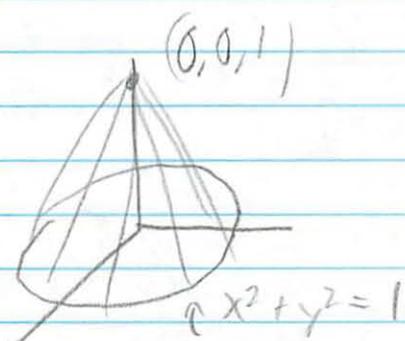
$$= y \quad \text{since graph is a plane}$$

$$R \text{ is rectangle } \begin{matrix} x \in [0, a] \\ y \in [0, b] \end{matrix}$$

$$\text{Vol} = \int_{x=0}^a \int_{y=0}^b y \, dy \, dx$$

function
is R rectangle
= $\frac{ab^2}{2}$ ← then do

b



$$\text{Vol} = \iint_R f \, dx \, dy$$

$$= \iint_R f \, r \, dr \, d\theta$$

$R = \text{unit disc}$

$$= \int_0^{2\pi} \int_0^1 f \, r \, dr \, d\theta$$

Michael Plasmeier

Get P-set 4 solution

20.51305

18.02 Problem Set 5 due Thurs. Mar.18, 10:45 2-106

Part I (15 points)

Lecture 15. Thurs. Mar. 1~~3~~ Chain rule for non-independent variables.

Read: Notes N.1-3 (N.4 optional) Work: 2J-1a, 2i,ii(for (a) only), 3a, 4a, 5a, 6, 7

Lecture 16. Fri. Mar. 1~~2~~ Double and iterated integrals in rectangular coordinates.

Read: 20.1, 20.2, Notes I.1 Work: 3A-1ad, 2b, 3b, 4c, 5a

Lecture 17. Tues. Mar. ¹⁶2~~3~~ Double integrals in polar coordinates

Read: 20.4, Notes I.2 Work: 3B-1ad, 2cd, 3bc

Part II (20 points)

Directions. Try each problem alone for 15 minutes. If you subsequently collaborate, solutions must be written up independently. It is illegal to consult problem sets from previous semesters. With each problem is the day it can be done.

Problem 1. (Thurs. 6 pts.: 1.5 each) Using the usual rectangular and polar coordinates, let w be the area of the right triangle in the first quadrant having its vertices at $(0,0)$, $(x,0)$, and (x,y) .

Using the equation expressing w in terms of x and y , and the equation expressing y in terms of x and θ , calculate the two partial derivatives $\left(\frac{\partial w}{\partial x}\right)_\theta$ and $\left(\frac{\partial w}{\partial \theta}\right)_x$ in three different ways:

- Directly, by first expressing w in terms of the independent variables x and θ ;
- by using the chain rule — for example, $\left(\frac{\partial w}{\partial x}\right)_\theta = w_x \left(\frac{\partial x}{\partial x}\right)_\theta + w_y \left(\frac{\partial y}{\partial x}\right)_\theta$, where w_x and w_y are the formal partial derivatives;
- by using differentials: get two equations connecting dw , dx , dy , and $d\theta$, and use them to eliminate one of the differentials, getting a single equation connecting the remaining differentials, from which the answers can be read off.
- Using the triangle picture and geometric intuition, estimate $\left(\frac{\Delta w}{\Delta x}\right)_\theta$ and $\left(\frac{\Delta w}{\Delta \theta}\right)_x$ from the picture, and show they agree with the two corresponding partial derivatives.

Problem 2. (Fri. 3 pts.) A rectangular prism is made by taking a long piece of wood with a rectangular cross-section, sawing off one end perpendicularly to the four sides, and the other end at an arbitrary angle (so that the four long edges have in general four different lengths).

As an exercise in using double integration, use it to show that the volume of the prism is the product of its cross-sectional area and the average of the lengths of the four long edges. Hint: place the prism so that one long edge lies along the z -axis, and the perpendicular end lies in the first quadrant of the xy -plane. So that everyone will use the same notation, let

a = length of the edge lying along the x -axis;

b = length of the edge lying along the y -axis;

$z = Ax + By + C$ be the equation of the plane forming the slanted top of the prism.

Problem 3. (Fri. 2 pts.) Evaluate by changing the order of integration:

$$\int_0^1 \int_{\sqrt{x}}^1 \sqrt{1+y^4} dy dx .$$

1

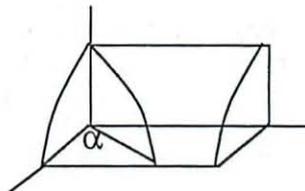
~~So far ahead this week - not using in class this - which wastes it - using valuable time - but use class time for other purposes~~

Problem 4. (Fri. 3 pts.: 2.5, .5)

The picture shows a quarter of a cylindrical log, whose perpendicular cross-section is a quarter of a circular disc of radius a . A wedge-shaped piece has been cut out of the end, by a cutting plane making an angle α with the perpendicular end of the log.

Find the volume of this wedge-shaped piece by using double integration. Place the log and piece with respect to the coordinate axes as shown in the picture.

When $\alpha = \pi/4$, what is the volume? To check whether this is a reasonable answer, find the volume of the tetrahedron ($\frac{1}{3}$ base \times height) having the same four corners as the wedge.

**Problem 5.** (Tues. 6 pts: 2,2,2) Work the following problems:

- a) 20.4/9 (cf. p. 564)
- b) 20.4/15 (cf. formulas at top of Exercises 3B in the Notes)
- c) 20.4/31a

P-Set 5

Michael Plasmeier

3/18

Lecture 15 Chain Rule for non independent variables

2J-1a Calc by direct substitution $\left(\frac{\partial w}{\partial y}\right)_2$
like N example 1

$$w = x^2 + y^2 + z^2$$

$$z = x^2 + y^2$$

$$\text{So } w = x^2 + y^2 + (x^2 + y^2)^2$$
$$x^2 + y^2 + x^4 + 2x^2y^2 + y^4$$

$$\frac{\partial w}{\partial y} = 0 + 2y + 0 + 4x^2y + 4y^3$$

means x is the dependent variable
so get rid of that

$$w = (z - y)^2 + y^2 + z^2 = z^2 - 2zy + y^2 + y^2 + z^2$$

$$\left(\frac{\partial w}{\partial y}\right)_2 = 0 + 0 = 0$$

I kinda see - the z are the indep. variables
which are changing, write the last
as the dep. variable
and then differentiate

2: Calc $\left(\frac{\partial w}{\partial y}\right)_z$ ~~$\left(\frac{\partial w}{\partial z}\right)_y$~~ w/ chain rule
- differentiate $z = x^2 + y^2$

So w/ same formulas:

$$w = x^2 + y^2 + z^2$$

$$\begin{aligned}\left(\frac{\partial w}{\partial y}\right)_z &= 2x x' + 2y + (2(x^2 + y^2)) \cdot (2x x' + 2y) \\ &= 2x x' + 2y + 4x x' (x^2 + y^2) + 2y(x^2 + y^2)\end{aligned}$$

First differentiate $z = x^2 + y^2$ w/ respect to y

$$0 = 2x \left(\frac{\partial x}{\partial y}\right)_z + 2y$$

$$\left(\frac{\partial x}{\partial y}\right)_z = -\frac{y}{x}$$

Now by chain rule

$$\begin{aligned}\left(\frac{\partial w}{\partial y}\right)_z &= 2x \left(\frac{\partial x}{\partial y}\right)_z + 2y \\ &= 2x \left(-\frac{y}{x}\right) + 2y \\ &= 0\end{aligned}$$

2ib

$$\left(\frac{\partial w}{\partial z}\right)_y$$

diff w/ respect to z \odot

$$z = x^2 + y^2$$

$$1 = \cancel{0} + 2x \left(\frac{\partial x}{\partial z}\right)_y + 0^2$$

← what is left

the dependent variable

$$\left(\frac{\partial x}{\partial z}\right)_y = \frac{1}{2x}$$

$$\left(\frac{\partial w}{\partial z}\right)_y = 0 + \cancel{2y} + 2x \left(\frac{\partial x}{\partial z}\right)_y + 2z$$

differentiate normally

$$= 2\cancel{y} + 2x \left(\frac{1}{2x}\right)$$

$$= 2\cancel{y} + \cancel{2x}$$

$$= 2\cancel{y} + \cancel{x}$$

$$= 1 + 2z$$

Should practice more

Reviewed both w/o looking on separate sheet

2ii a (a only) $\left(\frac{\partial w}{\partial y}\right)_z$ w/ differentials

$$w = x^2 + y^2 + z^2$$
$$dw = 2x dx + 2y dy + 2z dz$$

$$z = x^2 + y^2$$
$$dz = 2x dx + 2y dy$$

are we supposed to have a constraint as well?

~~$dw = 2x dx$~~ Want to eliminate dx
subtract 2nd eq from 1st eq

$$dw = 0 dx + (1 + 2z) dz$$

So what did they do

$$2x dx = dz - 2y dy$$

$$dw = (dz - 2y dy) + 2y dy + 2z dz$$
$$dw = dz + 2z dz$$
$$(1 + 2z) dz \quad \checkmark \text{ matches}$$

Then $Dz \rightarrow$ If n variables x, y, \dots are independent, 2 differentials are = if and only if their corresponding coefficients are =

$$Ax + By = A_1 x + B_1 y$$

only if $A = A_1$
 $B = B_1$

So what in all world does that mean?

$$\left(\frac{\partial w}{\partial y}\right)_z = 0 \quad \left(\frac{\partial w}{\partial z}\right)_y = 1 + 2z$$

So basically coefficient of $dx = \frac{\partial w}{\partial x}$
" " " " $dy = \frac{\partial w}{\partial y}$
" " " " $dz = \frac{\partial w}{\partial z}$

3a Using chain rule calc $\left(\frac{\partial w}{\partial t}\right)_{x,z}$ in terms x, y, z, t
example 2

So now 4 variables

$$w = x^3 y - z^2 t \quad xy = zt$$

So we want to get rid of y (the dep variable)

$$y = \frac{zt}{x}$$

$$w = x^3 \left(\frac{zt}{x}\right) - z^2 t$$

$$w = x^2 zt - z^2 t$$

$$\left(\frac{\partial w}{\partial t}\right)_{x,z} = x^2 \left(\frac{\partial y}{\partial t}\right)_{x,z} - z^2$$

differentiate original $w \rightarrow$ for y write $\left(\frac{\partial y}{\partial t}\right)_{x,z}$

differentiate constraint

$$\left(\frac{\partial x}{\partial t}\right)_{x,z} = \frac{2}{x}$$

↙ that is chain rule
seems simple - but
write it all out

Now plug in

$$\left(\frac{\partial w}{\partial t}\right)_{x,z} = x^3 \left(\frac{2}{x}\right) - 2^2$$

$x^2 2 - 2^2$

4a. Again w/ differential

$$w = x^3 y - 2^2 t \quad xy = 2t$$
$$\left(\frac{\partial w}{\partial t}\right)_{x,z} dw = 3x^2 dx dy - 2z dz dt \quad dx dy = dz dt$$

$$dy = \frac{dz dt}{dx} = x dy$$

$$3x^2 dx \left(\frac{dz dt}{dx}\right) - 2z dz dt$$

$$3x^2 dz dt - 2z dz dt$$
$$(3x^2 - 2z) dz dt$$

$$\text{coefficient } dz dt = 3x^2 - 2z = \left(\frac{\partial w}{\partial t}\right)_{x,z}$$

they get
?hav in all
world

$$dw = 2x^2 y dx + (x^2 z - 2^2) dt + (x^2 t - 2z t) dz$$

$$\hookrightarrow x^2 z - 2^2$$

5a Let $S = S(p, v, T)$ entropy of gas ~~PV = nRT~~

Give $\left(\frac{\partial S}{\partial p}\right)_v$ in terms of S_p, S_v, S_T

so what is constraint?

$$PV = nRT$$

↑↑ constants

$$\left(\frac{\partial S}{\partial p}\right)_v = S_p + S_T \left(\frac{\partial T}{\partial p}\right)_v$$

$$S_p + S_T \frac{v}{nR}$$

? I don't get what is so special about that

Q. IF $w = U^3 - UV^2$ $U = xy$ $V = U + x$

Find $\left(\frac{\partial w}{\partial U}\right)_x$ and $\left(\frac{\partial w}{\partial x}\right)_U$ using chain rule + differentials

Will do this
after recitation

so 2 constraints

- one for each one

- or will it work for both

~~$$\left(\frac{\partial w}{\partial U}\right)_x = 3U^2 \left(\frac{\partial U}{\partial U}\right)_x - \left(\frac{\partial V}{\partial U}\right)_x V^2$$~~

5a
red

$$PV - nRT = 0$$

$$s(P, V, T)$$

office
hrs

$$\left(\frac{\partial s}{\partial P}\right)_V$$

don't know s

~~$\frac{\partial s}{\partial P}$~~ $\rightarrow \frac{\partial s}{\partial P} \left(\frac{\partial P}{\partial P}\right)_V + \frac{\partial s}{\partial V} \left(\frac{\partial V}{\partial P}\right)_V$

$+ \frac{\partial s}{\partial T} \left(\frac{\partial T}{\partial P}\right)_V$

~~PVT~~

both
indp variables

$$\frac{\partial s}{\partial P} + \frac{\partial s}{\partial T} \left(\frac{\partial T}{\partial P}\right)_V$$

$$T = \frac{PV}{nR} \quad \left(\frac{\partial T}{\partial P}\right)_V = \frac{V}{nR}$$

$$\frac{\partial s}{\partial P} + \frac{\partial s}{\partial T} \left(\frac{V}{nR}\right)$$

Or do they want us to sub it in?

$$\begin{aligned}w &= (xy)^3 - (xy)(v+x)^2 \\&= x^3y^3 - (xy)(xy+x)^2 \\&= x^3y^3 - (xy)(x^2y^2 + 2x^2y + x^2) \\&= x^3y^3 - x^3y^3 - 2x^3y^2 + x^3y \\&= -2x^3y^2 + x^3y\end{aligned}$$

But then how deal w/ v

chain rule

$$\text{Just do } \left(\frac{\partial w}{\partial v}\right)_x = 3v^2 - v^2 - v \cdot 2v \left(\frac{\partial v}{\partial v}\right)_x$$

differentiate w/ respect to v

constraint

x constant

v should be $\left(\frac{\partial v}{\partial v}\right)_x$

which one?

$$\left(\frac{\partial v}{\partial v}\right)_x = 1 + 0$$

↑ plug in

$$\left(\frac{\partial w}{\partial v}\right)_x = 3v^2 - v^2 - 2v^2 \quad (\checkmark)$$

Now other one

$$\left(\frac{\partial w}{\partial x}\right)_v = 0 - v \cdot 2v \left(\frac{\partial v}{\partial x}\right)_v = 0$$

$$v = u + x$$

$$\left(\frac{\partial v}{\partial x}\right)_u = 0 + 1$$

diff w/ respect x

$$u = \text{constant}$$

$$v = \left(\frac{\partial v}{\partial x}\right)_u$$

$$\left(\frac{\partial w}{\partial x}\right)_u = -2uv \quad \checkmark \text{ got it no looking}$$

b) Now lets do same w/ differentials

$$dw = 3u^2 du - u \cdot 2v dv + v^2 du$$

$$dv = du + dx$$

$$\cancel{dw = 3u^2 du - u \cdot 2(u+dx) dv + (du+dx)^2 dv}$$

$$\begin{aligned} dw &= 3u^2 du - u \cdot 2v(du+dx) + v^2 du \\ &= 3u^2 du - 2uv du + 2uv dx + v^2 du \\ &= 3u^2 + v^2 - 2uv du - 2uv dx \end{aligned}$$

$$\left(\frac{\partial w}{\partial u}\right)_x = 3u^2 + v^2 - 2uv$$

almost right
product rule

$$\left(\frac{\partial w}{\partial x}\right)_u = -2uv \quad \checkmark$$

? add you do both at once \rightarrow faster

Lecture 16 Double + iterated integrals in rect. coordinates

3A-1a $\int_0^2 \int_{-1}^1 (6x^2y + 2y) dy dx$
? copy problem wrong

So this is volume under a surface

Integrate area in slice

Then Integrate all of the slices

So inner

$$\int_{-1}^1 6x^2y + 2y dy$$

$$\frac{6x^2y^2}{2} + \frac{2y^2}{2} \Big|_{-1}^1$$

$$3x^2y^2 + y^2 \Big|_{-1}^1$$

$$3x^2(1)^2(1)^2 - 6x^2(-1)^2(-1)^2$$
$$\frac{6x^2 + 1 - 6x^2 + 1}{2} = 12x^2$$

$$\int_0^2 12x^2 dx$$

$$\frac{12x^3}{3} \Big|_0^2$$

~~12~~ (32)

long way to screw up

7. $P = (1, -1, 1)$ $z = x^2 + y + 1$

$f(x, y, z)$ differentiable
 $\nabla f(x, y, z) = 2\hat{i} + \hat{j} - 3\hat{k}$ at that pt

$g(x, z) = f(x, y(x, z), z)$ Find ∇g at $(1, 1)$
 x, z

so x, z independent, y dependent ✓

so $\left(\frac{\partial g}{\partial x}\right)_z = 1$ $\left(\frac{\partial g}{\partial z}\right)_x = -1$

but how work backwards w/o function?

$dz = 2x dx + dy$ ✓ \rightarrow at $P = 2dx + dy$

$dy = dz - 2x dx$

$df = 2x dx + dy - 3 dz$ at P

↑
 Oh yeah had f and points
 - but its Δf

eliminate dy ✓

$df = 0 dx - 2 dz$ at $(x, y) = (1, 1)$

so $\nabla g = \langle 0, -2 \rangle$ at $(1, 1)$

don't get

redo 7

$$z = x^2 + y + 1$$

$$p = (1, -1, 1)$$

OH $f(x, y, z)$ I don't know

- he said what he has
 $\nabla f(x, y, z)$ at $p = 2\hat{i} + \hat{j} - \hat{k}$
 $\nearrow \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$

$$g(x, z) = f(x, y(x, z), z) \quad \text{(recognize pattern)}$$

Find ∇g at $x=1, z=1$

Can rewrite $y = 2 - x^2 - 1$

$$\nabla g = \left\langle \frac{\partial g}{\partial x} \hat{i} + \frac{\partial g}{\partial z} \hat{j} \right\rangle$$

\uparrow (find)_z \uparrow (find)_z

$$\frac{\partial g}{\partial x} = \frac{\partial f}{\partial x} \left(\frac{\partial x}{\partial x} \right)_z + \frac{\partial f}{\partial y} \left(\frac{\partial y}{\partial x} \right)_z + \frac{\partial f}{\partial z} \left(\frac{\partial z}{\partial x} \right)_z$$

because g is a function of x

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} (-2x) + 0$$

\uparrow from $y = 2 - x^2 - 1$

$$= \text{at } p \downarrow \text{ given } 2\hat{i} + \hat{j} - \hat{k}$$

$$2 + 1(-2(1)) = 0 \quad \leftarrow \text{at that pt}$$

\Rightarrow

$$= 0$$



that is for 1st
coord of gradient

$$\nabla g = \left\langle 0, \frac{\partial g}{\partial z} \right\rangle$$

↓ need to find (use differential)

$$dg = \frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial z} dz = \text{definition}$$



↑
coefficient

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$$

↑
know

↑

← known

try to conclude that
 $dy = dz - 2x dx$

$$df = 2 dx + (dz - 2x dx) + -3 dz$$

$$(2 - 2x) dx + 1 - 3 dz$$

at pt = 1

$$(2 - 2(1)) dx - 2 dz$$

$$\frac{\partial g}{\partial x} = 0 \quad \text{✓ verified}$$

$$\frac{\partial g}{\partial z} = -2$$

$$\left\langle 0, -2 \right\rangle$$

↓.
Hope this
goes better

$$\int_0^1 \int_0^u \sqrt{v^2 + 4} \, dv \, du$$

$$\int_0^u (v^2 + 4)^{1/2} \, dv$$

$$v (v^2 + 4)^{1/2} \Big|_0^u$$

$$u (v^2 + 4)^{1/2} - 0$$

$$\int_0^1 u (v^2 + 4)^{1/2} \, du$$

$$s = v^2 + 4$$

$$ds = 2 \, dv \, v$$

$$\frac{1}{2} \int \sqrt{s} \, ds$$

$$\frac{1}{2} \cdot \frac{2 s^{3/2}}{3}$$

$$\frac{s^{3/2}}{3}$$

$$\frac{1}{3} (v^2 + 4)^{3/2} \Big|_0^1$$

$$\frac{1}{3} (1^2 + 4)^{3/2}$$

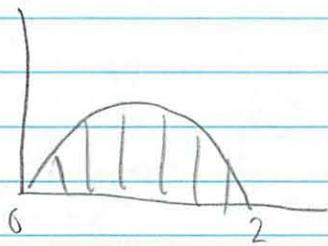
$$\frac{1}{3} \cdot 5^{3/2}$$

$$\frac{5\sqrt{5}}{3}$$

2b) Express double integral as iterated integral

R is finite region by $y = 2x - x^2$ and x -axis

1.) Express as $\iint_R dy dx$



what is iterated integral?
did we do that in lecture?

function y of x

Figure out bounds

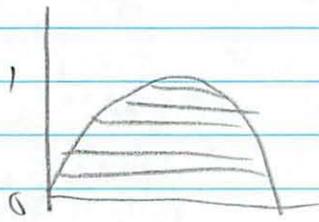
$$\int_0^2 \int_0^{2x-x^2}$$

? what here just $dy dx$

but how do we solve

don't think we have to - not in solution

b) $\int \int_R dx dy$ now other way



$$\int_0^1 \int_{2x-x^2}^{2x-x^2}$$

not going to work

next \rightarrow

Solve $y = 2x - x^2$ for x in terms of y

$$-x^2 + 2x - y = 0$$

Solve w/ quadratic formula

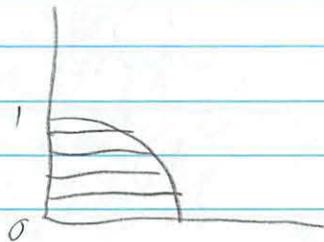
$$x = 1 \pm \sqrt{1-y}$$

$$\int_0^1 \int_{1-\sqrt{1-y}}^{1+\sqrt{1-y}} dx dy$$

3b. Evaluate

$$\iint_R (2x + y^2) dA$$

$y^2 = 1-x$ 1st quad
dx dy easier
↑ means Ⓐ



$$y = \sqrt{1-x}$$

for dx
↑ need in terms of $x = \text{something}$

~~$$\int_0^1 \int_0^{\sqrt{1-x}} (2x + y^2) dx dy$$~~

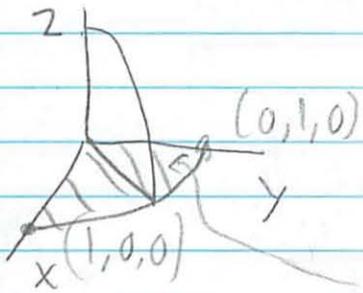
↑ why is this here?
and not before



36

$$\iint_R (2x + y^2) dA$$

$$y^2 = 1 - x$$



R is the region

$$\int_0^1 \int_{-\sqrt{1-x}}^{\sqrt{1-x}} (2x + y^2) dx dy$$

find range

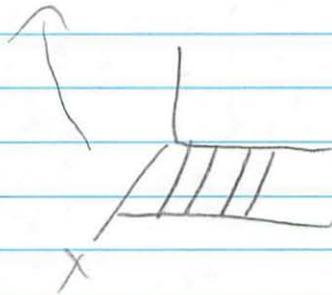


redo
Office
Hrs

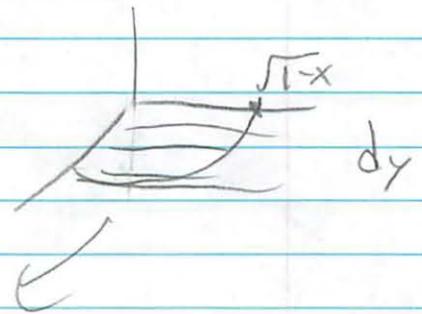
first \int over x

$$1 - y^2 = x$$

graphically y how far it
comes out of the page



dx



dy dx

$$\int_0^1 \int_0^{\sqrt{1-x}} (2x + y^2) dy dx$$

Also need to actually do it

$$\int_0^1 \int_0^{1-y^2} (2x+y^2) dx dy$$

$$\int_0^1 \int_0^{1-y^2} 2x+y^2 dx$$

$$\left. \frac{2x^2}{2} + y^2 \frac{x}{1} \right|_0^{1-y^2}$$

$$\begin{aligned} & (1-y^2)^2 + (1-y^2)y^2 - 0 \\ & 1^2 - 2y^2 + y^4 + y^2 - y^4 \\ & -y^2 + 1 \end{aligned}$$

$$\int_0^1 -y^2 + 1 dy$$

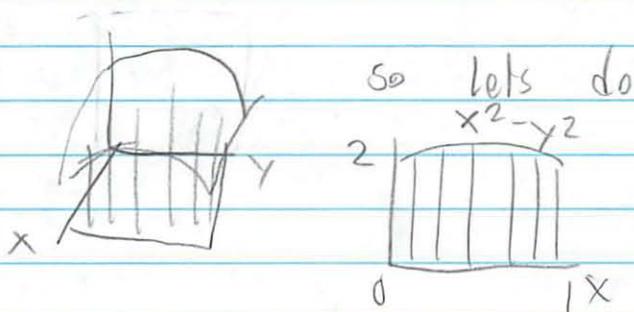
$$\left. -\frac{y^3}{3} + y \right|_0^1$$

$$-\frac{1^3}{3} + 1 - 0$$

$$\left(\frac{2}{3} \right) \quad 0$$

4c Find by 2x integration volume of following solids

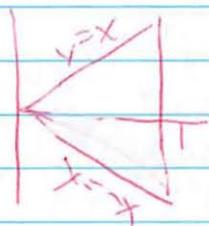
The finite solid lying underneath $x^2 - y^2$
above xy plane between $x=0$ planes
 $x=1$



$$\int_0^1 \int_0^{x^2 - y^2} dy dx$$

↑ what goes in here, if anything?

function $x^2 - y^2$ is 0 on $y = x$
positive in region $y = -x$



what are axis of this graph

$$\iint_R (x^2 - y^2) dA = \int_0^1 \int_{-x}^x (x^2 - y^2) dy dx$$

Now solve

$$\int_{-x}^x x^2 - y^2 dy$$

$$x^2 y - \frac{y^3}{3} + C \Big|_{-x}^x$$

$$x^2(x) - \frac{(x)^3}{3} - \left[x^2(-x) - \frac{(-x)^3}{3} \right]$$

$$x^3 - \frac{x^3}{3} - \left[-x^3 + \frac{x^3}{3} \right]$$

$$x^3 - \frac{x^3}{3} + x^3 - \frac{x^3}{3}$$

$$2x^3 - \frac{2x^3}{3}$$

$$\frac{4x^3}{3} - \frac{2x^3}{3}$$

$\frac{4x^3}{3}$ e shall have seen that

$$\int_0^1 \frac{4x^3}{3} dx$$

$$\frac{4x^4}{3 \cdot 4} \Big|_0^1 = \frac{x^4}{3}$$

$$\frac{(1)^4}{3} = \left(\frac{1}{3}\right) \textcircled{1}$$

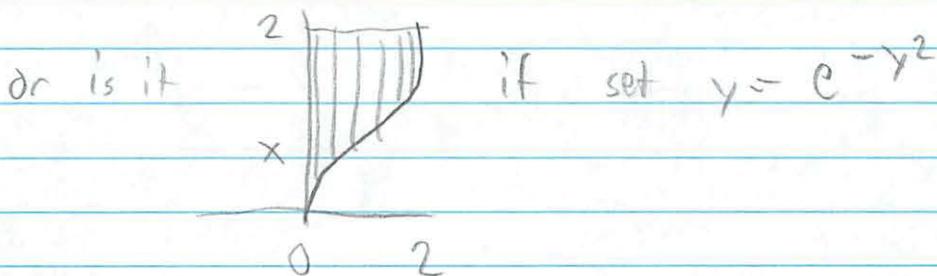
5a. Evaluate each of the following ^{iterated} integrals by changing the order of integration (draw R)

Once I get on a roll it gets fast

$$a) \int_0^2 \int_x^2 e^{-y^2} dy dx$$



So how do we flip - should be in notes



$$= \int_0^2 \int_0^y e^{-y^2} dx dy$$

↑ simple change

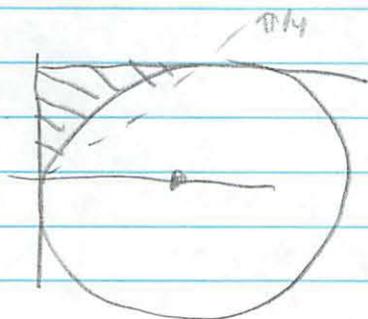
$$= \int_0^2 e^{-y^2} \cdot y dy$$

$$= \frac{1}{2} e^{-y^2} \Big|_0^2 = \frac{1}{2} (1 - e^{-4})$$

??
I don't really get

3b-1d

Office
hrs



Go from origin - always
from origin

$$\int_{\pi/4}^{\pi/2} \int_0^a$$

↳ fix θ



have to write right of r

convert

$$y = a$$

$$r \sin \theta = y = a$$

$$r = \frac{a}{\sin \theta}$$

← translate 'into polar'
do not forget

Translate ~~circle~~ function

$$(x - a)^2 + y^2 = a^2$$

$$(r \cos \theta - a)^2 + (r \sin \theta)^2 = a^2$$

$$r^2 - 2ar \cos \theta = 0$$

solve for r

$$r = 2a \cos \theta$$

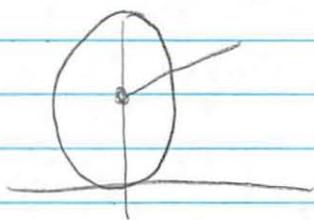
$$\int_{\pi/4}^{\pi/2} \int_0^{a/\sin \theta} 2a \cos \theta$$

Lecture 17 Double Integrals in Polar Coordinates

3B-1a Express each double integral over R as iterated integral in polar coords.
 May need to break up into parts

b) Circle of radius 1 center at $(0, 1)$

no ans
 on 1st
 problem
 stupid



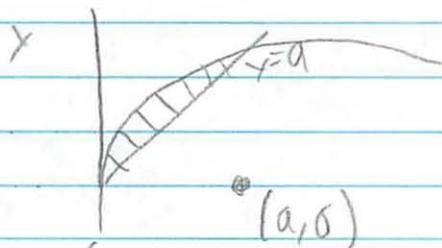
$$r = \sqrt{x^2 + y^2}$$

length of r is that

$$\int_0^{2\pi} \int_0^{\sqrt{1-r^2}} \frac{x^2 + y^2}{\sqrt{1-r^2}} r dr d\theta$$

well the $+1$ does not matter for volume, right

d Finite region



$$\int_{\frac{\pi}{2}}^{\pi} \int_a^r \frac{x^2 + y^2}{\sqrt{1-r^2}} r dr d\theta$$

well actually circle is $x^2 + y^2 + z^2 = 1$

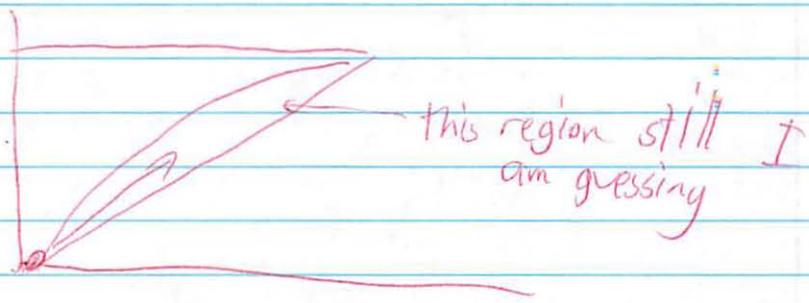
$$z = \sqrt{1 - x^2 - y^2} \quad r = \sqrt{x^2 + y^2}$$

$$z = \sqrt{1 - r^2}$$

↑
↑
↑
don't
get at
all

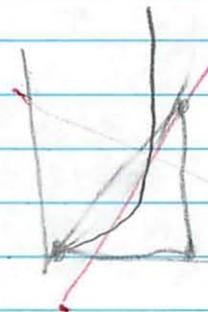
$$\iint_R r dr d\theta = \int_{\pi/4}^{\pi/2} \int_{2a \cos \theta}^{\csc \theta} r dr d\theta$$

Oh Jay drew pic much differently



2c Evaluate over the indicated region using polar coords

$$\iint_R \tan^2 \theta dA \quad R \text{ is triangle } (0,0)(1,0)(1,1)$$



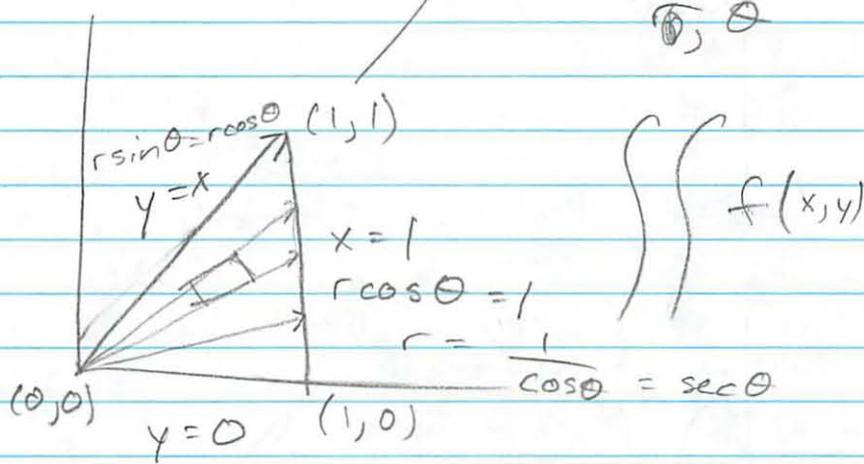
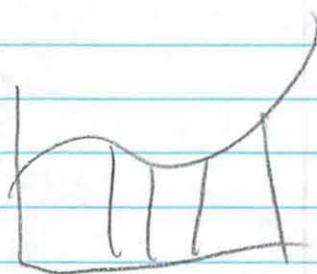
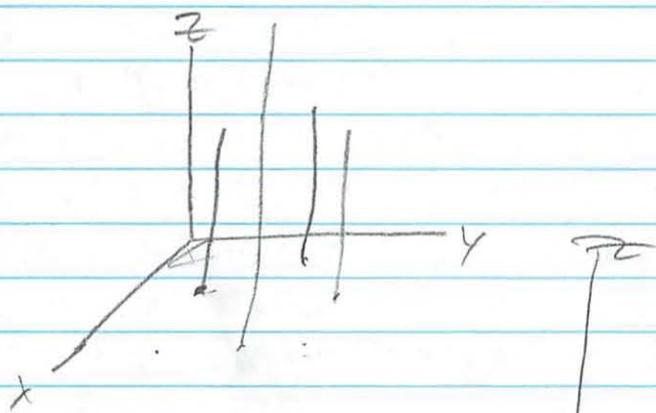
3D
does this not make more sense rectangular

~~$$\int_0^{\pi/2} \int_0^{\tan^2 \theta} \tan^2 \theta r dr d\theta$$~~

$$\int_0^{\pi/4} \int_0^{\sec \theta} \tan^2 \theta r dr d\theta$$

help from Jay
→

2c
 help
 from Jay
 last semester
 student



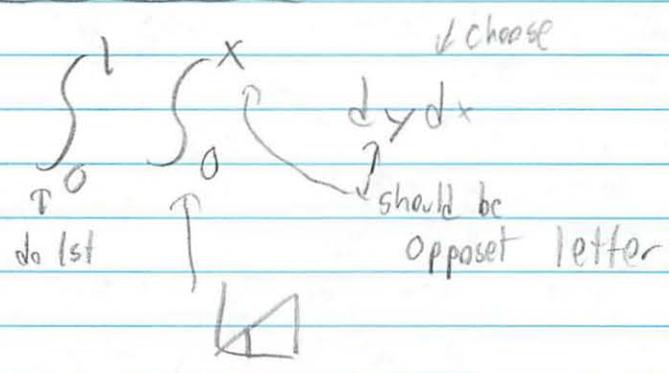
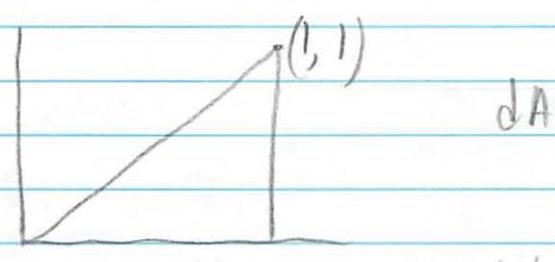
$$\iint f(x,y)$$

$$\int_0^{\pi/4} \int_0^{\sec \theta} \tan^2 \theta \, r \, dr \, d\theta$$

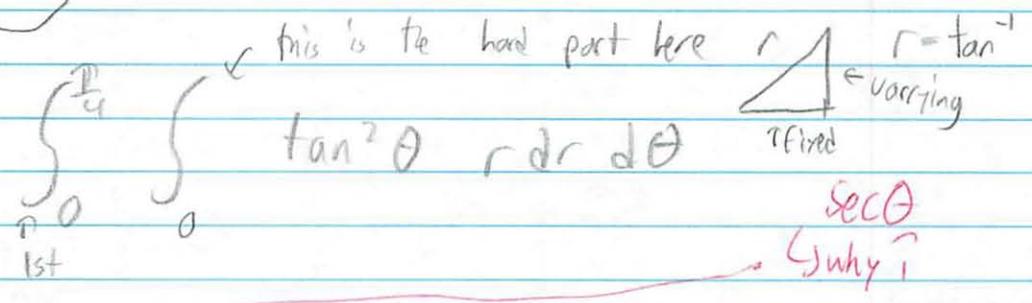
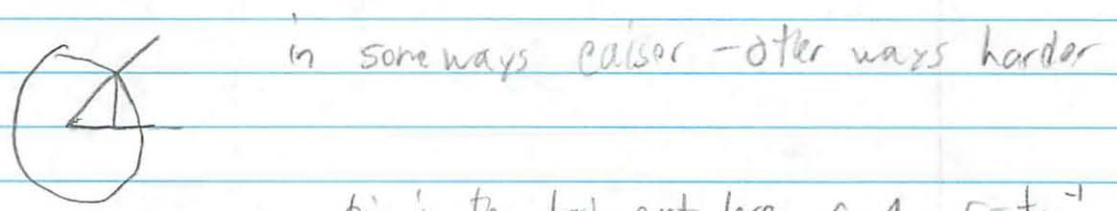
recitation 3/17
 Yeah this makes much more sense
 - ignore actual function for the boundaries
 - I was making it harder on myself

2c
redo
knowing
more

$$\iint_R \tan^2 \theta \, dA$$



But want polar



like Jay's picture $x=1$
 $r \cos \theta = x = 1 \leftarrow$ must know (used often)
 $r = \frac{1}{\cos \theta} = \sec \theta$

Now need to actually do

$$\int_0^{\sec \theta} \tan^2 \theta \, r \, dr$$

$$\frac{\tan^2 \theta r^2}{2} \Big|_0^{\sec \theta}$$

$$\frac{\tan^2 \theta \sec^2 \theta}{2}$$

$$\int_0^{\pi/4} \frac{\tan^2 \theta \sec^2 \theta}{2} \, d\theta$$

$$\frac{1}{2} \int u^2 \, du \quad \begin{array}{l} u = \tan \theta \\ du = \sec^2 \theta \end{array}$$

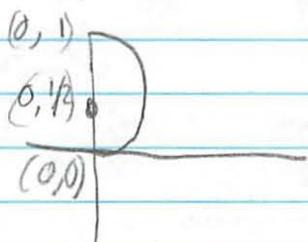
$$\frac{1}{2} \frac{u^3}{3}$$

$$\frac{\tan^3 \theta}{6} \Big|_0^{\pi/4}$$

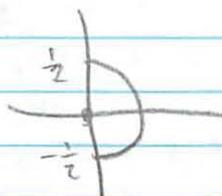
$$\frac{\tan^3 \left(\frac{\pi}{4} \right)}{6} = \frac{1}{6}$$

2d

$$\iint_R \frac{dx dy}{\sqrt{1-x^2-y^2}}$$

hopefully
know how!

→ position does
not
matter



$$\int_{-\pi/2}^{\pi/2} \int_0^{1/2} r dr d\theta$$

$$x = r \cos \theta$$

* need to convert function $y = r \sin \theta$

$$\sqrt{1 - r^2 \cos^2 \theta - r^2 \sin^2 \theta}$$

$$\sqrt{1 - r^2 (\cos^2 \theta + \sin^2 \theta)}$$

$$\sqrt{1 - \cos(2\theta)}$$

double angle

how do

$$\int_0^{1/2} \sqrt{1 - \cos(2\theta)} r dr$$

$$\frac{\sqrt{1 - \cos(2\theta)} r^2}{2} \Big|_0^{1/2}$$

$$\frac{\sqrt{1 - \cos(2\theta)} (\frac{1}{4})}{2}$$

$$\int_{-\pi/2}^{\pi/2} \frac{\sqrt{1 - \cos(2\theta)}}{8} d\theta$$

$$-\frac{\sqrt{1-\cos(2x)}}{8} \cot x \Big|_{-\pi/4}^{\pi/4}$$

$$= \frac{1}{4} (-1 + \sqrt{2})$$

$$\approx .10355$$

does
not seem
right

I went the wrong way w/ x and y

$$\rightarrow r = \sqrt{x^2 + y^2}$$

$$S_0 \int_0^{\pi/2} \int_0^{\sin \theta} \frac{r}{1-r^2} dr d\theta$$

$$\int_0^{\sin \theta} \frac{r}{1-r^2} dr$$

$$-\frac{1}{2} \int \frac{1}{u} du$$

$$u = 1-r^2 \\ du = -2r dr$$

$$-\sqrt{u}$$

$$-\sqrt{1-r^2} \Big|_0^{\sin \theta}$$

$$\int_0^{\pi/2} \sqrt{1-\sin^2 \theta} d\theta$$

$$= \int_0^{\pi/2} \sqrt{\cos^2 \theta} d\theta$$

$$= \int_0^{\pi/2} \cos \theta d\theta$$

had to use
PC to integrate
- be able to
do! started
HS calc
integration

$$\int -\sin \theta \Big|_0^{\pi/2}$$

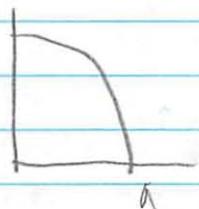
$$\theta - \sin \frac{\pi}{2}$$

$$\frac{\pi}{4} - (-1)$$

3b. Find volume by integrating polar coords

domain under xy over quarter disk region
inside $x^2 + y^2 = a^2$

↑ why can't they just rewrite
this??



$$\int_0^{\pi/2} \int_0^a xy \, r \, dr \, d\theta$$

↑ this is the plane!

* convert x and y

$$\int_0^{\pi/2} \int_0^a r \cos \theta \cdot r \sin \theta \cdot r \, dr \, d\theta$$

$$\int_0^{\pi/2} \int_0^a r^3 \cos \theta \sin \theta \, dr \, d\theta$$

$$\int_0^a r^3 \cos \theta \sin \theta \, dr$$

$$\frac{r^4 \cos \theta \sin \theta}{4} \Big|_0^a$$

$$\int_0^{\pi/2} \frac{a^4 \cos \theta \sin \theta}{4} d\theta$$

$$\frac{a^4 \cancel{\cos \theta} \frac{1}{2}}{8} \Big|_0^{\pi/2}$$

$$\frac{a^4 \cancel{\cos}^2 \left(\frac{\pi}{2} \right)}{8}$$

$$\text{but } \cos \theta \left(\frac{\pi}{4} \right) = 0$$

$$0 \quad \frac{a^4}{8}$$

keep making
quick mistakes

3c The domain lying under $z = \sqrt{x^2 + y^2}$ over circle
radius 1 center (0,1)

Does not matter, right?

- did something like this in recitation

So base of a cone $\rightarrow x^2 + y^2 = 1$

$$\text{Vol} = \iint_R f \, dx \, dy$$

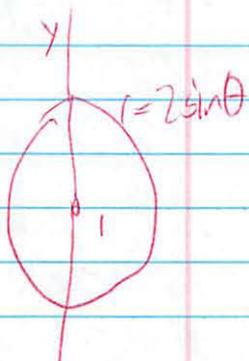
$$= \iint_{R \text{ unit disk}} f \, r \, dr \, d\theta$$

$$\int_0^{2\pi} \int_0^1 f \, dr \, d\theta$$

- so what does circle's domain have to do w/ it?

So that was the formula

In order to use integral formula at 3B
use symmetry about y axis to compute
volume on right + double that answer



$$\begin{aligned} & \iint_R \sqrt{x^2 + y^2} \, dA \\ &= 2 \int_0^{\pi/2} \int_0^{2 \sin \theta} r \, dr \, d\theta \end{aligned}$$

adding vertical slices? $= 2 \int_0^{\pi/2} \frac{1}{3} (2 \sin \theta)^3 \, d\theta$



$$= 2 \cdot \frac{8}{3} \cdot \frac{2}{3}$$

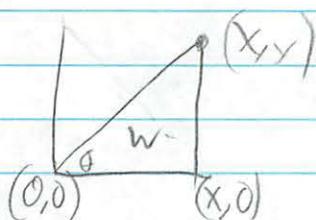
$$\left(\frac{32}{9} \right)$$

Oh there were formulas in the start of 3B question section
- just integration formulas

Think I visualized wrong

Part 2

1. Using the usual rectangular + polar coords



Express w in terms of x, y

\downarrow x, θ

$$w = \frac{1}{2} x y \checkmark$$

$$\tan \theta = \frac{y}{x}$$

$$y = x \tan \theta \checkmark$$

Calc $\left(\frac{\partial w}{\partial x}\right)_\theta$ $\left(\frac{\partial w}{\partial \theta}\right)_x$ in 3 ways

a) Directly \rightarrow express w in terms of x and θ

$$w = \frac{1}{2} x (x \tan \theta)$$
$$= \frac{1}{2} x^2 \tan \theta$$

$$\left(\frac{\partial w}{\partial x}\right)_\theta = \frac{1}{2} \cdot 2x \cdot \tan \theta$$

\uparrow diff x
 $\theta = \text{constant}$

$$= x \tan \theta \checkmark$$

$y = \left(\frac{\partial y}{\partial x}\right)_\theta$ is not
true so no problems

$$\left(\frac{\partial w}{\partial \theta}\right)_x = \frac{1}{2} \cdot x \cdot \sec^2 \theta \cdot x^2$$
$$= \frac{1}{2} \sec^2 \theta \cdot x^2$$

$\textcircled{-0.5}$

b By using chain rule

$$\text{example } \left(\frac{\partial w}{\partial x}\right)_\theta = w_x \left(\frac{\partial x}{\partial x}\right)_\theta + w_y \left(\frac{\partial y}{\partial x}\right)_\theta$$

↑ formal ↑ partial deriv
isn't this!

so are the 2 rules $w = \frac{1}{2}xy$
 $\tan\theta = \frac{y}{x} \rightarrow y = x \tan\theta$

$$\left(\frac{\partial w}{\partial x}\right)_\theta = \frac{1}{2} \cdot 1 \cdot \left(\frac{\partial y}{\partial x}\right)_\theta$$

$$\left(\frac{\partial y}{\partial x}\right)_\theta = 1 \cdot \tan\theta + 0 \cdot x$$

$$\left(\frac{\partial w}{\partial x}\right)_\theta = \frac{1}{2} \cdot \tan\theta$$
$$= \frac{\tan\theta}{2}$$

-1.5

x

does not =

$$\left(\frac{\partial w}{\partial \theta}\right)_x$$

now I see
a little clearer

$$\left(\frac{\partial W}{\partial \theta}\right)_x = \text{wait } \theta \text{ is not in original eq}$$

- i does not matter

$$\frac{1}{2} \cdot x \left(\frac{\partial v}{\partial \theta}\right)_x$$

constant τ replace w

$$\theta = \tan^{-1}\left(\frac{v}{x}\right)$$

$$\left(\frac{\partial v}{\partial \theta}\right)_x = 0$$

0

e? again what's wrong

c) differentials

I actually like this better

$$dw = \frac{1}{2} dx dy \quad dy = dx d\theta$$

← ? what is wrong

$$dw = \frac{1}{2} dx (dx d\theta)$$

↓ ↓ ↓ ? some different again

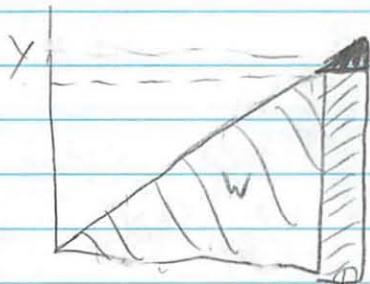
Should really get this - what is missing in

-1.5

d Using the triangular picture and geometric intuition estimate $\left(\frac{\Delta w}{\Delta x}\right)_\theta$ and $\left(\frac{\Delta w}{\Delta \theta}\right)_x$

Show that agree w/ earlier results

office
hrs
Oliver



make x vary
keep θ fixed

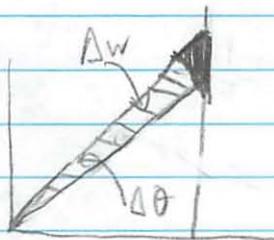
$$\Delta w \approx y \Delta x + \frac{\Delta x \Delta y}{2}$$

\rightarrow y is not changing $\left\{ \begin{array}{l} \text{small triangle} \\ \text{on top} \\ \text{small 2nd order} \end{array} \right.$

$$\frac{\Delta w}{\Delta x} = y + \frac{\Delta y}{2}$$

$$\hookrightarrow y = \left(\frac{\Delta w}{\Delta x}\right)_\theta \quad \checkmark$$

ii)

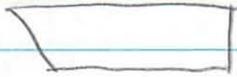


$$\Delta w = \frac{r^2}{2} \Delta \theta + \text{shape at end}$$

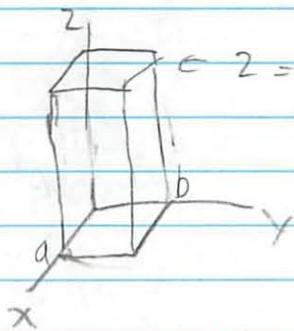
$\hookrightarrow x$ held constant \checkmark

2. Rectangular prism

but all 4 different



Show using double integration that volume is product of cross sectional area and average of all 4 edge lengths



$$z = Ax + By + C$$

but only 2 edges ? ? ?

so $\int \int dy dx$

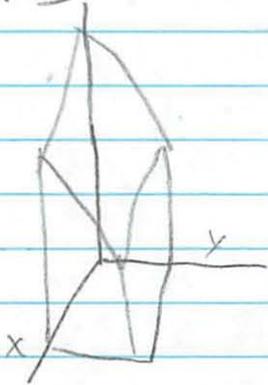
$$\int_0^a \int_0^b dy dx$$

$$\int_0^a \int_0^b (Ax + By + C) dy dx \checkmark$$

of the region!

continued in method 2
→

Method 1



office
hrs
oliver

know x, y
plug in know height

$$\frac{C + aA + C + aA + bB + C + bB + C}{4}$$

average

$$C + \frac{1}{2}aA + \frac{1}{2}bB \quad \downarrow \text{reduces to}$$

$$\text{Method 1} \quad \text{Vol} = ab \left(C + \frac{aA}{2} + \frac{bB}{2} \right)$$

self

Method 2

$$\int_0^a \int_0^b Ax + By + C \, dy \, dx$$

$$Axy + B \frac{y^2}{2} + Cy \Big|_0^b$$

$$\int_0^a Ax b + B \frac{b^2}{2} + Cb \, dx$$

$$A \frac{bx^2}{2} + \frac{Bb^2}{2}x + Cbx \Big|_0^a$$

$$A \frac{ba^2}{2} + \frac{Bb^2}{2}a + Cba \quad \checkmark$$

$$\text{Vol} = ab \left(A \frac{a}{2} + B \frac{b}{2} + C \right) \quad \textcircled{D} \text{ Same}$$

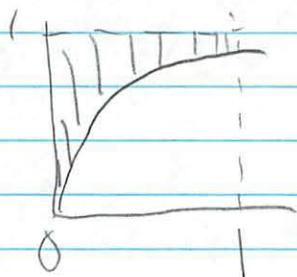
cool how this
works out

3. Evaluate by changing order of integration

will do after
wed recitation
- when practice
it more

$$\int_0^1 \int_{\sqrt[3]{x}}^1 \sqrt{1+y^4} dy dx$$

So need to draw pic of what limit is



$$\sqrt[3]{x} = y$$

$$x = y^3$$

don't function
- right???

$$\int_0^1 \int_0^{y^3} \sqrt{1+y^4} dx dy \quad \checkmark$$

$$\int_0^1 y^3 \sqrt{1+y^4} dx$$

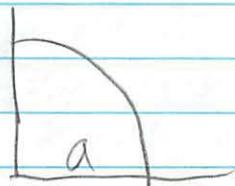
$$x \sqrt{1+y^4} \Big|_0^{y^3}$$

$$\int_0^1 y^3 \sqrt{1+y^4} dy \quad \checkmark$$

$$\frac{[y^4+1]^{3/2}}{6} \Big|_0^1 \quad \checkmark$$

$$\frac{(1^4+1)^{3/2}}{6} = \frac{\sqrt{2}}{3} \quad \checkmark$$

4. Quarter of cylindrical log



veg shaped piece removed



volume of that piece

Find Volume of piece w/ 2x integration

Check by finding volume when $a = \frac{\pi}{4}$

volume \rightarrow below graph of function

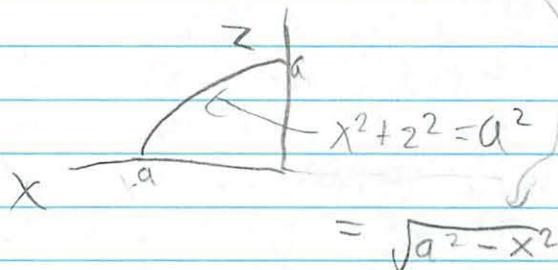
$$= \iint_R f \, dx \, dy$$



triangle on bottom

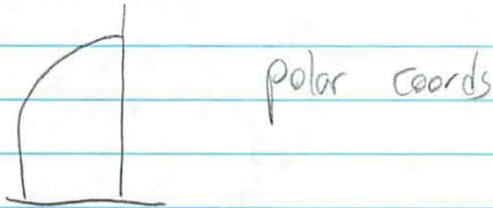
$f(x, y) =$ quarter of circle
 $= z$

$=$ cylinder around y -axis
 radius a



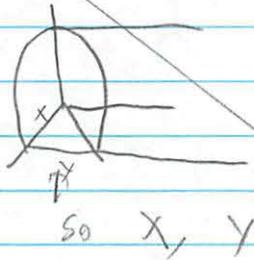
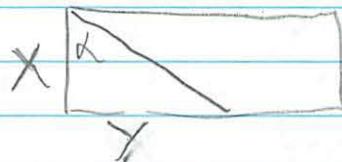
office hrs
 oliver

so the base is that end of the log (it's so much
 easier than I first thought)



$$\int_{\frac{\pi}{2}}^{2\pi} \int_0^a f(x,y) r dr d\theta$$

we have to find a function
 for the slice



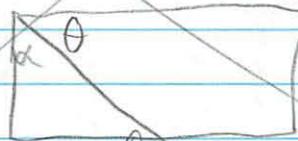
$$\tan \alpha = \frac{y}{x}$$

from triangle

- but this is polar

$$y = x \tan \alpha$$

$$x = \frac{y}{\tan \alpha}$$

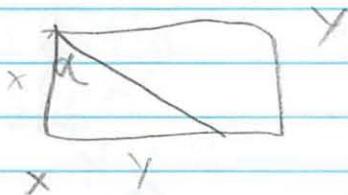


note r length = $x^2 + y^2$

$$\int_{\frac{\pi}{2}}^{2\pi}$$

Don't want boundaries

want plane equation!



What is equation of a plane
- normal vector

$$\text{So } \swarrow \quad x\hat{i} + y\hat{j}$$

$$\text{So } -y\hat{i} + x\hat{j}$$

$$\text{Plane eq. } -yA + xB$$

$$-x \tan \alpha + xB$$

$$\text{or } x = r \cos \theta$$

$$y = r \sin \theta$$

$$-r \sin \theta \tan \alpha + r \cos \theta$$

$$\int_{\frac{\pi}{2}}^{\frac{3\pi}{4}} \int_0^a -r \sin \theta \tan \alpha + r \cos \theta \cdot r \, dr \, d\theta$$

$$\int_0^a -r^2 \sin \theta \tan \alpha + r^2 \cos \theta \, dr$$

$$\frac{r^3 (\cos \theta \cos \alpha - \sin \theta \sin \alpha)}{3 \cos \alpha} \Big|_0^a$$

$$\int_{\frac{\pi}{2}}^{\frac{3\pi}{4}} \frac{a^3 (\cos \theta \cos \alpha - \sin \theta \sin \alpha)}{3 \cos \alpha}$$

$$\frac{a^3 (\cos \theta \sin \alpha + \sin \theta \cos \alpha)}{3 \cos \alpha} \Big|_{\frac{\pi}{2}}^{\frac{3\pi}{4}}$$

have calc to bounds \downarrow

$$\frac{a^3 \left((\sqrt{2}-2) \cos \alpha - \sqrt{2} \sin \alpha \right)}{6 \cos \alpha} \quad \times$$

So volume when $\alpha = \pi/4$

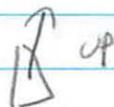
$$\text{Volume} = -\frac{a^3}{3}$$

$(\alpha = \frac{\pi}{4})$

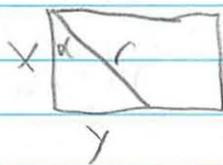
\uparrow why is volume \ominus ?

Vol tetrahedron

$$= \frac{1}{3} (\text{area base}) \cdot \text{height}$$

\uparrow
so we are going to do 

area base =



so if $\alpha = \frac{\pi}{4}$

$$\tan \frac{\pi}{4} = \frac{y}{x} = 1 \text{ so } \frac{1}{1}$$

$$\frac{1}{3} \cdot \left(\frac{1}{2} \cdot 1 \cdot 1 \right) \cdot a$$

$$\frac{a}{6} \quad \leftarrow \text{half my answer}$$

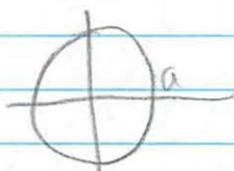
\checkmark

\ominus

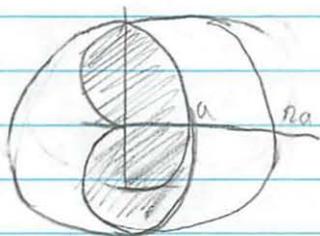
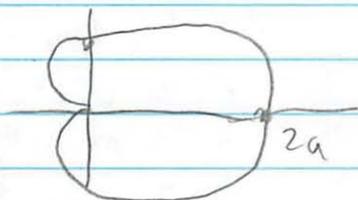
5a Exercise 20.4/9

Use double integrals + polar coords

The region inside the cardioid $r = a(1 + \cos \theta)$
and outside circle $r = a$



areas
not volumes!



↑ so that is the only area that matters



↑ just cardioid
↑ just half circle

$$\int_{-\pi/4}^{\pi/4} \int_0^a r \, dr \, d\theta + \int_{\pi/4}^{3\pi/4} \int_0^{a(1+\cos\theta)} r \, dr \, d\theta$$

↑ it's that for finding area of a circle
its when to use what that is confusing

Actually cartoid in back

$$= 2 \int_0^{\pi} \int_0^{a(1+\cos\theta)} r \, dr \, d\theta$$

$$= 2 \int_0^{\pi} \left[\frac{1}{2} r^2 \right]_0^{a(1+\cos\theta)} d\theta$$

$$= 2 \int_0^{\pi} \frac{1}{2} a^2 (1+\cos\theta)^2 d\theta$$

$$= a^2 \int_0^{\pi} (1+2\cos\theta+\cos^2\theta)$$

actually finding

but nothing there

$$\text{So } \int_{-\pi/4}^{\pi/4} \int_0^a r \, dr \, d\theta + \int_{\pi/4}^{3\pi/4} \int_0^{a(1+\cos\theta)} r \, dr \, d\theta$$

keep it like this - now need to actually do it

$$\begin{aligned} & \int_{-\pi/4}^{\pi/4} a^2 d\theta + \int_{\pi/4}^{3\pi/4} [a(1+\cos\theta)]^2 \\ & a^2 \theta \Big|_{-\pi/4}^{\pi/4} + a^2 \sin^2\theta \Big|_{\pi/4}^{3\pi/4} \\ & a^2 \frac{\pi}{4} + a^2 \frac{\pi}{4} + \frac{\pi}{2} \end{aligned}$$

$$\frac{\pi}{2} a^2 + \frac{\pi}{2} \times (-2)$$

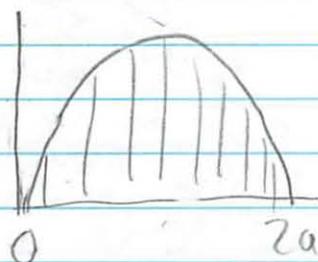
5b 20.4 #15

Evaluate by changing to polar

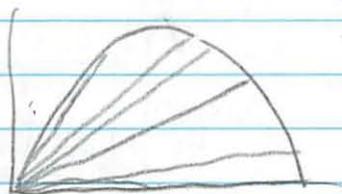
$$\int_0^{2a} \int_0^{\sqrt{2ax-x^2}} (x^2+y^2) dy dx$$

$$x = r \cos \theta$$
$$y = r \sin \theta$$

↑
vertical
|||



$$r^2 \cos^2 \theta + r^2 \sin^2 \theta$$
$$r^2 (1)$$
$$r^2$$

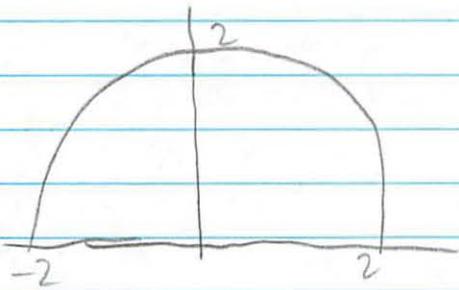


$$\int_0^{\pi/2} \int_0^{\sqrt{2a(r \cos \theta) - r^2 \cos^2 \theta}} r^2 r dr d\theta$$

$$\int_0^{\pi/2} \int_0^{\sqrt{2a(r \cos \theta) - r^2 \cos^2 \theta}} r^3 dr d\theta$$

$$\int_0^{\pi/2} \int_0^{\sqrt{2ar \cos \theta - r^2 \cos^2 \theta}} r^3 dr d\theta$$

office
hrs
oliver
results



$$r^2 - 2ar \cos \theta = 0$$
$$r = 2a \cos \theta$$

$$\int_0^{\pi/2} \int_0^{2a \cos \theta}$$

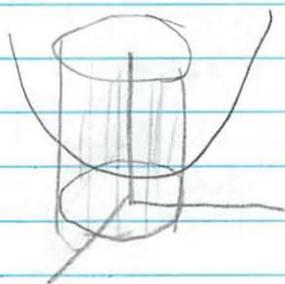
- but how does this fit w/ what I found
made me more confused! :c

-2

sc 20.4 #31a

For the solid bounded by the xy plane, the cylinder $x^2 + y^2 = a^2$, the paraboloid $z = b(x^2 + y^2)$ with $b > 0$. Find the volume

officer's
Oliver



$$x^2 + y^2 = a^2$$

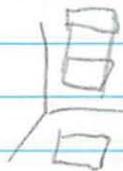
$$z = b(x^2 + y^2)$$

↑ paraboloid in cylinder
at some point it will cut it
want volume inside

$$\text{Vol} = \iint_R f(x, y) \, dx \, dy$$

↑ is the paraboloid
↑ is a circle/disk

if it was raised up



just subtract it out

$$\int_0^{2\pi} \int_0^a$$

$$b(x^2 + y^2) \, r \, dr \, d\theta$$

could also do in rectangular

Self

Do I have to convert

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$\int_0^{2\pi} \int_0^a b (r^2 \cos^2 \theta + r^2 \sin^2 \theta)$$

$$\int_0^{2\pi} \int_0^a b r^2 r dr d\theta$$

$$\int_0^a b r^3 dr d\theta$$

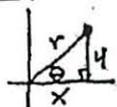
$$b \frac{r^4}{4} \Big|_0^a$$

$$\int_0^{2\pi} b \frac{a^4}{4} d\theta$$

$$b \frac{a^4 \theta}{4} \Big|_0^{2\pi}$$

$$\text{Volume} = \boxed{\frac{2\pi a^4 b}{4}} \checkmark$$

1) a) $w = \frac{1}{2}xy, \quad y = x \tan \theta$



a) using x, θ as ind. vars:

$$w = \frac{1}{2}x^2 \tan \theta$$

$$\left(\frac{\partial w}{\partial x}\right)_\theta = x \tan \theta, \quad \left(\frac{\partial w}{\partial \theta}\right)_x = \frac{1}{2}x^2 \sec^2 \theta$$

$$(\text{= } y) \quad (\text{= } \frac{1}{2}r^2)$$

b) $\left(\frac{\partial w}{\partial x}\right)_\theta = w_x + w_y \left(\frac{\partial y}{\partial x}\right)_\theta$

$$= \frac{1}{2}y + \frac{1}{2}x \cdot \tan \theta = \begin{cases} y \\ x \tan \theta \end{cases}$$

$$\left(\frac{\partial w}{\partial \theta}\right)_x = w_x \left(\frac{\partial x}{\partial \theta}\right)_x + w_y \left(\frac{\partial y}{\partial \theta}\right)_x$$

$$= \frac{1}{2}x \cdot x \sec^2 \theta = \begin{cases} \frac{1}{2}x^2 \sec^2 \theta \\ \frac{1}{2}r^2 \end{cases}$$

c) $dw = \frac{1}{2}y dx + \frac{1}{2}x dy$

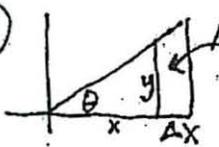
$$dy = \tan \theta \cdot dx + x \sec^2 \theta d\theta$$

Eliminating dy :

$$dw = \left(\frac{1}{2}y dx\right) + \frac{1}{2}x \left(\tan \theta \cdot dx + x \sec^2 \theta \cdot d\theta\right)$$

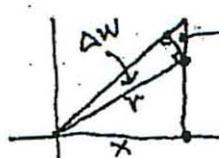
$$= \frac{1}{2}(y + x \tan \theta) dx + \frac{1}{2}(x^2 \sec^2 \theta) d\theta$$

coefficients are $\left(\frac{\partial w}{\partial x}\right)_\theta$ and $\left(\frac{\partial w}{\partial \theta}\right)_x$

d)  $\Delta w \approx y \Delta x$

$$\therefore \frac{\Delta w}{\Delta x} \approx y = \left(\frac{\partial w}{\partial x}\right)_\theta$$

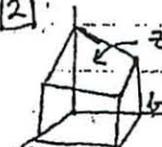
(θ held constant)

 arc is $r \Delta \theta$

$$\therefore \Delta w \approx \frac{1}{2}r \cdot r \Delta \theta$$

$$\frac{\Delta w}{\Delta \theta} \approx \frac{1}{2}r^2 = \left(\frac{\partial w}{\partial \theta}\right)_x$$

(x held constant)

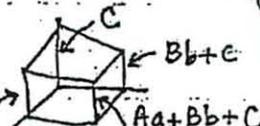
2)  $z = Ax + By + C$

$$\text{vol} = \int_0^a \int_0^b (Ax + By + C) dy dx$$

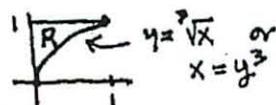
Inner: $Axy + \frac{By^2}{2} + Cy \Big|_0^b = Abx + \frac{Bb^2}{2} + Cb$

Outer: $Abx \Big|_0^a + \left(\frac{Bb^2}{2} + Cb\right)x \Big|_0^a = \frac{Aba^2}{2} + \left(\frac{Bb^2}{2} + Cb\right)a$

volume = $ab \left(\frac{Aa}{2} + \frac{Bb}{2} + C\right)$ $\left(\frac{Bb^2}{2} + Cb\right)a$

lengths of 4 edges: 

Quantity in parentheses \otimes
= (sum of four edges) / 4

3) The region is  $y = \sqrt{x}$ or $x = y^2$

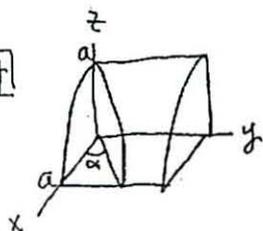
Making slices in the horizontal direction:

 $\int_0^1 \int_0^{y^2} \sqrt{1+y^4} dx dy$

inner integral: $\int_0^{y^2} \sqrt{1+y^4} dx = (1+y^4)^{1/2} x \Big|_0^{y^2} = y^3(1+y^4)^{1/2}$

outer integral: $\int_0^1 y^3(1+y^4)^{1/2} dy = \frac{1}{5}(1+y^4)^{3/2} \Big|_0^1 = \frac{1}{5}[2\sqrt{2} - 1]$

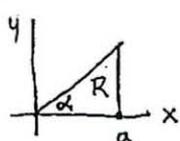
4



The equation of the cylindrical top surface is $x^2 + z^2 = a^2$

or $z = \sqrt{a^2 - x^2}$

Region in the xy-plane is



the line is $y = x \tan \alpha$

$$\begin{aligned} \therefore V &= \iint_R \sqrt{a^2 - x^2} dy dx \\ &= \int_0^a \int_0^{x \tan \alpha} \sqrt{a^2 - x^2} dy dx \end{aligned}$$

$$\begin{aligned} \text{Inner integral} &= \sqrt{a^2 - x^2} y \Big|_0^{x \tan \alpha} \\ &= x \sqrt{a^2 - x^2} \cdot \tan \alpha \end{aligned}$$

$$\begin{aligned} \text{Outer integral:} \\ &= \tan \alpha \cdot \int_0^a x (a^2 - x^2)^{1/2} dx \\ &= \tan \alpha \cdot \left[-\frac{1}{3} (a^2 - x^2)^{3/2} \right]_0^a \\ &= \frac{\tan \alpha}{3} \cdot a^3 \end{aligned}$$

If $\alpha = \pi/4$, $\tan \alpha = 1$,
Volume = $a^3/3$

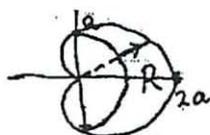
Volume of tetrahedron with height a & base a



$$\begin{aligned} &= \frac{1}{3} \text{ base} \cdot \text{height} \\ &= \frac{1}{3} \cdot \frac{a^2}{2} \cdot a = \frac{a^3}{6} \text{, half the volume.} \end{aligned}$$

5 a) 20.4/9

By symmetry,



center R where $r = a$, leaves where $r = a(1 + \cos \theta)$

$$\frac{1}{2} \text{ area } R = \int_0^{\pi/2} \int_a^{a(1+\cos \theta)} r dr d\theta$$

$$\text{Inner: } \left[\frac{r^2}{2} \right]_a^{a(1+\cos \theta)}$$

$$= \frac{a^2}{2} [(1 + \cos \theta)^2 - 1]$$

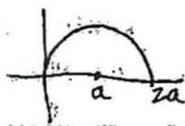
$$= \frac{a^2}{2} [2 \cos \theta + \cos^2 \theta]$$

$$\begin{aligned} \text{Outer: } &\frac{a^2}{2} \int_0^{\pi/2} (2 \cos \theta + \cos^2 \theta) d\theta = \frac{a^2}{2} \left[2 \sin \theta + \frac{\theta}{2} + \frac{\sin 2\theta}{4} \right]_0^{\pi/2} \\ &= \frac{a^2}{2} \left[2 + \frac{\pi}{4} + 0 \right] \end{aligned}$$

$\therefore \text{area } R = a^2 \left(2 + \frac{\pi}{4} \right)$
(double the above)

b) 20.4/15

$$\int_0^{2a} \int_0^{\sqrt{2ax-x^2}} (x^2 + y^2) dy dx$$



$y = \sqrt{2ax - x^2}$ is

$$y^2 + x^2 = 2ax$$

(completing the square) or $y^2 + (x-a)^2 = a^2$
upper circle shown

Polar eqn is $r = 2a \cos \theta$



\therefore integral becomes

$$\int_0^{\pi/2} \int_0^{2a \cos \theta} r^2 \cdot r dr d\theta$$

$$\text{Inner: } \left[\frac{r^4}{4} \right]_0^{2a \cos \theta} = 4a^4 \cos^4 \theta$$

$$\begin{aligned} \text{Outer: } &4a^4 \int_0^{\pi/2} \cos^4 \theta d\theta = 4a^4 \cdot \frac{3 \cdot 1 \cdot \pi}{4 \cdot 2 \cdot 2} \\ &= \frac{3\pi}{4} a^4 \end{aligned}$$

c) 20.4/31a

$x^2 + y^2 = r^2$; in polar coords:



$$\int_0^{2\pi} \int_0^a b r^2 \cdot r dr d\theta$$

$$\text{inner: } \left[\frac{b r^4}{4} \right]_0^a = \frac{b a^4}{4}$$

$$\text{outer: } 2\pi \cdot \frac{b a^4}{4} = \frac{\pi b a^4}{2}$$

Lecture 18

3/18

Changing variables in a double SS

$$\text{Ex } \iint_R f(x, y) dy dx$$

polar	$x = r \cos \theta$	$r = \sqrt{x^2 + y^2}$
	$y = r \sin \theta$	$\theta = \arctan \frac{y}{x}$

change limits } $r dr d\theta$ } sometimes use or sometimes other
 } integrand } direct substitution

Must practice!

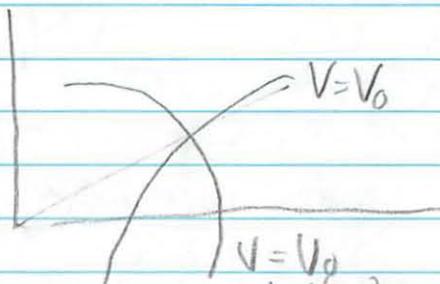
$$\iint_A f(x, y) dA$$

$$x = x(u, v)$$
$$y = y(u, v)$$

in $u-v$ coordinates (like polar coords)

look for grid lines
(unit curves)

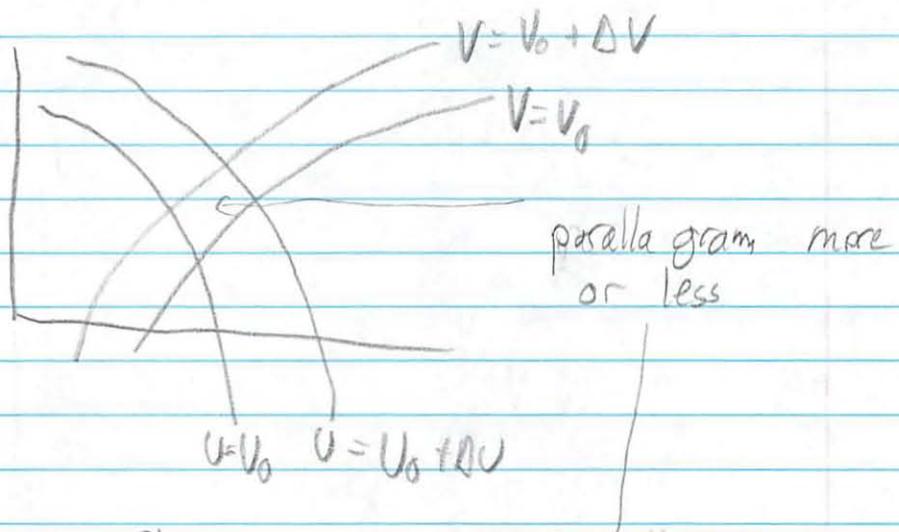
$$u = u_0 = c_1$$
$$v = v_0 = c_2$$



don't have to be \perp to each other
makes integral nicer

Find expression for typical little piece

- harder for this system



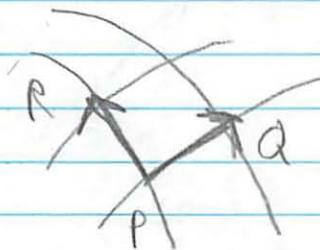
How to find area of a parallelogram



$$\text{area} \approx \pm \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$$

- so draw the vectors

- and find out what they are explicitly in terms of \hat{i} and \hat{j} system



$$\vec{PQ} = \begin{matrix} a \\ \Delta y \end{matrix} = -\Delta x \hat{i} + \Delta y \hat{j}$$

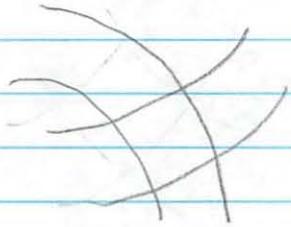
$$\Delta x \approx x_u \Delta U + x_v \Delta V$$

↑
moved along level
of curve Δ change

$$\Delta y \approx y_u \Delta U + y_v \Delta V$$

$$\vec{PQ} = (x_u \hat{i} + y_u \hat{j}) \Delta u \quad \leftarrow \text{moving along } v=v_0$$

$$\vec{PR} = (x_v \hat{i} + y_v \hat{j}) \Delta v \quad \leftarrow \text{moving along } u=u_0$$



$$\Delta A \approx \begin{vmatrix} x_u & y_u \\ x_v & y_v \end{vmatrix} \Delta u \Delta v$$

its always written as transpose

$$dA = \Delta A \approx \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} du dv$$

↑ called The Jacobian

$$\frac{\partial(x,y)}{\partial(u,v)} \quad \leftarrow \text{scalar function}$$

just the matrix = The Jacobian Matrix

$$\begin{bmatrix} \frac{\partial(x,y)}{\partial(u,v)} \end{bmatrix}$$



So warm
Feels like last
day vacation

Polar Coordinates

$$J = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix}$$

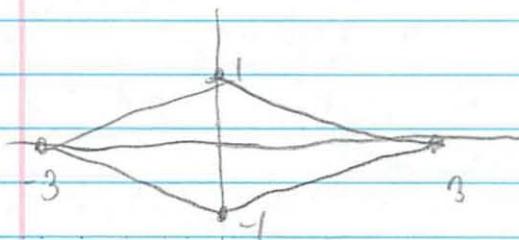
$$\cos \theta \cdot r \cos \theta - (-r \sin \theta \cdot \sin \theta)$$
$$r \cos^2 \theta + r \sin^2 \theta$$

So that is why it is $r dr d\theta$

example + Putting in Limits

$$\iint_R (x^2 - 9y^2)^4 dy dx$$

split



$$x^2 - 9y^2 = (x - 3y)(x + 3y)$$

\uparrow \downarrow \uparrow \downarrow telling us

Normally region has something to do w/

$$\iint U^4 V^4$$

\uparrow must calc Jacobian

$$\frac{\partial(x,y)}{\partial(u,v)}$$

$$U = x + 3y$$

$$V = x - 3y$$

neave; solve for x, y calc in usual way

Shortcut instead

$$\frac{\partial(x,y)}{\partial(u,v)} \cdot \frac{\partial(u,v)}{\partial(x,y)} = 1$$

$$\begin{vmatrix} 1 & 3 \\ 1 & -3 \end{vmatrix}$$

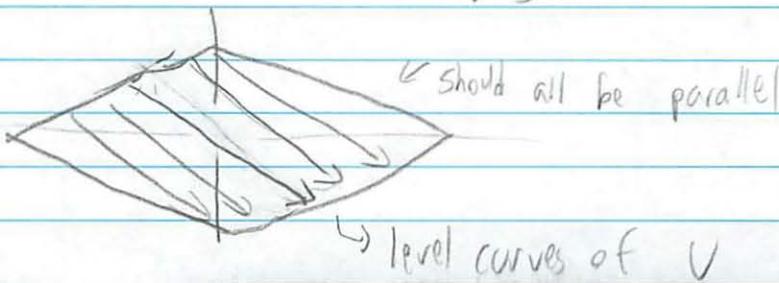
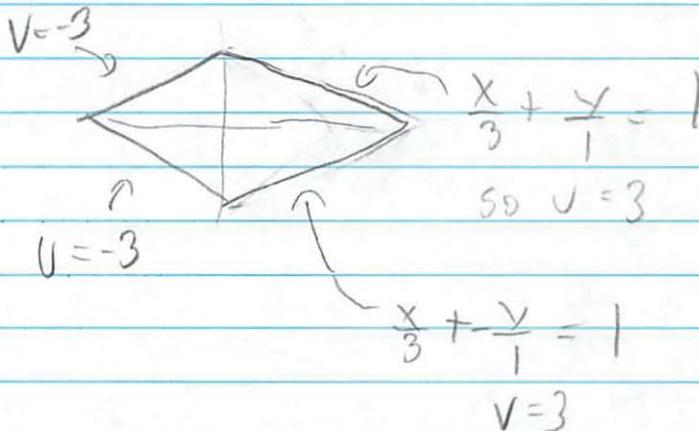
$$\begin{matrix} -3 & -3 \\ -6 \end{matrix}$$

So that must be $-\frac{1}{6}$

What we actually want

(sometimes \ominus , but area always \oplus)
so abs value

$$\iint u^4 v^4 \cdot \underbrace{\frac{1}{6}}_{dA} dv du$$



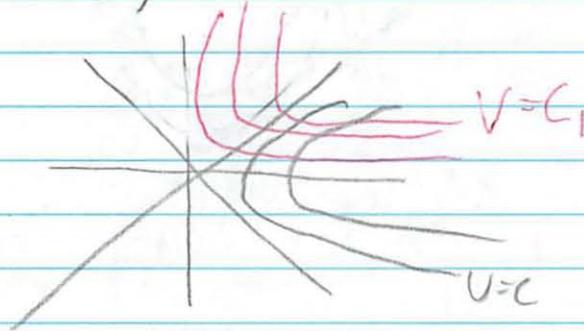
$$\int_{-3}^3 \int_{-3}^3 u^4 v^4 \cdot \frac{1}{6} du dv$$

(can evaluate it yourself)

ex 2

$$u = x^2 - y^2$$

$$v = xy$$



$$J = \frac{\partial(x, y)}{\partial(u, v)} \text{ need}$$

$$J^{-1} = \begin{vmatrix} 2x & -2y \\ y & x \end{vmatrix}$$

$$= 2(x^2 + y^2)$$

$$= \frac{1}{2(x^2 + y^2)}$$

when plug in 'integral'
in terms of x and y

can get lucky + be able to solve

$$U^2 = x^4 + y^4 - 2x^2y^2$$

$$V^2 = x^2y^2$$

$$(x^2 + y^2)^2 = U^2 + 4V^2$$

$$\frac{1}{2(x^2 + y^2)} = \frac{1}{2\sqrt{U^2 + 4V^2}}$$

Notes Section CV

3/28

Sometime easier to work in polar coords

$$r = \sqrt{x^2 + y^2} \quad x = r \cos \theta$$
$$\theta = \tan^{-1} \left(\frac{y}{x} \right) \quad y = r \sin \theta$$

3 steps

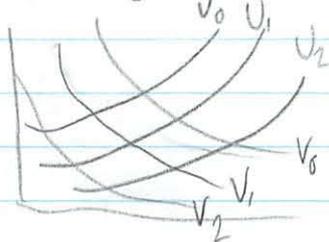
1. Change $f(x, y)$ to $g(r, \theta)$
2. Supply area element $dA = r dr d\theta$
3. Use region to look in limits of \int

Can also do for new coords UV

$$U = U(x, y) \quad x = x(u, v)$$
$$V = V(x, y) \quad y = y(u, v)$$

↑ both directions
usually use one

Make a grid



for step 2 need a determinant called
The Jacobian

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix}$$

So we get

$$dA = \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

So change of variable formula

$$\iint_R f(x, y) dx dy = \iint_R g(u, v) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

So they as an example show it works w/
polar

$$\frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} x_r & x_\theta \\ y_r & y_\theta \end{vmatrix} = \begin{vmatrix} \cos\theta & -r\sin\theta \\ \sin\theta & r\cos\theta \end{vmatrix}$$
$$= r(\cos^2\theta + \sin^2\theta) = r$$

What is this again??
partial deriv w/ respect to stuff

Ok lets start P-Set

Changing Limits

$$\iint_R f(x,y) dx dy = \iint_R g(u,v) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

$$g(u,v) = f(x(u,v), y(u,v))$$

$$x = x(u,v)$$

$$y = y(u,v)$$

$$\frac{\partial(x,y)}{\partial(u,v)} \cdot \frac{\partial(u,v)}{\partial(x,y)} = 1 \quad \leftarrow \text{Oh use this here}$$

\therefore I really don't get what it is trying to say

Example

$$\iint_R \frac{y}{x} dx dy \quad \begin{array}{l} x^2 - y^2 = 1 \\ x^2 - y^2 = 4 \end{array} \quad \begin{array}{l} y = 0 \\ y = \frac{x}{2} \end{array}$$

So this suggests $u = x^2 - y^2$

$$v = \frac{y}{x}$$

$$\frac{\partial(u,v)}{\partial(x,y)} = \begin{vmatrix} 2x & -2y \\ -\frac{y}{x^2} & \frac{1}{x} \end{vmatrix}$$

$$= 2 - 2 \frac{y^2}{x^2}$$

$$= 2 - 2v^2$$

$$\text{Flip } \frac{\partial(x,y)}{\partial(u,v)} = \frac{1}{2 - 2v^2} = \frac{1}{2(1-v^2)}$$

Use this eq to put in limits + evaluate

$$\iint_R f(x,y) dx dy = \iint_R g(u,v) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

$$\iint_R \frac{y}{x} dx dy = \iint \frac{v}{2(1-v^2)} du dv$$

$$\int_0^{1/2} \int_1^4 \frac{v}{2(1-v^2)} du dv$$

$$-\frac{3}{4} \ln(1-v^2) \Big|_0^{1/2}$$

$$-\frac{3}{4} \ln\left(\frac{3}{4}\right)$$

Lecture 19

Physical applications of double integrals

Makeup
3/27

Skipped lecture 3/19 due to Spring Break travel

Notes chap 20.3

$\iint_R f(x, y) dA$ gives volume of a
certain solid if $f(x, y) \geq 0$

The way we've seen before is volume

$$dV = f(x, y) dA$$

$$V = \iint_R f(x, y) dA$$

dA sweeps over the region and we add
up to the surface

We cut the quantity up into many small pieces
and add the pieces together

Mass

If $\delta = \delta(x, y)$ is density

$\delta(x, y) dA$ is the mass contained in the
element of dA

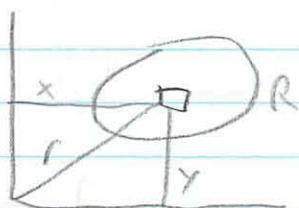
$$M = \iint_R \delta(x, y) dA$$

total mass of
plate

Moment

Moment of element of mass $\delta(x, y) dA$
w/ respect to the x -axis is multiplied
by the "lever arm" y namely $y\delta(x, y)dA$

$$M_x = \iint_R y \delta(x, y) dA$$



$$M_y = \iint_R x \delta(x, y) dA$$

Center of Mass

$$\bar{x} = \frac{M_y}{M} = \frac{\iint_R x \delta(x, y) dA}{\iint_R \delta(x, y) dA}$$

$$\bar{y} = \frac{M_x}{M} = \frac{\iint_R y \delta(x, y) dA}{\iint_R \delta(x, y) dA}$$

Where mass could be concentrated without
changing momentum, when density δ is constant,
the δ can be canceled away (since com
is the geometric center)

Moment of Inertia

When square of lever arm used get moment of inertia of plate around corresponding axis

$$I_x = \iint_R y^2 \delta(x,y) dA$$

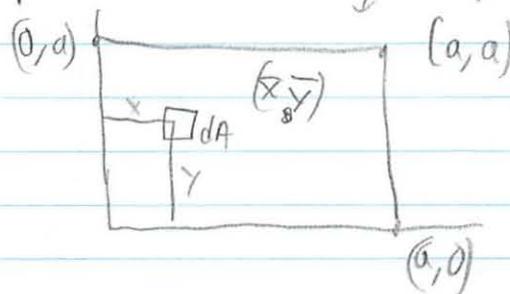
$$I_y = \iint_R x^2 \delta(x,y) dA$$

polar $\rightarrow I_z = \iint_R r^2 \delta(x,y) dA$

$$r^2 = x^2 + y^2$$

Moment of inertia = capacity to resist angular acceleration

Example



Thin plate of material

density $\delta = xy$

$$\begin{aligned} M &= \iint_R \delta dA \\ &= \int_0^a \int_0^a xy dy dx \\ &= \int_0^a \frac{1}{2} xy^2 \Big|_0^a dx \end{aligned}$$

$$= \frac{1}{2} a^2 \int_0^a x dx$$

$$= \frac{1}{4} a^4$$

$$\bar{x} = \frac{M_y}{M} = \frac{4}{a^4} \iint_R x \delta dA$$

$$= \frac{4}{a^4} \int_0^a \int_0^a x^2 y dy dx$$

$$= \frac{4}{a^4} \int_0^a \left[\frac{1}{2} x^2 y^2 \right]_0^a dx$$

$$= \frac{2}{a^2} \int_0^a x^2 dx$$

$$= \frac{2}{3} a$$

By symmetry $\bar{x} = \bar{y} = \frac{2}{3} a$

$$I_x = \iiint_R x^2 \delta dA$$

$$= \int_0^a \int_0^a x y^3 dy dx$$

$$= \int_0^a \left[\frac{1}{4} x y^4 \right] dx$$

$$= \frac{1}{4} a^4 \int_0^a x dx$$

$$= \frac{1}{8} a^6$$

And in terms of Mass

$$I_x = \frac{1}{2} Ma^2$$

Remarks

dA, dx, dy are not differentials

Euler's formula

$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$$

by doing a $2x$ integral

Alright let's see how P-set goes

Recitation

3/29

Lectures

Change of Variable $x, y \rightarrow u, v$

$$\iint_R f(x, y) \, dx \, dy = \iint_R f \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \, du \, dv$$

$$\text{def } \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} \leftarrow \text{determinant}$$

$$\text{Useful } \frac{\partial(x, y)}{\partial(u, v)} = \frac{1}{\frac{\partial(u, v)}{\partial(x, y)}}$$

$$\frac{\partial(x, y)}{\partial(r, \theta)} = r$$

Practical Applications

Averages of f over R

$$\frac{\iint_R f \, dx \, dy}{\iint_R dx \, dy} \leftarrow \text{area}$$

Mass of 2D object

$$M = \iint_R dm$$

Center of Mass
 (\bar{x}, \bar{y})

$$\bar{x} = \frac{1}{M} \iint_R x \, dA$$

Moment of inertia

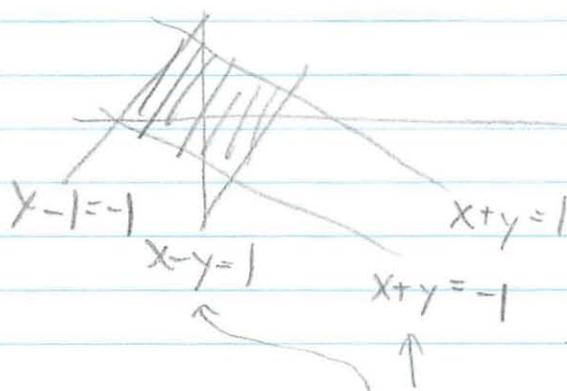
$$MI = \iint_D D^2 \, dM$$

where $D =$ distance to axis

$$dM = \underset{\substack{\uparrow \\ \text{small} \\ \text{mass}}}{\sigma} \underset{\substack{\uparrow \\ \text{density}}}{dA} = \underset{\substack{\uparrow \\ \text{small area}}}{\sigma} dx \, dy$$

ex 1

Compute $I = \iint_R (x+y) e^{x^2-y^2} dx \, dy$



Use change of variables

So $u = x+y$ * We picked this because
 $v = x-y$ area easily expressed
in terms of u and v

(Can we express $f(x,y)$ in terms of u and v)

$$f(x, y) = uv e^{uv}$$

$$\hookrightarrow \text{Remember } x^2 - y^2 = (x+y)(x-y) = uv$$

Now calculate Jacobian

$$\hookrightarrow \text{put use } \frac{\partial(x, y)}{\partial(u, v)} = \frac{1}{\frac{\partial(u, v)}{\partial(x, y)}}$$

$$= \frac{1}{\begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix}}$$

$$u_x = \frac{\partial u}{\partial x} \quad v_x = \frac{\partial v}{\partial x}$$

from $u = x + y$
 $v = x - y$

$$= \frac{1}{\begin{vmatrix} 1 & 1 \\ 1 & -1 \end{vmatrix}} = \frac{1}{-1 - 1} = -\frac{1}{2}$$

abs value = $\left(\frac{1}{2}\right)$

at this pt

$$I = \iint_R uv e^{uv} \frac{du dv}{2}$$

"prefix"

Now express domain
-hardest part

$$R = \begin{cases} -1 \leq x+y \leq 1 \\ -1 \leq x-y \leq 1 \end{cases} = \begin{cases} -1 \leq u \leq 1 \\ -1 \leq v \leq 1 \end{cases}$$

$$\int_{-1}^1 \int_{-1}^1 uv e^{uv} \frac{du dv}{2}$$

du dv order

- just choose something

- depends on form of domain - sometimes one is easier

Now actually calculate (quickly)

$$= \int_{-1}^1 \frac{e^{uv}}{2} \Big|_{-1}^1 du$$

$$= \int_{-1}^1 \frac{e^u - e^{-u}}{2} du$$

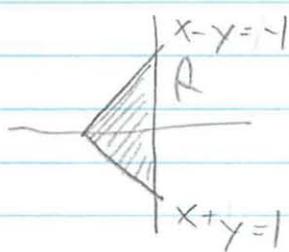
$$= \frac{e^u + e^{-u}}{2} \Big|_{-1}^1$$

$$= \frac{e^1 + e^{-1}}{2}$$

..... easy calculations

you will always be given a domain

b)



$$R \begin{cases} -1 \leq x+y \leq 1 \\ -1 \leq x-y \leq 1 \end{cases} \quad \text{??? hardest part}$$

well write

now express in u, v

$$\begin{cases} -1 \leq x+y \\ -1 \leq x-y \\ x \leq 0 \end{cases} \quad \begin{array}{l} \rightarrow -1 \leq u \\ \rightarrow -1 \leq v \\ \rightarrow \frac{u+v}{2} \leq 0 \end{array}$$

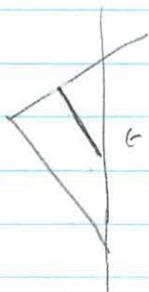
\Rightarrow

$$\frac{x+y+x-y}{2} = \frac{2x}{2} = x$$

\Rightarrow

(*) would never have thought of this!
Manipulate u and v so matches
the x and y you have (*)

$$\int_u \int_v u e^{uv} \frac{dv du}{2}$$



\leftarrow for a given v , what is the range of u

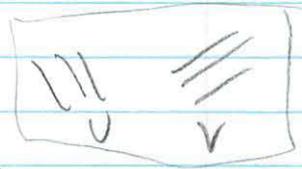
actually this part is fairly hard too

$$\int_{-1}^1 \int$$

v v
 \uparrow \uparrow constrained
 still the same depends on u

$$-1 \leq v \leq -u$$

~~same~~ same
 \uparrow its v that changes as u



is fixed

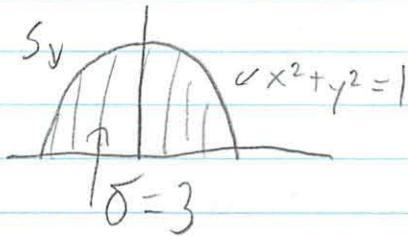
$$\int_{-1}^1 \int_{-1}^u v e^{uv} \frac{dr du}{2}$$

Now solve as usual.

ex 2

Compute Moment of Inertia of S

was awake till 3
 but awake now
 since got up at 10:50
 + pre fresh here
 makes it slide



a) around \hat{z} axis (at of board)

Want distance from axis 2

by definition

$$MI = \iint_R \rho^2 dm$$

$$D = r = \sqrt{x^2 + y^2}$$



Hint: Clearly polar coords

~~$$\int_0^\pi \int_0^r r \, dr \, d\theta$$~~

← almost had it

forgot density

did not write in function²
which is distance to axis²

$$\begin{aligned} dM &= \delta \, dx \, dy \\ &= 3r \, dr \, d\theta \end{aligned}$$

↑ don't forget density

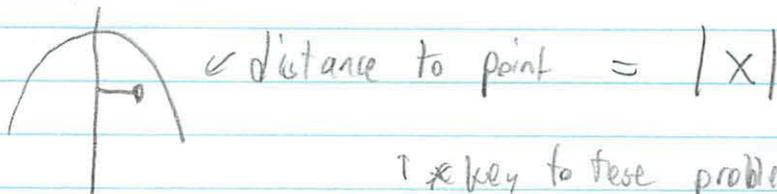
$$\iint_D r^2 \cdot 3r \, dr \, d\theta$$

$$\int_0^\pi \int_0^r 3r^3 \, dr \, d\theta$$

Calculate ... = $\frac{3}{4}\pi$

On weekend always
try to do everything
for week - of course
does not get done

b) around y axis



↑ key to these problems
did not realize

Can you simplify using symmetry?

$$MI = 2 \iint_{\substack{+ \\ y}} D^2 dM$$

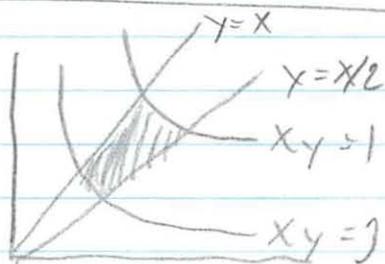

$$0 = |x| = r \cos \theta$$

in polar!

$$MI = 2 \int_0^{\pi/2} \int_0^1 (r \cos \theta)^2 \cdot 3r dr d\theta$$

Calculate ...

Ex 3



Find the average of function $F(x,y)$ over R

$$f(x,y) = (xy)^3$$

Change of variables

$$u = xy \quad \leftarrow \text{pick these}$$

$$v = \frac{x}{y}$$

- notice this is a good idea

- want to simplify

- notice can have $\frac{x}{y} = 1$ $\frac{x}{y} = 2$

$$\uparrow$$
$$y = \frac{x}{2}$$

Now have nice region

$$A = \begin{cases} 1 \leq u \leq 3 \\ 1 \leq v \leq 2 \end{cases}$$

Still need to do Jacobian, right?

$$\hookrightarrow \frac{\partial(u,v)}{\partial(x,y)} = \begin{vmatrix} \frac{y}{x} & \frac{x}{y^2} \\ \frac{y}{x} & -\frac{x}{y^2} \end{vmatrix} = -2 \frac{x}{y}$$

Now want, in terms of u and v

$$\text{so } -2 \frac{x}{y} = -2v$$

Recitation / Review

3/31

Practice for exam 2

Questions

Ex1. Let $f(x, y) = x^2y^2 + x^2 + y^2$.

- Find critical points of f and say whether they are local min, local max or saddle points.
- Find where the minimum and maximum of f are attained on the unit circle $x^2 + y^2 = 1$ using Lagrange multipliers.
- What are the minimum and maximum values of f in the unit disc $x^2 + y^2 \leq 1$?

Ex2. Let $f = w(x, y)$ satisfying $\nabla f(1, 2) = \langle 3, 1 \rangle$. Consider 2 new variables u, v .

- Express $\frac{\partial f}{\partial u}$ and $\frac{\partial f}{\partial v}$ at the point $(x, y) = (1, 2)$ in terms of x_u, x_v, y_u, y_v .
- Suppose $u = (x + y)/2$ and $v = (x - y)/2$. What are the values of $\frac{\partial f}{\partial u}$ and $\frac{\partial f}{\partial v}$ at $(x, y) = (1, 2)$?

Ex3. Find the volume above the graph $z = x^2 + y^2$ and below the plane $z = 4$.

Ex4. Evaluate $\int_0^1 \int_{x^2}^x e^y / (\sqrt{y} - y) dy dx$ by changing the order of integration.

Ex5. Let T be the triangle $(1, 0), (0, 1), (1, 1)$ with density $\delta = 1$.

- Find the center of mass.
- Find the moment of inertia around the x -axis.

Recitation

Review

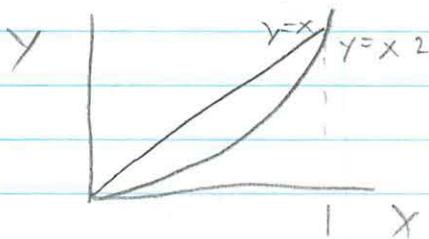
3/31

w/ question sheet

See sheet
ex 4

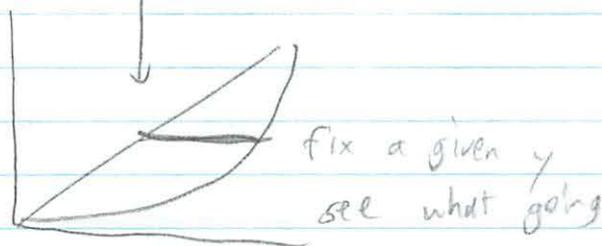
$$I = \int_0^1 \int_{x^2}^x \frac{e^y}{\sqrt{y-y}} dy dx$$

Step 1 Draw graph of givens



Now Reverse Limits

$$\int_{y=0}^1 \int_{x=0}^{\sqrt{y}} \frac{e^y}{\sqrt{y-y}} dx dy$$



$$\int_{y=0}^1 \int_{x=0}^{\sqrt{y}} \frac{e^y}{\sqrt{y-y}} dx dy$$

Now actually calculate

$$I = \int_0^1 \frac{e^y}{\sqrt{y-y}} (\sqrt{y-y}) dy$$

$$= \int_0^1 e^y dy$$

$$e^x \Big|_0^1$$

$$e - 1$$

ex2

a) Have $x, y \rightarrow$ want to go to new variables u, v

$$\frac{\partial f}{\partial u} = \text{"chain rule type thing"}$$

$$= x_u f_x + y_u f_y$$

$$\text{know } \nabla f(1,2) = \langle 3, 17 \rangle = \langle f_x, f_y \rangle$$

$$\frac{\partial f}{\partial u} = 3x_u + 17y_u$$

$$\text{Similarly } \frac{\partial f}{\partial v} = 3x_v + 17y_v$$

b) $u = \frac{x+y}{2} \quad v = \frac{x-y}{2}$

Solve for x, y

$$U + V = x$$

$$U - V = y$$

↓

$$\begin{array}{l} x_U = 1 \quad x_V = 1 \\ y_U = 1 \quad y_V = -1 \end{array}$$

$$\frac{\partial f}{\partial U} = 3 \cdot 1 + 1 \cdot 1 = 4$$

$$\frac{\partial f}{\partial V} = 3 \cdot 1 \cdot 1 \cdot -1 = -2$$

ex 1 Optimization Problem

- find min + max

$$f(x, y) = x^2 y^2 + x^2 + y^2$$

a) we know we want $f_x = 0$
 $f_y = 0$

$$\begin{aligned} f_x &= 2xy^2 + 2x = 2x(y^2 + 1) \\ f_y &= 2yx^2 + 2y = 2y(x^2 + 1) \end{aligned}$$

So set = to

$$\begin{aligned} 0 &= 2x(y^2 + 1) \\ 0 &= 2y(x^2 + 1) \end{aligned}$$

We know that

$$\begin{aligned} y^2 + 1 &\neq 0 \quad (\text{can never } = 0) \\ x^2 + 1 &\neq 0 \end{aligned}$$

So this means that

$$x = 0$$

$$y = 0$$

Only critical pt is $(x, y) = (0, 0)$

Now Concavity or Saddle Point?

$$f_{xx} f_{yy} - f_{xy}^2$$

$$f_{xx} = 2(y^2 + 1)$$

$$f_{yy} = 2(x^2 + 1)$$

$$f_{xy} = 4xy$$

← take deriv of (f_x) w/ respect to y

remember
this →

$$\begin{aligned} f_{xx} f_{yy} - f_{xy}^2 &= 4(y^2 + 1)(x^2 + 1) - (4xy)^2 \\ &= 4 \quad \text{at } (0, 0) \end{aligned}$$

↳ this is $(+)$ so look at f_{xx}
which is 2 at $(0, 0)$
 $(+)$ so local min

b) Let us denote $g(x,y) = x^2 + y^2 - 1$
 So that the constraint is $g(x,y) = 0$

La grange system

Remember this tool.

$$\begin{cases} f_x = \lambda g_x \\ f_y = \lambda g_y \\ x^2 + y^2 = 1 \end{cases}$$

$$\downarrow$$

$$\begin{cases} 2x(y^2 + 1) = \lambda 2x \\ 2y(x^2 + 1) = \lambda 2y \\ x^2 + y^2 = 1 \end{cases}$$

case	\sim
	$x \neq 0$
	$y \neq 0$

$$\begin{cases} y^2 + 1 = \lambda \\ x^2 + 1 = \lambda \\ x^2 + y^2 = 1 \end{cases}$$

Now try to solve these equations

$$\begin{cases} x^2 = \lambda - 1 \\ y^2 = \lambda - 1 \\ x^2 + y^2 = 2\lambda - 2 = 1 \end{cases}$$

$$\begin{cases} \lambda = \frac{3}{2} \\ x^2 = \frac{1}{2} \\ y^2 = \frac{1}{2} \end{cases}$$

(x, y) can be

$$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$
$$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$$
$$\begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$
$$\begin{pmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$$

Case 2 \downarrow
 $x=0$

$$2y = \lambda 2y$$
$$y^2 = 1$$

(x, y) can be

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$$
$$\begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

Case 3 \downarrow
 $y=0$

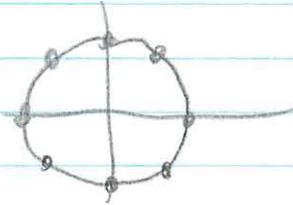
$$2x = \lambda 2x$$
$$x^2 = 1$$

I think he did not write

(x, y) can be

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
$$\begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

So 8 possible values



c)



Candidates are from part b

$f(0,0)$ is critical pt on domain

plug into original eq to compute

(x,y)	$f(x,y)$
$(0,0)$	0 is the minimum
$(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$	$\frac{\sqrt{2}}{4}$ is maximum
$(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}})$	$\frac{\sqrt{2}}{4}$
\vdots	
$(0,1)$	1
$(1,0)$	1

ex 5



need to memorize these formulas

a) center of mass

$$(\bar{x}, \bar{y})$$

$$\bar{x} = \frac{1}{M} \iint_T x \underbrace{\delta}_{dm} dx dy$$

Need to find mass first

$$M = \text{Area} \cdot \delta \quad (\text{since } \delta \text{ is constant})$$

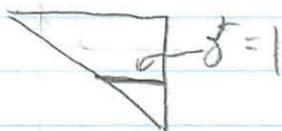
$\frac{1}{2} \cdot 1$
 $\frac{1}{2}$

otherwise would have to \int
(this is what I really need to
be clear on)

$$\iint_T x dx dy$$

$$\int_y \int_x x dx dy$$

look at limit & be able to set it



$$\int_0^1 \int_{1-y}^1 x dx dy$$

$$= \dots = \frac{1}{3}$$

$$\bar{x} = \frac{1}{\frac{1}{2}} \cdot \frac{1}{3} = \frac{2}{3}$$

$\bar{y} = \frac{2}{3}$ as well because of axis of symmetry



b) Compute Moment of Inertia

$$MI = \iint_T y^2 \delta \, dx \, dy$$

y^2 since $y =$ distance from y axis

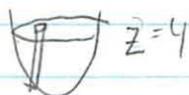
ex 3



← want volume inside domain

All of these you
seen kinda
familiar - but
can I do them
from scratch?
- prob not

$$Vol = \iint_R 4 - (x^2 + y^2) \, dx \, dy$$



What is the region?

Look from the top

$$x^2 + y^2 \leq z \leq 4$$

$$R: x^2 + y^2 \leq 4$$

↳ Disk of Radius 2

Michael Alasmolier

Oliver 12 PM

PT 24/25

PT 14.5/20

38.5/45

18.02 Problem Set 6A due Thurs. Apr. 8, 10:45 2-106

This problem set should be done before Exam 2, since the material will be included on the exam. It has Part I problems only, so you will have solutions available. Problem Set 6B will be given out Tuesday Mar. 30, with the later material not included in Exam 2. Hand in 6A and 6B stapled together, on Apr. 8.

Part I (10 points)

Lecture 18. Thurs. Mar. 18 Changing variables in a double integral.

Read: Notes CV.1-3 (through Example 3, top p. 5). Work: 3D-1,3,5,9.

(Hint for 3D-9, not solved in the Notes:

Since the equations (21) in Notes CV are obtained by solving (20) for u and v in terms of x and y , we can write

$$x(u(x, y), v(x, y)) = x, \quad y(u(x, y), v(x, y)) = y.$$

Now use the chain rule to find the partial derivatives of both sides of these two equations with respect to x , and also find their partial derivatives with respect to y . This gives four equations in all involving partial derivatives.

Show that these four equations can be expressed by a single matrix equation

$$\begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} \begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

(This is a good example of how matrices can be used to summarize and simplify a system of equations. The matrix on the left is called the *Jacobian matrix* of x and y with respect to u and v . There is no standard notation for it, but we will write it

$$\left[\frac{\partial(x, y)}{\partial(u, v)} \right] = \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix}$$

The determinant of the Jacobian matrix is called the *Jacobian* $\frac{\partial(x, y)}{\partial(u, v)}$ of x and y with respect to u and v . Note that the vertical lines are not used in the notation.)

Finally, finish the exercise, by using the determinant law for any two $n \times n$ matrices A and B : $|AB| = |A||B|$ as directed in the exercise.

Lecture 19. Fri. Mar. 19 Physical applications of double integration.

Read: 20.3 Work: 3C-1abc, 2ab, 4, 5 (cf. p. 565).

Spring Break

Lecture 20. Tues. Mar. 30 Vector fields and line integrals in 2D.

Read: Notes V1; Textbook: 21.1

Problem Set 6B given out in lecture and posted.

Exam 2. Thurs. April 1 11:05-11:55 Walker 3rd floor

The exam will cover Lectures 9 - 19 on Partial Differentiation and Double Integration. No books, notes, calculators; no use of cell-phones.

Practice Exam problems with solutions will be given out and posted Friday. Whatever formulas are given to you to use on the Practice Exam problems will also be given to you on the Exam 2 paper.

18.02

P-Set 6A

Michael Plasmeier

3/28

Lecture 18 Changing Variables w/ a double integral

30-1 Evaluate $\iint_R \frac{x-3y}{2x+y} dx dy$ where R is bounded by $y = -2x + 1$ $y = \frac{x}{3}$
 $y = -2x + 4$ $y = \frac{x-1}{3}$

$$u = x - 3y$$
$$v = 2x + y$$

Step 1 Convert function

$$dA = dA \approx \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} du dv$$

$$\begin{vmatrix} 1 & -3 \\ 2 & 1 \end{vmatrix}$$

Now opposit for some reason

since we want $\frac{\partial(x,y)}{\partial(u,v)}$ but we found $\frac{\partial(u,v)}{\partial(x,y)}$ which was easier to calc $\frac{1}{7}$ Step 2 Supply area element
Think I did that above

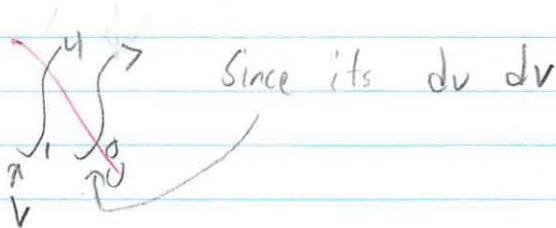
Step 3 Limits

So we had $u = x - 3y$
 $v = 2x + y$

$2x + y = 1$ so v from $1 \rightarrow 4$
 $2x + y = 4$

$x = 3y$ $0 = x - 3y$
 $x - 7 = 3y$ $7 = x - 3y$

so u from $0 \rightarrow 7$



Well they have $dv du$

$\frac{1}{7} \int_0^7 \int_1^4 \frac{u}{v} dv du$
 realize that's what it is
 modifier you find w/ jacobian

But why this order??

Did they just pick this arbitrarily
 -so you could switch and it
 would work just as well

111

Step 4 Solve
- just like before

$$\int_1^4 \frac{u}{v} dv$$

$$\int_1^4 u v^{-1} dv$$

$$u \ln v \Big|_1^4$$

$$u \ln 4 - (u \ln 1)$$
$$u (2 \ln 2)$$

$$\int_0^7 u (2 \ln 2) du$$

$$\frac{u^2 (2 \ln 2)}{2} \Big|_0^7$$

$$7^2 \ln 2 - 0^2 \ln 2$$

$$\frac{1}{2} \cdot (49 \ln 2)$$

$$7 \ln 2$$

don't forget prefix



3. Find the volume under the surface
 $z = 16 - x^2 - 4y^2$ and over the $x-y$ plane
simplify the integral w/ $u = x$
 $v = 2y$

$$\iint_R 16 - x^2 - 4y^2 \, dA$$

$$\iint 16 - u^2 - v^2 \, du \, dv$$

Limits $x = x$ $x = 0$

$y = y$ $y = 0$

n should figure out what this is, right?

No first is Jacobian

$$\frac{\partial(u,v)}{\partial(x,y)} = \begin{vmatrix} 1 & 0 \\ 0 & 2 \end{vmatrix} = 2$$

$$\text{so } \frac{\partial(x,y)}{\partial(u,v)} = \frac{1}{2} \quad \textcircled{1}$$

$$\frac{1}{2} \iint 16 - u^2 - v^2 \, du \, dv$$

R is elliptical region $x^2 + 4y^2 = 16$ in rect.
But in our coords

so I did get it

But next line

$$\frac{1}{2} \int_0^{2\pi} \int_0^4 (16-r^2) r \, dr \, d\theta$$

How in all world does it jump to this??
Why did they switch again to polar coords

Well it does make sense $x^2 + y^2 = 16$
which is a circle of radius 4
So I can see why it works
Did not know it was legal to switch twice

Now Solve

$$\int_0^4 (16-r^2) r \, dr$$

$$\int_0^4 16r - r^3 \, dr$$

$$\left. \frac{16r^2}{2} - \frac{r^4}{4} \right|_0^4$$

$$\frac{128 - 64}{64}$$

$$\int_0^{2\pi} 64 \, d\theta$$

$$\frac{640 \int_0^{2\pi}}{2} = \frac{1}{2} \cdot 128\pi$$

$$\frac{64\pi}{2} \quad \text{Don't forget the "prefix"}$$

✓

5, Set up the iterated integral for the polar moment of inertia of the finite "triangular" region R

$y = x$ $xy = 3$
 $y = 2x$

$$\iint_R r^2 dA$$

What is u, v ? Or should I change to r, θ ?

$$u = xy \quad y^2 = uv$$

$$v = \frac{y}{x} \quad x^2 = \frac{u}{v}$$

So first is the jacobian

$$\begin{vmatrix} 1 & 1 \\ \frac{1}{2} & 1 \end{vmatrix} = \frac{1}{2} \quad \text{flipped} = 2$$

well do w/ variables

$$\begin{vmatrix} \frac{y}{x} & x \\ -\frac{y}{x^2} & \frac{1}{x} \end{vmatrix} = \frac{2y}{x} = 2v \quad \rightarrow \text{flipped } \frac{1}{2v}$$

↑ convert

$$\iint_R (x^2 + y^2) dx dy =$$

how did
you know this
- was that the reference
to polar?

Now convert

$$\frac{1}{2v} \iint \frac{u}{v} + uv \, du dv$$

they do $dv du$

$$\frac{1}{2v} \iint_R \frac{u}{v} + uv \, dv du$$

so now for this

$$\text{we have } \begin{matrix} y = x & xy = 3 \\ y = 2x \end{matrix}$$

$$\text{so } v = 3 \rightarrow 0$$

$$v = 1 \rightarrow 2$$

$$\frac{1}{2v} \int_0^3 \int_1^2 \frac{u}{v} + uv \, dv du$$

slowly figuring out

Now solve

$$\int_1^2 \frac{v}{v} + uv \, dv$$

$$\int_1^2 uv^{-1} + uv \, dv$$

$$v \ln v + \frac{uv^2}{2} \Big|_1^2$$

$$v \ln(2) + v^2 - \left(v \ln(1) + \frac{1}{2}v \right)$$

$$v \left(\ln(2) - \ln(1) + \frac{3}{2} \right)$$

$$\int_0^3 v \left(\ln(2) + \frac{3}{2} \right) dv$$

$$v^2 \left(\ln(2) + \frac{3}{2} \right) \Big|_0^3$$

$$3^2 \left(\ln(2) + \frac{3}{2} \right)$$

$$\Rightarrow \frac{1}{2v} \left(9 \ln(2) + 13.5 \right)$$

No they have a simpler solution

$$\text{Inner } \frac{-v}{2v} + \frac{v}{2} v \Big|_1^2$$

$$v \left(-\frac{1}{4} + 1 + \frac{1}{2} - \frac{1}{2} \right) = \frac{3v}{4}$$

$$\text{outer } \frac{3}{8} v^2 \Big|_0^3$$

$$= \left(\frac{27}{8} \right)$$

✓

* and you don't
take prefix
out - must
integrate it *

9. Prove the relationship between Jacobians

$$\frac{\partial(x, y)}{\partial(u, v)} \cdot \frac{\partial(u, v)}{\partial(x, y)} = 1$$

Using the chain rule for partial differentiation
and the rules for multiplying determinants
 $|AB| = |A||B|$ where A and B are matrices
- of the same size

Hints from problem sheet

That equation is obtained by solving

$$x = x(u, v) \quad y = y(u, v)$$

So can write

$$\begin{pmatrix} x(u(x, y), v(x, y)) \\ y(u(x, y), v(x, y)) \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$$

Now use chain rule to find partial derivatives of both sides w/ respect to x and y

$$\frac{\partial}{\partial y} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{\partial x}{\partial y} \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{\partial x}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial x}{\partial v} \frac{\partial v}{\partial y} \\ \frac{\partial y}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial y}{\partial v} \frac{\partial v}{\partial y} \end{pmatrix}$$

I don't think that's what they want

Now they want you to express it in a single matrix equation

$$\begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} \begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

↑ Good example of how a matrix can be used to simplify a system of equations

↳ Jacobean matrix of x and y with respect to u and v

$$\frac{\partial (x, y)}{\partial (u, v)} = \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix}$$

Now finish by using determinant law for any 2 $n \times n$ matrices

$$|AB| = |A||B|$$

$$\det = x_u y_v - x_v y_u$$

$$(x_u y_v - x_v y_u)(u_x v_y - u_y v_x) = 1 - 0$$

$$x_u y_v \cdot u_x v_y - x_u y_v \cdot u_y v_x - x_v y_u u_x v_y +$$

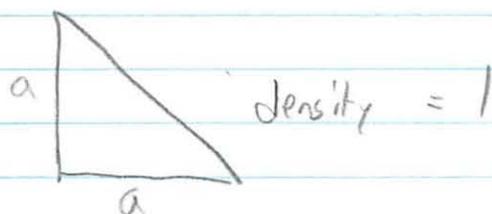
$$\rightarrow x_v y_u \cdot u_y v_x$$

so adds to 1



Lecture 19 Physical applications of double integrations

3C-1a Let R be a right triangle



Find Moment of inertia about a leg

$$\int_0^a \int_0^{a-x} x^2 dy dx$$

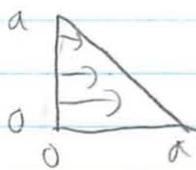
P: where is this from
Should prob go to recitation 1st

$$I_x = \iint_R y^2 \delta(x, y) dA$$

well they do I_y

$$I_y = \iint_R x^2 \delta(x, y) dA$$

then its just figure out region



don't forget normal
how to find region rules

Now solve

$$\int_0^{a-x} x^2 dy$$

$$x^2 y \Big|_0^{a-x}$$

$$x^2(a-x) - 0$$
$$ax^2 - x^3$$

$$\int_0^a ax^2 - x^3 dx$$

$$\frac{ax^3}{3} - \frac{x^4}{4} \Big|_0^a$$

$$\frac{a \cdot a^3}{3} - \frac{a^4}{4}$$

$$\frac{a^4}{3} - \frac{a^4}{4}$$

$$I_y = \frac{a^4}{12} \quad \checkmark$$

b Polar moment of inertia about right-angle vertex
(should be able to deduce from a)

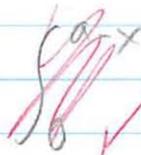
$$I_z = \iint r^2 \delta(x, y) dA$$
$$r^2 = x^2 + y^2$$

? Is that just the same thing?

$$\iint_Q (x^2 + y^2) dA$$

↑ No - plug it in!

$$\int_0^a \int_0^{a-x} (x^2 + y^2) dx dy$$



split x^2
and y^2

shortcut

$$\frac{a^4}{12}$$

+

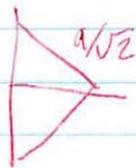
$$\frac{a^4}{12}$$

$$\left(\frac{a^4}{6} \right)$$



c) Moment of inertia around hypotenuse

Divide triangle into smaller triangles



$$2 \cdot \frac{1}{12} \cdot \left(\frac{a}{\sqrt{2}} \right)^4$$

$$\frac{a^4}{24}$$



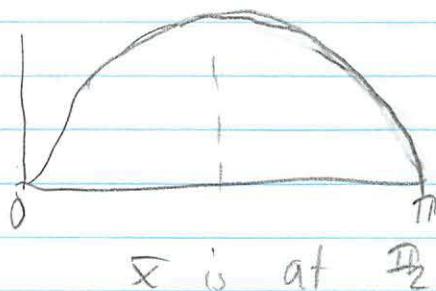
??
don't
get what
they did
resp

2a. Find the center of mass inside 1 arch of $\sin x$
if $\delta = 1$

$$\bar{x} = \frac{M_y}{M} = \frac{\iint_R x \delta(x, y) dA}{\iint_R \delta(x, y) dA}$$

So what does that mean?
do I actually need to solve for each?

Well \bar{x} is clear by symmetry



Find mass (st denominator what we need)

$$M = \iint_R \delta(x, y) dA$$

well just sum over the area

$$\int_0^{\pi} \int_0^{\sin x} 1 dy dx$$

they just have

$$\int_0^{\pi} \sin x dx = 2$$

I guess that is the simpler version of it

Then calculate the moment

$$\iint_R y \delta(x, y) dA$$

$$\int_0^{\pi} \int_0^{\sin x} y dy dx$$

here they use both

$$\int_0^{\sin x} y dy$$

$$\frac{y^2}{2} \Big|_0^{\sin x}$$

$$\frac{1}{2} \int_0^{\pi} \sin^2 x dx$$

$$\frac{\pi}{4}$$

$$\text{so } \bar{y} = \frac{\frac{\pi}{4}}{2} = \left(\frac{\pi}{8} \right) \checkmark$$

b Now $\delta = y$ (so density changes over shape)

Mass

$$\iint_R y dA = \frac{\pi}{4}$$

so they are hiding the

$$\int_0^{\pi} \sin x y dx \text{ in there}$$

Moment

$$\int_0^{\pi} \int_0^{\sin x} y \cdot y \, dy \, dx$$

$$\int_0^{\pi} \int_0^{\sin x} y^2 \, dy \, dx \quad \checkmark$$

$$\frac{y^3}{3} \Big|_0^{\sin x}$$

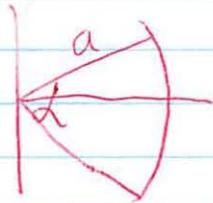
$$2 \cdot \int_0^{\pi} \frac{\sin^3 x}{3} \, dx$$

$$2 \cdot \frac{1}{3} \cdot \frac{2}{3} = \left(\frac{4}{9} \right)$$

$$\text{So } \frac{\frac{\pi}{4}}{\frac{4}{9}} = \left(\frac{16}{9\pi} \right) \quad \checkmark$$

? still don't clearly get why we are doing this

4. Find the center of gravity of a circular dish
of radius a whose vertex angle is 2α
Take $\sigma = 1$



so the trick on this one is to know
the shape

By symmetry know \bar{x}
Need to find \bar{y} ✓

Since constant density \Rightarrow area + mass are the same

~~3C-4~~

3C-5? (-1)

18.02 Exam 2 Thurs. Apr.1, 2010 11:05-11:55

Directions:

1. There are 3 sheets, printed on both sides: nine problems in all.
2. Do all the work on these sheets; use the blank part below if truly necessary. Write down enough to show you are not guessing.
3. No books, notes, calculators, use of cell-phones, etc.
4. Please don't start until the signal is given; stop at the end when asked to; don't talk until your paper is handed in.
5. When the exam starts, read through the exam and start with what you are surest of.
6. Fill out the information below now.

Name Michael Plauder e-mail@mit.edu theplaz

Recitation teacher Oliver Rec. hour 12

Recitation
Mean 69
Median 74

pg.1 19
pg.2 12
pg.3 8
pg.4 14
pg.5 19
Total 72

Problem 1. (10) For the function $w = x^2y - xy^3$, find its directional derivative $\left. \frac{dw}{ds} \right|_{P, \hat{u}}$ at the point $P: (1,1)$ in the direction \hat{u} of the vector $\mathbf{i} + \mathbf{j}$.

$$= \nabla W \cdot \hat{u}$$

$$W_x = 2xy - y^3$$

$$W_y = x^2 - 3xy^2$$

plug pts in

$$W_x = 2(1)(1) - (1)^3 = 1$$

$$W_y = 1^2 - (1) \cdot 3(1)^2 = -2$$

$$\left. \frac{dw}{ds} \right|_{P, \hat{u}} = \langle 1, -2 \rangle \cdot \frac{\langle 1, 1 \rangle}{\sqrt{2}}$$

$$\begin{aligned} & \left(1 \cdot \frac{1}{\sqrt{2}} \right) + \left(-2 \cdot \frac{1}{\sqrt{2}} \right) \\ & \frac{1}{\sqrt{2}} - \frac{2}{\sqrt{2}} \\ & \frac{-1}{\sqrt{2}} \cdot \frac{\sqrt{2}}{\sqrt{2}} = \left(\frac{-\sqrt{2}}{2} \right) \end{aligned}$$

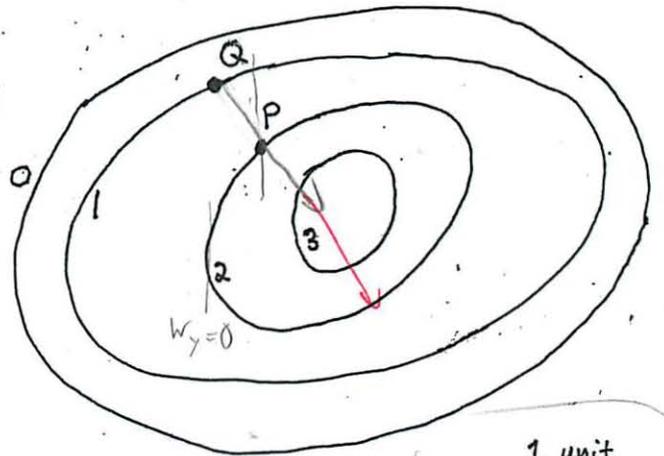
$$\nabla = \langle 1, -2 \rangle$$

$$\sqrt{1^2 + 1^2} = \sqrt{2}$$

Problem 2 (10: 4,6) Some level curves for $w = f(x, y)$ are shown; \mathbf{u} is a unit distance.

- a) At P , estimate the value of w_y .
- b) At Q , draw the vector $(\nabla f)_Q$.

$$w_y|_P = \frac{\partial w}{\partial y} = \frac{1 \text{ change of curve}}{\frac{1}{2} \text{ distance in } y \text{ dir}} = -2$$



$Q = (\nabla f)_Q$ draw gradient towards increasing ground

$$= \left\langle \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y} \right\rangle$$

$$= \left\langle -\frac{1}{2}, -\frac{1}{2} \right\rangle$$

$$\langle 2, -2 \rangle$$

5/6

Problem 3. (20: 3, 12, 5) Find the point P on the surface $x^2 + yz + 3z - 8 = 0$ which is closest to the origin, by following the steps below.

(a) It suffices to find the point P which minimizes the square of the distance to the origin. Show this leads to finding the point which minimizes $w(y, z) = y^2 + z^2 - yz - 3z + 8$.

optimization

rewrite constraint

$$d = \sqrt{x^2 + y^2 + 2z}$$

(b) Find the point (y_0, z_0) which minimizes $w(y, z)$, and use it to find P . (You don't have to prove it is a minimum point.)

$$w_y = 2y + 0 - z - 0 + 0$$

$$w_z = 0 + 2z - y - 3 + 0$$

Set = to 0

$$2y - z = 0$$

$$0 = 2z - y - 3$$

find pts

$$3 = 2z - y$$

$F = z$

$$(y, z) \quad (1, 2)$$

$$(1, 2)$$

$$(-1, -2)$$

$$(-1, -2)$$

(0)

Try each

$$1^2 + (2)^2 - 1 \cdot 2 - 3 \cdot 2 + 8 = 5 \quad \leftarrow \text{minimum point } (1, 2)$$

$$(-1)^2 + (-2)^2 - (-1)(-2) - 3(-2) + 8 = 15$$

what is difference (y_0, z_0) and P

(c) If this problem is solved by Lagrange multipliers instead, give one of the equations involving the multiplier λ , and use it to determine the value of λ corresponding to the point P .

$$2x + 0 + 0 - 0 = \lambda$$

$$0 + z + 0 - 0 = \lambda$$

$$0 + y + 3 - 0 = \lambda$$

$$\begin{aligned} 2x &= \lambda \\ z &= \lambda \\ y + 3 &= \lambda \end{aligned}$$

λ

$$2x - z = y + 3$$

5) Problem 4 (10) Let $w = f(x, y)$, where in turn $x = 2u - v^2$ and $y = uv$.

If in xy -coordinates $\nabla f = \langle 2, 3 \rangle$ at the point $P : (4, 0)$, find the value of $\frac{\partial w}{\partial v}$ at the point in uv -coordinates corresponding to P .

$$\frac{\partial w}{\partial v} = \frac{\partial w}{\partial x} \cdot \frac{\partial x}{\partial v} + \frac{\partial w}{\partial y} \cdot \frac{\partial y}{\partial v}$$

$$= 2 \cdot 0 - 2v$$

$$= 2 \cdot -2v$$

$$= 2 \cdot -2(0)$$

$$= 0$$

point

$$4 = 2u - v^2$$

$$0 = uv$$

$v = \frac{y}{u}$

$$4 = 2(2) - (0)^2$$

$$u = 2$$

$$v = 0$$

3) Problem 5 (10: 5,5)

can't picture graphically at all

they are not independent - have some relation

a) Suppose $f(x, y, z) = 0$. Derive a formula for $\left(\frac{\partial z}{\partial x}\right)_y$ in terms of the formal partial derivatives f_x, f_y, f_z , i.e., the derivatives taken as if x, y, z were independent; use the chain rule or differentials.

$$\left(\frac{\partial f}{\partial x}\right)_y = f_x \left(\frac{\partial x}{\partial x}\right)_y + f_y \left(\frac{\partial y}{\partial x}\right)_y + f_z \left(\frac{\partial z}{\partial x}\right)_y$$

f_x by definition

$\frac{\partial x}{\partial x} = 1$

$\frac{\partial y}{\partial x} = 0$

$\frac{\partial z}{\partial x} = ?$ (we want)

$0 = f_x + f_z \left(\frac{\partial z}{\partial x}\right)_y$

$$\left(\frac{\partial z}{\partial x}\right)_y = \frac{-f_x}{f_z}$$

almost

b) Letting x, y, r, θ be the usual rectangular and polar coordinates, calculate $\left(\frac{\partial r}{\partial \theta}\right)_x$ in terms of r and θ .

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$r = \sqrt{x^2 + y^2}$$

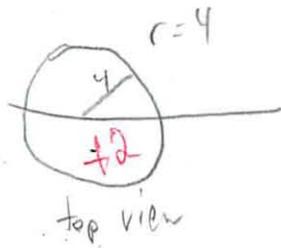
$$\theta = \tan^{-1} \left(\frac{y}{x}\right)$$

so $f(x, r, \theta) = 0$ for $f(x, r, \theta) = x - r \cos \theta$

$$\left(\frac{\partial r}{\partial \theta}\right)_x = \frac{-f_\theta}{f_r} = \frac{-r \sin \theta}{-\cos \theta} = r \tan \theta$$

Problem 6 (10: 3,7) Set up a double iterated integral in polar coordinates which gives the volume of the solid lying under the graph of $z = 16 - x^2 - y^2$ and above the xy -plane, as follows.

- Show the region of integration is the interior of the circle $x^2 + y^2 = 16$.
- Then set up the integral. Do not evaluate the integral.



$$\int_0^{2\pi} \int_0^4 (16 - \underbrace{x^2 - y^2}_{r^2}) r \, dr \, d\theta$$

+6



Problem 7 (10) By changing the order of integration, evaluate $\int_0^1 \int_{\sqrt{x}}^1 \cos(y^3) \, dy \, dx$.



$$\int_0^1 \int_0^{y^2} \cos(y^3) \, dx \, dy$$

+3

don't change inside.

$$y = \sqrt{x}$$

$$y^2 = x$$

$$\int_0^1 \cos(y^3) \, dx$$

$$\cos(y^3) \times \left. \frac{1}{y^2} \right|_0^{y^2}$$

$$\int_0^1 y^2 \cos(y^3) \, dy$$

$$u = \cos y^3$$

$$du = -\sin y^3 \cdot 3y^2 \, dy$$

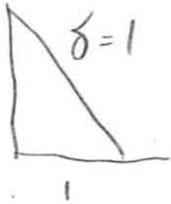
$$\frac{y^3 \cos(y^3)}{3} \Big|_0^1$$

$$\frac{1^3 \cos(1^3)}{3} - \frac{0^3 \cos(0^3)}{3} = \frac{\cos(1)}{3}$$

+3

Integration wrong

Problem 8 (10) A uniform metal plate has the form of an isosceles right triangle having its two legs both of length 1; find its moment of inertia about one of its legs L , taking the density $\delta = 1$.
 (Place the triangle in the first quadrant so the right angle is at the origin, and L lies along the y -axis.)



Moment of inertia $= \iint_{\text{Area}} x^2 \delta \text{Area } dA$

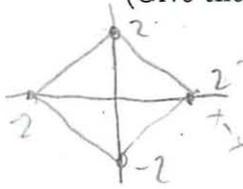
Mass = area \cdot density
 $\frac{1}{2} \cdot 1 \cdot 1 \cdot 1$
 $= \frac{1}{2}$

$\int_0^1 \int_0^{1-x} x^2 \cdot \frac{1}{2} dy dx$
 $\frac{1}{2} \int_0^1 x^2 dy$
 $\frac{1}{2} \cdot x^2 y \Big|_0^{1-x}$
 $\frac{1}{2} \int_0^1 x^2 (1-x) dx$

$\frac{1}{2} \int_0^1 x^2 - x^3 dx$
 $\frac{1}{2} \left(\frac{x^3}{3} - \frac{x^4}{4} \right) \Big|_0^1$
 $\frac{1}{2} \left(\frac{1^3}{3} - \frac{1^4}{4} \right)$
 $\frac{1}{2} \left(\frac{4}{12} - \frac{3}{12} \right)$
 $\frac{1}{2} \left(\frac{1}{12} \right)$

Problem 9. (10) Consider the double integral $\iint_R \sin(x-y) \cos(x+y) dy dx$, where R is the square xy -region having its vertices at the four points ± 2 on the x - and y - axes.

Change it to a double iterated integral in uv -coordinates, where $u = x - y$ and $v = x + y$. (Give the new limits, integrand, and area element dA , but do not evaluate.)



$u = x - y$
 $v = x + y$

$x = \frac{u+v}{2}$
 $y = \frac{v-u}{2}$

Want x in terms of u and v

~~$x = u + y = v - y$
 $x = x - y + y$
 $x = x$
 $x = u + x - u$~~

look graphically

$\int_{-2}^2 \int_{-2}^2$
 $v \quad u$

$\sin(u) \cos(v) \left| \begin{array}{cc} x_u & x_v \\ y_u & y_v \end{array} \right| du dv$

$\left| \begin{array}{cc} u_x & u_y \\ v_x & v_y \end{array} \right| = \left| \begin{array}{cc} 1 & -1 \\ 1 & 1 \end{array} \right| = \frac{1}{2} \sqrt{+4}$

18.02 Exam 2 Solns - Spring 2010

1) $w = x^2y - xy^3$
 $\nabla w = \langle 2xy - y^3, x^2 - 3xy^2 \rangle$
 $(\nabla w)_{(1,1)} = \langle 1, -2 \rangle$
 $\frac{dw}{ds} \Big|_{p, \hat{u}} = \langle 1, -2 \rangle \cdot \frac{\langle 1, 1 \rangle}{\sqrt{2}} = \frac{-1}{\sqrt{2}}$

4) $\frac{\partial w}{\partial v} = \frac{\partial w}{\partial x} \cdot \frac{\partial x}{\partial v} + \frac{\partial w}{\partial y} \cdot \frac{\partial y}{\partial v}$
 $\begin{matrix} \parallel & \parallel \\ 2 & 3 \end{matrix}$ $\begin{cases} x=4 \\ y=0 \end{cases}$
 $x = 2u - v^2$ $\frac{\partial x}{\partial v} = -2v$ corresponds to
 $y = uv$ $\frac{\partial y}{\partial v} = u$ $\begin{cases} v=0 \\ u=2 \end{cases}$
 At $u=2, v=0,$ ($u=0$ says $y=-v^2$)
 $\frac{\partial w}{\partial v} = 2 \cdot 0 + 3 \cdot 2 = 6$ - no soln

2) $(w_y)_p \approx \frac{\Delta w}{\Delta y} = \frac{-1}{1/2} = -2$
 $(\nabla f)_0$: direction $\sqrt{\hat{u}}$
 $|\nabla f|_0 \approx \frac{\Delta w}{\Delta s} \Big|_{\hat{u}} = \frac{1}{1/2} = 2$
 so it should have length 2

5) a) $f(x, y, z) = 0$
 $f_x \left(\frac{\partial x}{\partial x} \right)_y + f_y \left(\frac{\partial y}{\partial x} \right)_y + f_z \left(\frac{\partial z}{\partial x} \right)_y = 0$
 $\therefore \left(\frac{\partial z}{\partial x} \right)_y = -\frac{f_x}{f_z}$

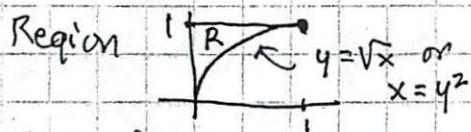
3) $w = x^2 + y^2 + z^2$ (**)
 a) $x^2 = -yz - 3z + 8$ (*)
 $\therefore w = y^2 + z^2 - yz - 3z + 8$
 b) $\frac{\partial w}{\partial y} = 2y - z = 0 : z = 2y$
 $\frac{\partial w}{\partial z} = -y + 2z - 3 = 0 : 3y = 3$
 solving: $y = 1, z = 2$
 using (*) $x^2 = -2 - 6 + 8 = 0$
 $\therefore P: (0, 1, 2)$

b) $x = r \cos \theta = 0$
 By formula: $\left(\frac{\partial r}{\partial \theta} \right)_x = \frac{-f_\theta}{f_r} = \frac{-r \sin \theta}{-\cos \theta} = r \tan \theta$
 Directly:
 $r = \frac{x}{\cos \theta} = x \sec \theta$ $\left(\frac{\partial r}{\partial \theta} \right)_x = x \sec \theta \tan \theta = r \tan \theta$
 [can give ans. in sin + cos also]

c) $\nabla w = \langle 2x, 2y, 2z \rangle = \lambda \nabla g$
 (from **) $= \lambda \langle 2x, z, y+3 \rangle$
 $g(x, y, z) = x^2 + yz + 3z - 8$
 $2x = \lambda \cdot 2x$ useless (since $x \neq 0$)
 $\begin{cases} 2y = \lambda z & -OK: \lambda = 1 \\ 2z = \lambda(y+3) & -OK: \lambda = 1 \end{cases}$

6) a) Graph intersects xy -plane
 where $z=0$: $16 - x^2 - y^2 = 0$
 $x^2 + y^2 = 16$ (R)
 inside R , $16 - (x^2 + y^2) > 0$ radius 4
 (outside: < 0)
 b) $\int_0^{2\pi} \int_0^4 (16 - r^2) \cdot r \, dr \, d\theta$

$$7 \int_0^1 \int_{\sqrt{x}}^1 \cos(y^3) dy dx$$

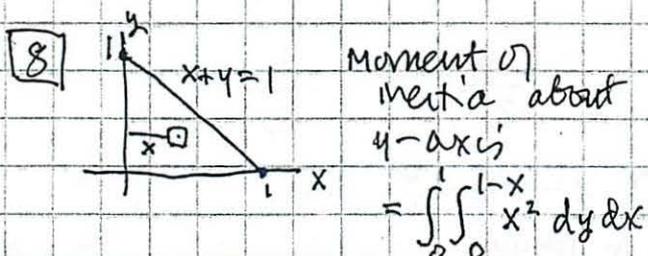


Changed order:

$$\int_0^1 \int_0^{y^2} \cos(y^3) dx dy$$

Inner: $\cos(y^3) x \Big|_0^{y^2} = y^2 \cos(y^3)$

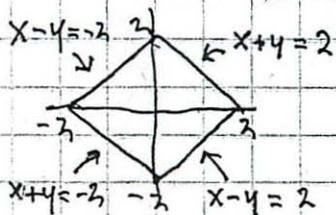
Outer: $\frac{1}{3} \sin(y^3) \Big|_0^1 = \frac{1}{3} \sin(1)$



Inner = $x^2 y \Big|_0^{1-x} = x^2(1-x)$

Outer = $\frac{1}{3} x^3 - \frac{x^4}{4} \Big|_0^1 = \frac{1}{3} - \frac{1}{4} = \frac{1}{12}$

$$9 \iint_R \sin(x-y) \cos(x+y) dy dx$$



$$u = x - y$$

$$v = x + y$$

$$\frac{\partial(u,v)}{\partial(x,y)} = \begin{vmatrix} 1 & -1 \\ 1 & 1 \end{vmatrix} = 2$$

$$\therefore \frac{\partial(x,y)}{\partial(u,v)} = \frac{1}{2}$$

$$\int_{-2}^2 \int_{-2}^2 \sin u \cos v \cdot \frac{1}{2} dv du$$